

Real-time Machine Learning for triggering at the LHC making very fast decisions

Thea Klæboe Årrestad (ETH Zürich)
thea.aarrestad@cern.ch

Example of GPT-4 visual input:

User What is funny about this image? Describe it panel by panel.



Source: <https://www.reddit.com/r/hmmm/comments/ubab5v/hmmm/>

GPT-4 The image shows a package for a "Lightning Cable" adapter with three panels.

Panel 1: A smartphone with a VGA connector (a large, blue, 15-pin connector typically used for computer monitors) plugged into its charging port.

Panel 2: The package for the "Lightning Cable" adapter with a picture of a VGA connector on it.

Panel 3: A close-up of the VGA connector with a small Lightning connector (used for charging iPhones and other Apple devices) at the end.

The humor in this image comes from the absurdity of plugging a large, outdated VGA connector into a small, modern smartphone charging port.

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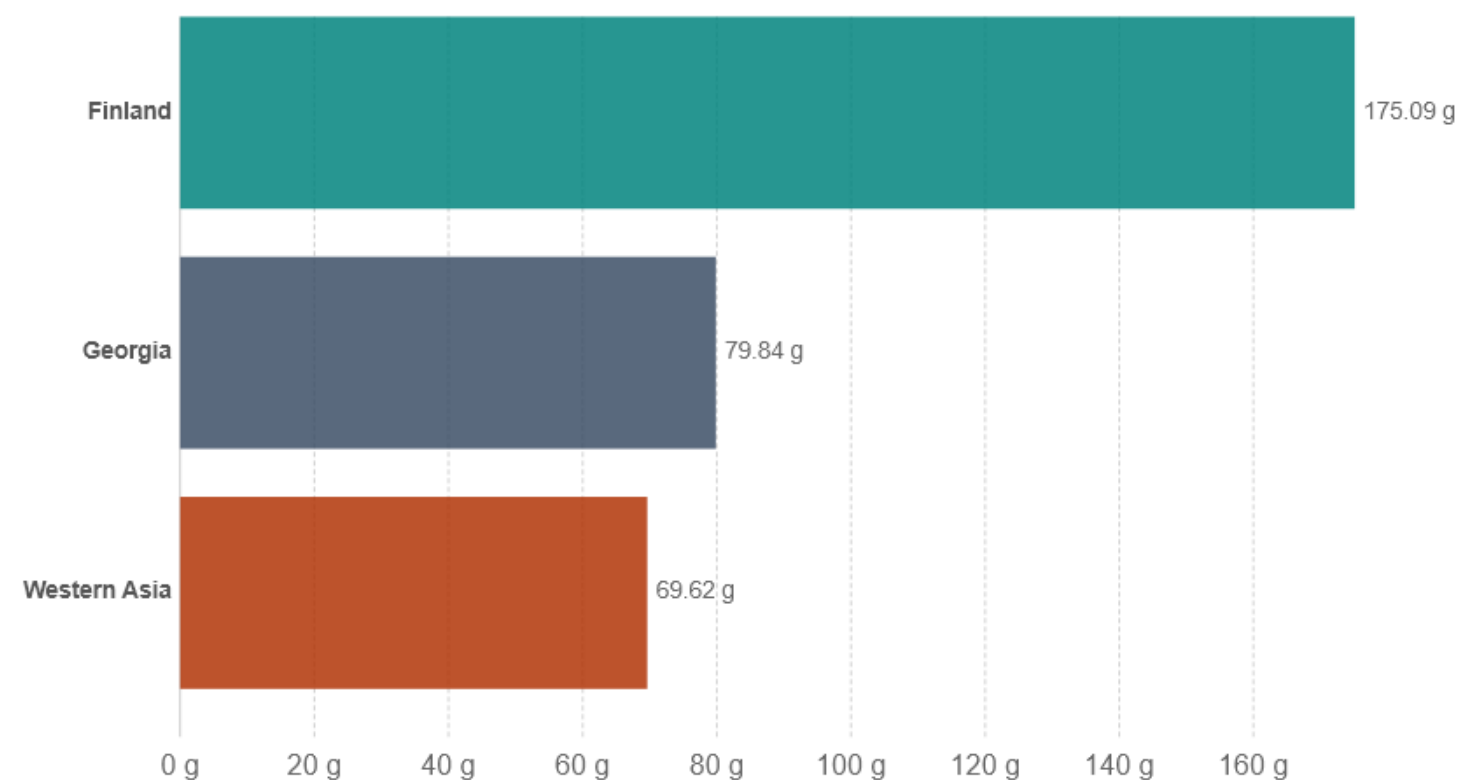
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GPT-4 visual input example, Chart Reasoning:

