

Object Oriented Programming and Meta-Programming (C++)

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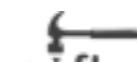


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software carpentry

Agenda

- Programming paradigms
- Classes: derivation and templates
- Design patterns
- Meta-programming

Paradigms (imperative)

- Procedural (C, Fortran etc)
- Object-oriented (C++, Java, Python etc)
- Aspect-oriented (AspectJ)
- Dataflow (Verilog, VHDL, Linda etc)

Paradigms: OOP principles

- Abstraction
- Encapsulation (hiding implementation)
- Inheritance
- Polymorphism

Classes and instances

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <iostream>
4 #include <vector>
5
6 namespace view {
7     class Square {
8     public:
9         Square(int m, int rgb = 0)
10            : points(m*m), dim(m), color(rgb)
11        {}
12    }
13    void draw(){}
14    void erase(){}
15    int get_dim() const {
16        return dim;
17    }
18    void set_dim(int m){
19        this->dim = m;
20        this->erase();
21        this->draw();
22    }
23    ~Square(){
24        this->erase();
25    }
26    private:
27        int dim;
28        int color;
29        std::vector<std::pair<int,int> > points;
30    };
31
32 }
33
34 int main(){
35     view::Square A(10,255);
36     A.draw();
37
38     view::Square* B = new view::Square(10);
39     B->draw();
40
41     delete B;
42     return 0;
43 }
```

Classes and inheritance

```
19  class Circle : public Shape {  
20  public:  
21      Circle(int r, int rgb = 0) : Shape(rgb), radius(r) {  
22          this->reserve(radius);  
23      }  
24      void reserve(int r){  
25          Shape::reserve(M_PI*r*r);  
26      }  
27      void set_radius(int r){  
28          this->erase();  
29          this->radius = r;  
30          this->reserve(r);  
31          this->draw();  
32      }  
33      int get_radius() const {  
34          return radius;  
35      }  
36  private:  
37      int radius;  
38 };  
  
1  class Shape {  
2  public:  
3      Shape(int rgb) : color(rgb) {}  
4      void draw(){  
5      }  
6      void erase(){  
7      }  
8      void reserve(int n){  
9          this->points.reserve(n);  
10     }  
11     ~Shape(){  
12         this->erase();  
13     }  
14  protected:  
15      std::vector<std::pair<int,int> > points;  
16  private:  
17      int color;  
18 };  
  
39  class Square : public Shape {  
40  public:  
41      Square(int m, int rgb = 0) : Shape(rgb), dim(m) {  
42          this->reserve(m);  
43      }  
44      void reserve(int n){  
45          Shape::reserve(n*n);  
46      }  
47      void set_dim(int m){  
48          this->erase();  
49          this->dim = m;  
50          this->reserve(m);  
51          this->draw();  
52      }  
53      int get_dim() const {  
54          return dim;  
55      }  
56  private:  
57      int dim;  
58 };  
  
void resize(Circle* s, int size){  
    s->set_radius(size);  
}  
void resize(Square* s, int size){  
    s->set_dim(size);  
}  
  
int main(){  
    Square A(10,255);  
    Circle B(10,255);  
  
    resize(&A, 100);  
    resize(&B, 100);  
    return 0;  
}
```

Classes and run-time polymorphism

```
20  class Circle : public Shape {  
21  public:  
22      Circle(int r, int rgb = 0) : Shape(rgb), radius(r) {  
23          this->reserve(radius);  
24      }  
25      void reserve(int r){  
26          Shape::reserve(M_PI*r*r);  
27      }  
28      virtual void set_dim(int r){  
29          this->erase();  
30          this->radius = r;  
31          this->reserve(r);  
32          this->draw();  
33      }  
34      int get_radius() const {  
35          return radius;  
36      }  
37  private:  
38      int radius;  
39 };  
  
1  class Shape {  
2  public:  
3      Shape(int rgb) : color(rgb) {}  
4      void draw(){  
5      }  
6      void erase(){  
7      }  
8      void reserve(int n){  
9          this->points.resize(n);  
10     }  
11     virtual void set_dim(int dim) = 0;  
12     ~Shape(){  
13         this->erase();  
14     }  
15  protected:  
16      std::vector<std::pair<int,int> > points;  
17  private:  
18      int color;  
19 };  
  
