

The University of Mancheste

ONE LAST THING

I am graduating this year.

Currently on the job market.

Would love to get a postdoc opportunity!

Jodrell Bank Centre for Astrophysics



The University of Manchester

A First Detection of Neutral Hydrogen Intensity Mapping on Mpc Scales

Zhaoting Chen, on behalf of Sourabh Paul, Mario Santos and Laura Wolz

SKA Cosmology SWG Meeting 2023



Outline

- Why is it very difficult
- Analysis of the MeerKAT DEEP2 data
- HI Science from the data

• How to use interferometric radio data to do HI intensity mapping



Outline

• How to use interferometric radio data to do HI intensity mapping



Foreground Avoidance

• We can measure the HI power spectrum outside the "wedge"



Liu, Parsons, and Trott 1404.2596





- Why is it very difficult

Outline

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• Why is it very difficult

• Faint HI signal demands extreme field depth

Integration Time







Paul, Santos et al. 2009.13550

• Why is it very difficult

• Systematic issues such as RFI

Wang et al. 2011.13789

precision K **Comoving distance**

The Uphill Battle

• Why is it very difficult

• EXTREME requirements for instrument stability and calibration precision Comoving distance Comoving distance

Intensity

The Uphill Battle

• Why is it very difficult

Frequency

• EXTREME requirements for instrument stability and calibration

The Uphill Battle

• Why is it very difficult

• EXTREME requirements for instrument stability and calibration precision. $e < 10^{-4}$ is needed for enabling the measurements.

Barry et al. 1603.00607

The Uphill Battle

• Why is it very difficult

• Accurate understanding of the sensitivity of the instrument to remove the noise bias.

3.2.3 Noise statistics and weight estimates

Several noise metrics are computed to analyse the noise statistics in the data. In general, the noise can be estimated with reasonable accuracy from the Stokes V image cube (circularly polarized sky), the sky being only weakly circularly polarized. Ten second time-difference visibilities, $\delta_t V(u, v, \nu)$, are obtained from taking the difference between the odd and even gridded visibilities sets, yielding a good estimate of the thermal noise (at this time resolution, the fore-grounds and ionospheric errors cancel out almost perfectly).

Another noise estimate can be derived from the visibility difference between sub-bands, $\delta_{\nu}V(u, v, \nu)$, which should better reflect the spectrally-uncorrelated noise in the data. Compared to the time difference noise spectrum (in baselinefrequency space), we find that the sub-band difference noise variance is on average higher by a factor ≈ 1.35 for Stokes V and ≈ 2 for Stokes I (sixth and seventh columns of Table 1, respectively) with a small night-to-night variation. We also

Mertens et al. 2002.07196

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The Uphill Battle

- Why is it very difficult

 - Mode-mixing from the primary beam

• Leakage from bright sources in side-lobes shows up in high delay

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Integration Time MeerKAT DEEP2 data Avoid Bright Sources • Pointing at the DEEP2 field. 96 hrs in total, 9 observing sessions.

Right ascension

9e-5 7e-5 Jy/beam 3e-5 e-5 4:00:00 50:00 3:40:00 10:00

Mauch et al. 1912.06212

- Pointing at the DEEP2 field. 96 hrs in total, 9 observing sessions in L-band.
- Well-tested, established calibration pipeline using **processMeerKAT** (Collier et al.).
- Our own data processing pipeline after calibration.

• Two sub-bands, each with a width of 46MHz centred around 986 and 1077.5 MHz.

Wang et al. 2011.13789

• Two sub-bands, each with a width of 46MHz centred around 986 and 1077.5 MHz.

Wang et al. 2011.13789

• Cross-correlating even and odd scans to remove noise bias, avoiding the effects of wrongly estimated noise amplitude.

Residual RFI

• A clear structure of contamination in the cylindrical power spectrum

Thermal Noise

• Use Stokes V data to estimate and simulate thermal noise

sigma cuts.

Masking Residual RFI

• The simulations are then used to mask the excess power with 5-

Masking Residual RFI

• We are able to mitigate the RFI structure from the masking

even x odd

• Cross-correlating visibility data from different sub-bands

No Sizeable Leakage

Null Test

The Measurement

The Measurement

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Modelling the Power Spectrum

• The power spectrum measured at these scales are dominated by the velocity dispersion and the shot noise. $P_{\rm D}(k_{\perp}, k_{\parallel}) = P_{2\rm h}(k_{\perp}, k_{\parallel}) + P_{1\rm h}(k_{\perp}, k_{\parallel}) + \frac{P_{\rm SN}}{1 + (\sigma_p k_{\parallel})^2/2}, \ \sigma_p = \sigma_v (1 + z)/(Hf)$

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$\sigma_v \propto w_{50}$

Sinigaglia et al. 2208.01121

Parameter Fitting

• We put in a basic 3-parameter halo model and perform MCMC fitting.

Z. Chen et al. 2010.07985 Murray, Diemer, **Z. Chen** et al. 2009.14066

- We don't have constraining power of the overall amplitude.
- Degeneracy between velocity and shot,
 noise due to 1-D binning.

- Using HIMF to calculate the shot noise and check with HI density from halo model.
- Need additional input from stacking. Ree et al. 1709.07596
- A proof-of-concept for the z=0.32 bin

$P_{SN}^0 = 0.34_{-0.16}^{+0.33}$ (HIMF) $P_{SN}^{0} = 40.33_{-21.82}^{+19.86} \text{ (NP)}$ $P_{SN}^{0} = 40.21_{-21.57}^{+19.42} \text{ (WP)}$

15 ,00

Constraining the HIMF

Using HIMF to calculate the shot noise and check with HI density from halo model. Consistent with GMRT results as well as MIGHTEE-HI.

Conclusion

- intensity mapping.
- and large signal-to-noise ratio.
- Milestone in 21cm cosmology!
- The inner-halo scales inform us about the density profile, the velocity widths of the HI galaxies, and the HIMF.

• We report the first-ever detection of the HI auto-power spectrum using

• The detection is possible due to sufficient RFI mitigation, precise calibration