User What is the sum of average daily meat consumption for Georgia and Western Asia? Provide a step-by-step reasoning before providing your answer.

Daily meat consumption per person, 1997

Average daily meat consumption per person, measured in grams per person per day. Countries with daily meat consumption greater than the expected EU average of 165g per person are shown in red; yellow are those countries below 165g but exceeding the more ambitious limit of 40g per person; and in blue are those below 40g per person.



Source: UN Food and Agricultural Organization (FAO)

CC BY

GPT-4 To find the sum of average daily meat consumption for Georgia and Western Asia, we will follow these steps:

1. Identify the average daily meat consumption for Georgia.
2. Identify the average daily meat consumption for Western Asia.
3. Add the values from steps 1 and 2.

Step 1: From the provided chart, we see that the average daily meat consumption for Georgia is 79.84 grams per person per day.

Step 2: From the chart, we see that the average daily meat consumption for Western Asia is 69.62 grams per person per day.

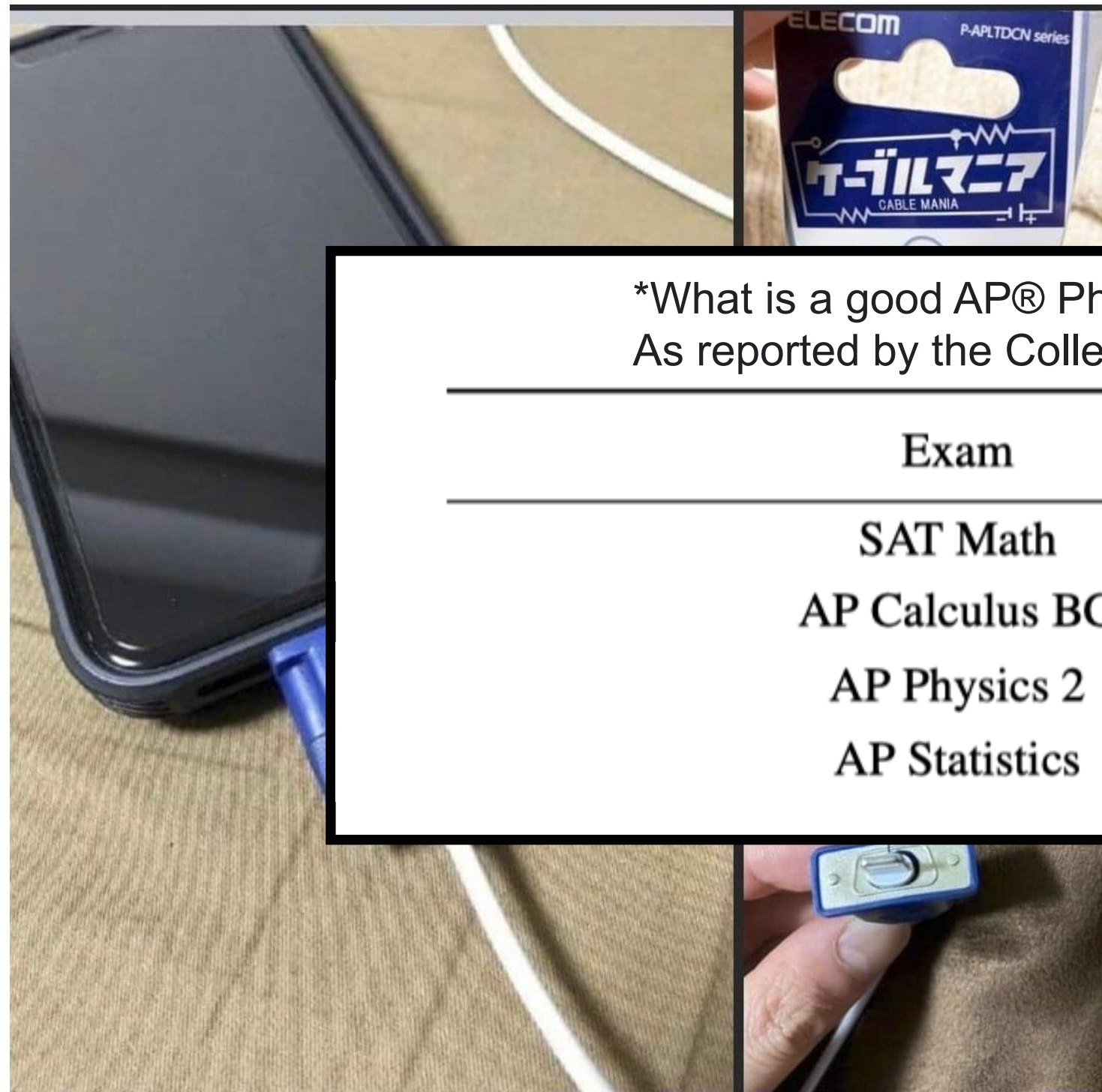
Step 3: Add the values from steps 1 and 2.