40  class Square : public Shape {  
41  public:  
42      Square(int m, int rgb = 0) : Shape(rgb), dim(m) {  
43          this->reserve(m);  
44      }  
45      void reserve(int n){  
46          Shape::reserve(n*n);  
47      }  
48      virtual void set_dim(int m){  
49          this->erase();  
50          this->dim = m;  
51          this->reserve(m);  
52          this->draw();  
53      }  
54      int get_dim() const {  
55          return dim;  
56      }  
57  private:  
58      int dim;  
59 };  
  
void resize(Shape* s, int size){  
    s->set_dim(size);  
}  
  
int main(){  
    Shape* A = new Square(10,255);  
    Shape* B = new Circle(10,255);  
  
    resize(A, 100);  
    resize(B, 100);  
    return 0;  
}
```

Classes and run-time polymorphism (alt)

```
32  class Circle : public Shape {  
33  public:  
34      Circle(int r, int rgb = 0) : Shape(r, rgb) {  
35          this->reserve(r);  
36      }  
37      virtual void reserve(int r){  
38          Shape::reserve(M_PI*r*r);  
39      }  
40      int get_radius() const {  
41          return this->dim;  
42      }  
43  };  
  
44  class Square : public Shape {  
45  public:  
46      Square(int m, int rgb = 0) : Shape(m, rgb) {  
47          this->reserve(m);  
48      }  
49      virtual void reserve(int n){  
50          Shape::reserve(n*n);  
51      }  
52      int get_dim() const {  
53          return this->dim;  
54      }  
55  };  
  
7   class Shape {  
8  public:  
9      Shape(int dim, int rgb) : dim(dim), color(rgb) {}  
10     void draw(){  
11    }  
12     void erase(){  
13    }  
14     virtual void reserve(int n){  
15         this->points.resize(n);  
16     }  
17     void set_dim(int dim){  
18         this->erase();  
19         this->dim = dim;  
20         this->reserve(dim);  
21         this->draw();  
22     }  
23     ~Shape(){  
24         this->erase();  
25     }  
26 protected:  
27     std::vector<std::pair<int,int> > points;  
28     int dim;  
29 private:  
30     int color;  
31 };  
  
void resize(Shape* s, int size){  
    s->set_dim(size);  
}  
  
int main(){  
    Shape* A = new Square(10,255);  
    Shape* B = new Circle(10,255);  
  
    resize(A, 100);  
    resize(B, 100);  
    return 0;  
}
```

Classes and compile-time polymorphism

Function templates:

```
1 template <typename T>
2 T max(T a, T b) {
3     return a > b ? a : b;
4 }
5
6 int main(){
7     std::cout << max(13, 14) << "\n"; // same as max<int>(13, 14)
8     std::cout << max(4.5, 4.6) << "\n"; // same as max<float>(4.5, 4.6)
9     std::cout << max<int>(4.5, 4.6) << "\n"; // explicit template / implicit casting
10    return 0;
11 }
```

Function overloading:

```
12 inline double distance(const std::complex<double>& a, const std::complex<double>& b){
13     return fabs(std::norm(a) - std::norm(b));
14 }
15
16 inline double distance(double a, double b){
17     return fabs(fabs(a) - fabs(b));
18 }
```

Classes and compile-time polymorphism

Class template:

```
1  template <typename T>
2  class vector {
3  public:
4      typedef T value_type;
5      explicit vector(size_t n, T init = T()) : length(n){
6          elements = (T*)std::malloc(sizeof(T)*length);
7          for(size_t i = 0; i < n; i++) elements[i] = init;
8      }
9      T operator[](size_t k) const {
10         return elements[k];
11     }
12     T& operator[](size_t k){
13         return elements[k];
14     }
15     template<typename S>
16     vector<T>& operator += (const vector<S>& other){
17         for(size_t i = 0; i < length; i++) (*this)[i] += other[i];
18         return *this;
19     }
20     ~vector(){
21         std::free(elements);
22     }
23     private:
24     value_type* elements;
25     size_t length;
26 }
```

```
int main(){
    vector<int> a(29, 7);
    vector<float> b(29, 4.5);

    a += b;
    return 0;
}
```

Classes and compile-time polymorphism

Template Class Specialisation:

```
28     template <>
29     class vector<bool> {
30     public:
31         typedef bool value_type;
32         explicit vector(size_t n, bool init = false) : length(n){
33             int size = std::ceil((float)length/8);
34             elements = (char*)std::malloc(size);
35             memset(elements, (init ? 255 : 0), size);
36         }
37         bool operator[](size_t k) const {
38             return (elements[k/8] & (1 << (k % 8))) >> k % 8;
39         }
40         void set(size_t k, bool value){
41             if(value) elements[k/8] |= 1 << k % 8;
42             else elements[k/8] &= ~(1 << k % 8);
43         }
44         ~vector(){
45             std::free(elements);
46         }
47     private:
48         char* elements;
49         size_t length;
50     };
```

Design patterns: principles

- Inversion of Control
- S.O.L.I.D.

Design patterns: S.O.L.I.D.

- The Single Responsibility Principle: one reason to change
- The Open Closed Principle: read-only, open for extension
- The Liskov Substitution Principle: substitution-robust behaviour
- The Interface Segregation Principle: dependance - means usage
- The Dependency Inversion Principle: low-level depends on high-level

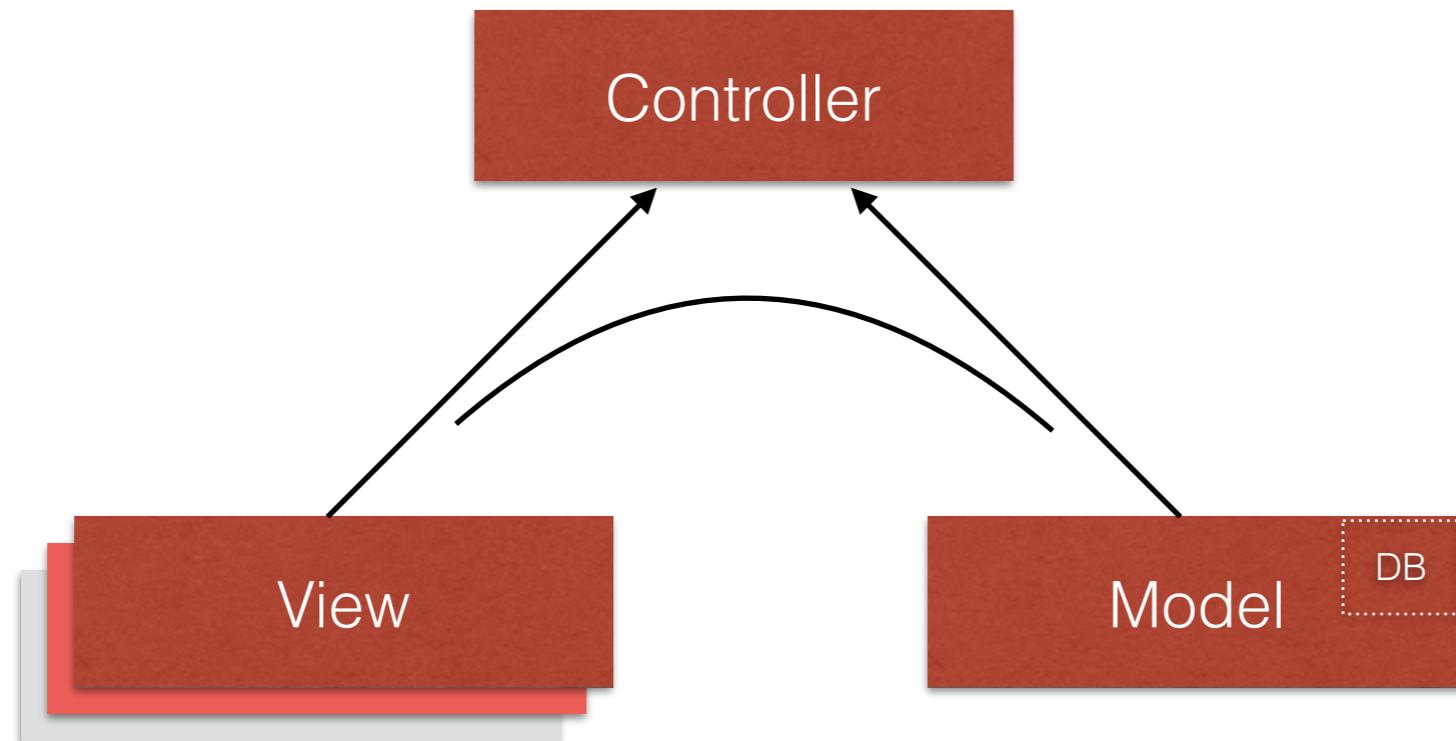
Design patterns: examples

- Dependency Injection
- Template method pattern
- Model View Controller
- Adapter
- Singleton
- Factory

Design patterns: Template method pattern

```
1 class Algorithm {  
2 public:  
3     virtual void initialize() = 0;  
4     virtual void writeAnswer() = 0;  
5     virtual bool converged() = 0;  
6     virtual void iterate() = 0;  
7  
8     void compute() {  
9         initialize();  
10        while(!converged()) iterate();  
11        writeAnswer();  
12    }  
13};  
14  
15 class IterativeAlgorithm : public Algorithm {  
16 public:  
17     virtual void initialize(){  
18     }  
19     virtual void writeAnswer(){  
20     }  
21     virtual bool converged(){  
22     }  
23     virtual void iterate(){  
24     }  
25};
```

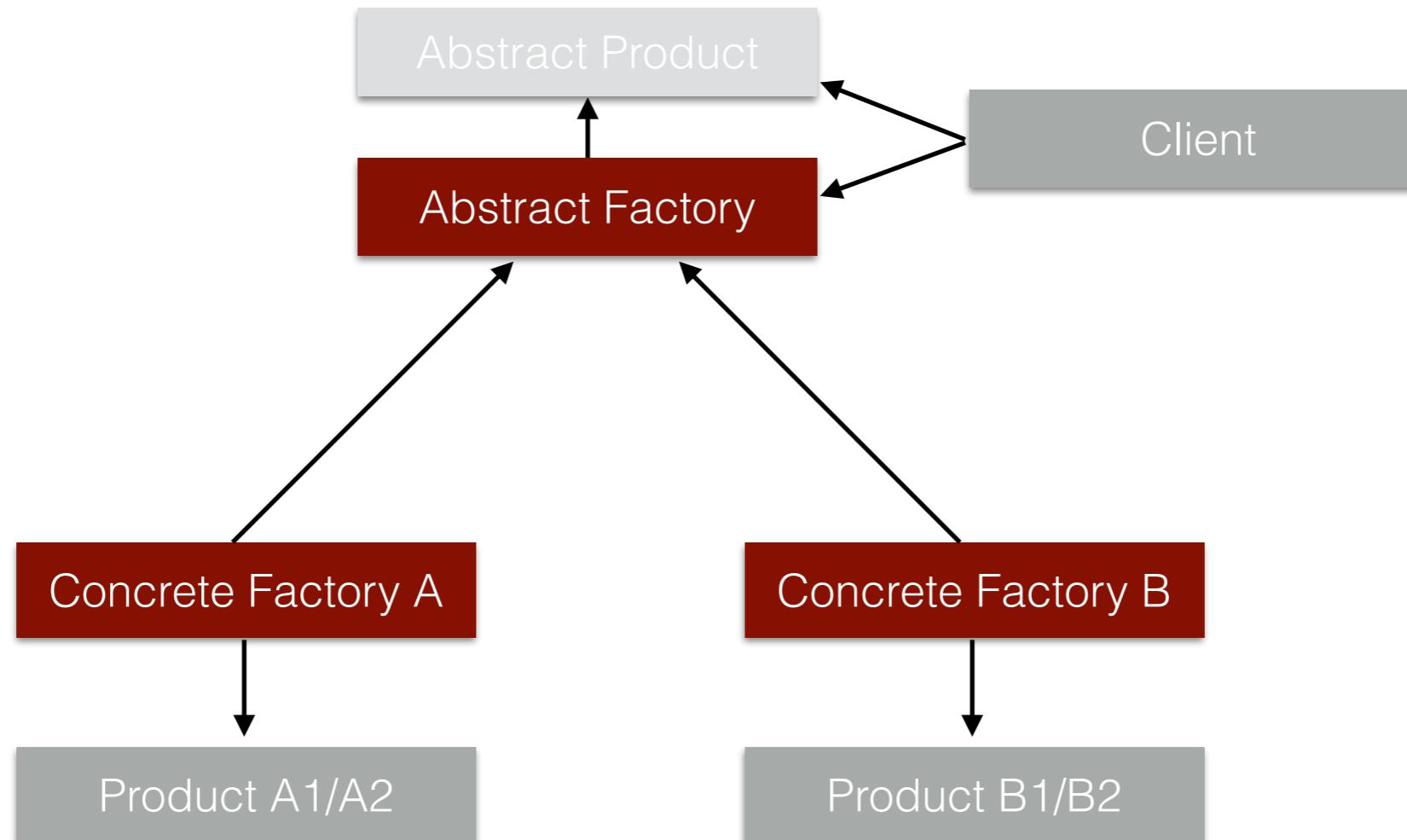
Design patterns: Model View Controller



Design patterns: Singleton

```
1  class A {
2  protected:
3      A(){ }
4      A(A const&){ }
5  };
6
7  template <typename T>
8  class singleton : public T {
9  public:
10     static T& instance(){
11         static singleton s;
12         return s;
13     }
14 private:
15     inline singleton(){}
16     singleton(singleton const&);
17     singleton& operator=(singleton const&);
18 };
19
20 int main(){
21     A& a = singleton<A>::instance();
22     A b(a); // error
23     A c;    // error
24     return 0;
25 }
```

Design patterns: Factory



Meta-programming

Example: prime number

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <iostream>
4
5 constexpr bool is_prime(unsigned long n, unsigned long div){
6     return n % div == 0 ?
7         false : (div * div > n ? true : is_prime(n, div + 2));
8 }
9 constexpr bool is_prime(unsigned long n){
10    return n == 2 || n == 3 || (n % 2 && is_prime(n, 3));
11 }
12
13 template<bool Prime>
14 class Number {
15 public:
16     Number(){ printf("Default number constructor\n"); }
17 };
18
19 template<>
20 class Number<true> {
21 public:
22     Number(){ printf("Prime number constructor\n"); }
23 };
24
25 int main(){
26     Number<is_prime(997)> a;
27     Number<is_prime(169)> b;
28     return 0;
29 }
```

Meta-programming

Example: looping

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <iostream>
4
5 constexpr int max(int a, int b){
6     return a > b ? a : b;
7 }
8
9 template<int N, template<int I> class Iteration>
10 constexpr bool repeat(){
11     return N != 0 ? Iteration<max(1,N)>::iterate() && repeat<max(0,N-1), Iteration>() : false;
12 }
13
14 constexpr int factorial(int N){
15     return N != 1 ? N*factorial(N-1) : 1;
16 }
17
18 template<int N>
19 struct compile_time {
20     static void check(){ std::cout << N << "\n"; }
21 };
22
23 template<int I>
24 class loop_iteration{
25 public:
26     static bool iterate(){
27         std::cout << "Loop iteration: " << I << "; ";
28         std::cout << "Value: ";
29         compile_time<factorial(I)>::check();
30         return true;
31     }
32 };
33
34 int main(){
35     repeat<10, loop_iteration>();
36     return 0;
37 }
```

Meta-programming

Example: lambda deduction

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <iostream>
4 #include <functional>
5
6 template <typename Function>
7 struct function_traits : public function_traits<decltype(&Function::operator())> {};
8
9 template <typename ClassType, typename ReturnType, typename... Args>
10 struct function_traits<ReturnType(ClassType::*)(Args...) const> {
11     typedef ReturnType (*pointer)(Args...);
12     typedef const std::function<ReturnType(Args...)> function;
13 };
14
15 template <typename Function>
16 typename function_traits<Function>::function to_function (Function& lambda) {
17     return static_cast<typename function_traits<Function>::function>(lambda);
18 }
19
20 template <class L>
21 struct overload_lambda : L {
22     overload_lambda(L l) : L(l) {}
23     template <typename... T>
24     void operator()(T& ... values){
25         to_function(*(&L::this))(std::forward<T>(values)...);
26     }
27 };
28
29 template <class L>
30 overload_lambda<L> lambda(L l){
31     return overload_lambda<L>(l);
32 }
33
34 int main(){
35     auto call = lambda([](int a){ std::cout << a << "\n"; });
36     call(10);
37     return 0;
38 }
```

Meta-programming

Example: Substitution failure is not an error (SFINAE) lookup

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <iostream>
4 #include <functional>
5
6 namespace allocators {
7     template<typename T> struct default_allocator {
8         static void info(){ std::cout << "Default allocator!\n"; }
9     };
10    template<typename T> struct my_allocator {
11        static void info(){ std::cout << "My allocator!\n"; }
12    };
13 }
14 template <typename T>
15 struct has_allocator {
16     template <typename T1> static typename T1::allocator_type test(int);
17     template <typename> static void test(...);
18     enum { value = !std::is_void<decltype(test<T>(0))>::value };
19 };
20 template <bool HAS, typename T> struct checked_get_allocator {};
21 template <typename T> struct checked_get_allocator<true, T> { typedef typename T::allocator_type type; };
22 template <typename T> struct checked_get_allocator<false, T> { typedef typename allocators::default_allocator<T> type; };
23 template <typename T> struct get_allocator { typedef typename checked_get_allocator<has_allocator<T>::value, T>::type type; };
24
25 template <class T> struct smart_type : public T {
26     typedef typename get_allocator<T>::type allocator_type;
27 };
28 int main(){
29     struct user_A { };
30     struct user_B { typedef allocators::my_allocator<double> allocator_type; };
31     smart_type<user_A>::allocator_type::info();
32     smart_type<user_B>::allocator_type::info();
33     return 0;
34 }
```

Questions

End of the second part