$$79.84 \text{ g (Georgia)} + 69.62 \text{ g (Western Asia)} = 149.46 \text{ g}$$

So, the sum of average daily meat consumption for Georgia and Western Asia is 149.46 grams per person per day.

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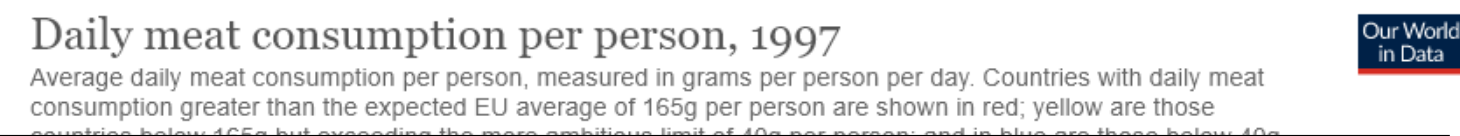
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User What is the sum of average daily meat consumption for Georgia and Western Asia? Provide a step-by-step reasoning before providing your answer.



*What is a good AP® Physics 2 score? Earning a 3, 4, or 5 is generally accepted as scoring well on an AP® exam. As reported by the College Board, a 3 is 'qualified,' a 4 'well qualified,' and a 5 'extremely well qualified.'

Exam	GPT-4	GPT-4 (no vision)	GPT-3.5
SAT Math	700 / 800 (~89th)	690 / 800 (~89th)	590 / 800 (~70th)
AP Calculus BC	4 (43rd - 59th)	4 (43rd - 59th)	1 (0th - 7th)
AP Physics 2	4 (66th - 84th)	4 (66th - 84th)	3 (30th - 66th)
AP Statistics	5 (85th - 100th)	5 (85th - 100th)	3 (40th - 63rd)

Source: UN Food and Agricultural Organization (FAO) CC BY

GPT-4 To find the sum of average daily meat consumption for Georgia and Western Asia, we will follow these steps:

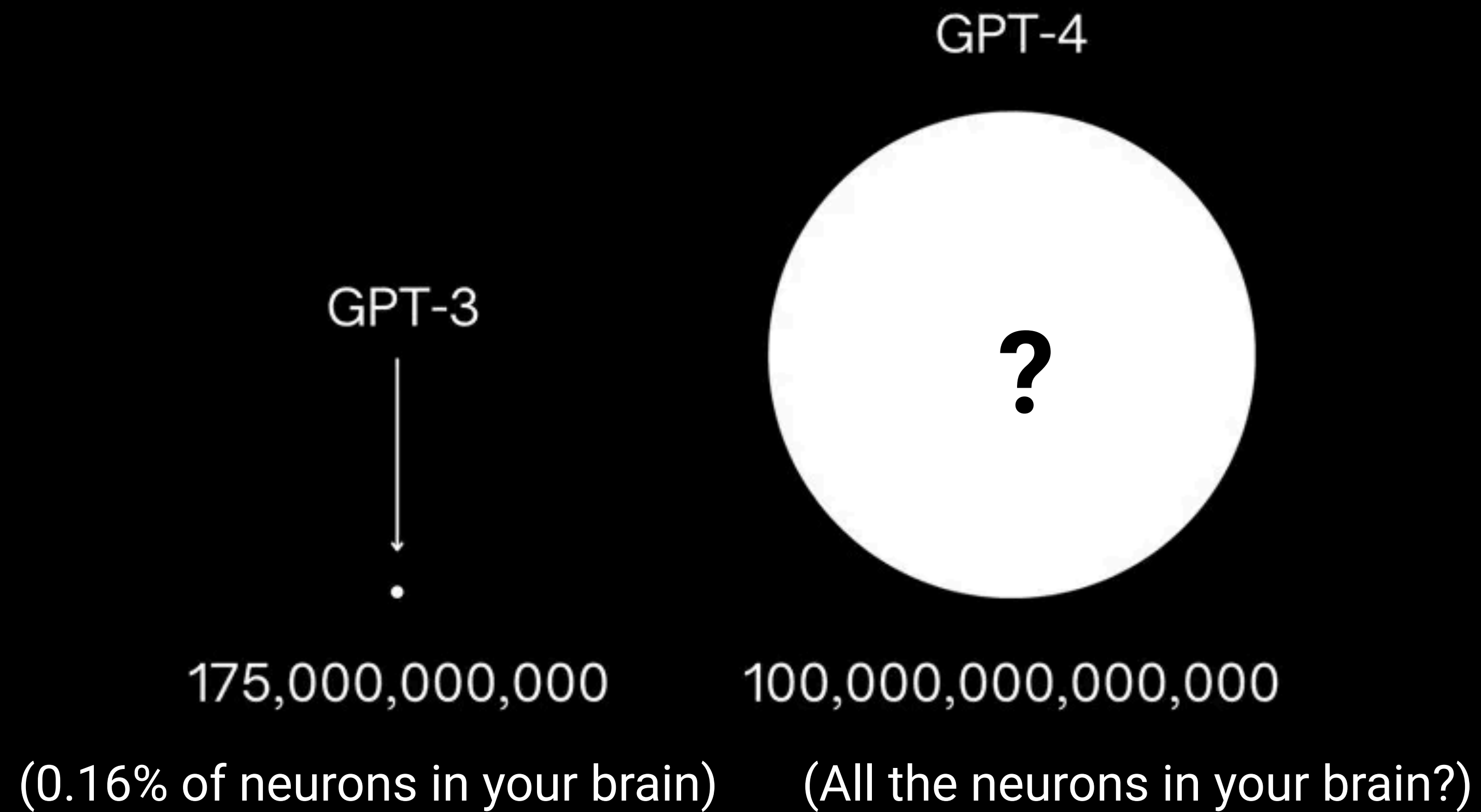
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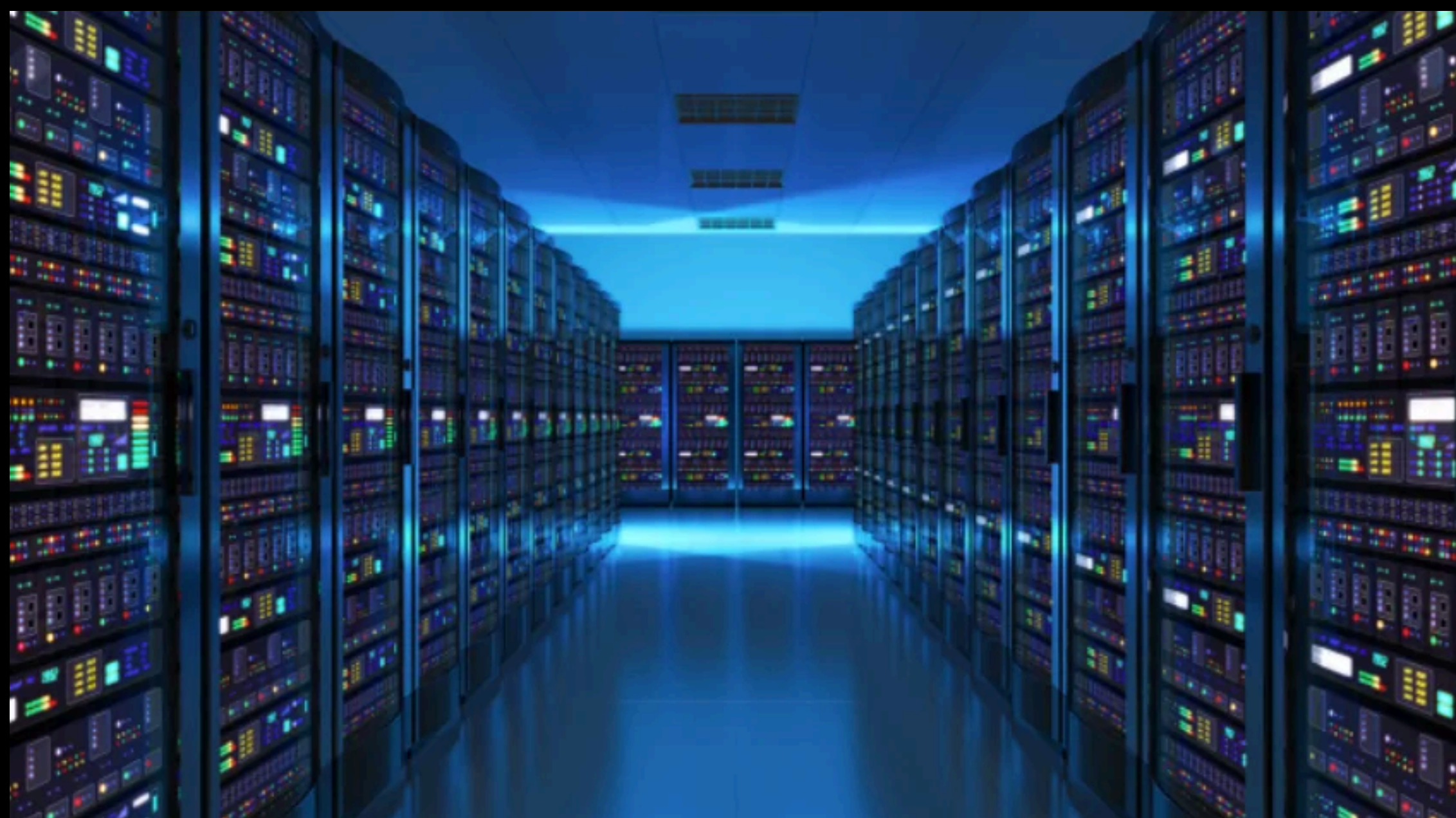
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Train (GPT-3):

- **285,000 CPU cores**
- **10,000 GPUs**
- **400 Gb/s network**
- **Several weeks**
- **Trained on ~25 km high book of text**



Train (GPT-3):

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T I'm a bit late with my presentation, could you summarise the latest progress in Machine Learning for Particle Physics?

Sure! In recent years, there has been significant progress in the application of machine learning techniques to particle physics. Some key areas where machine learning has made significant contributions include: 👍 🗨

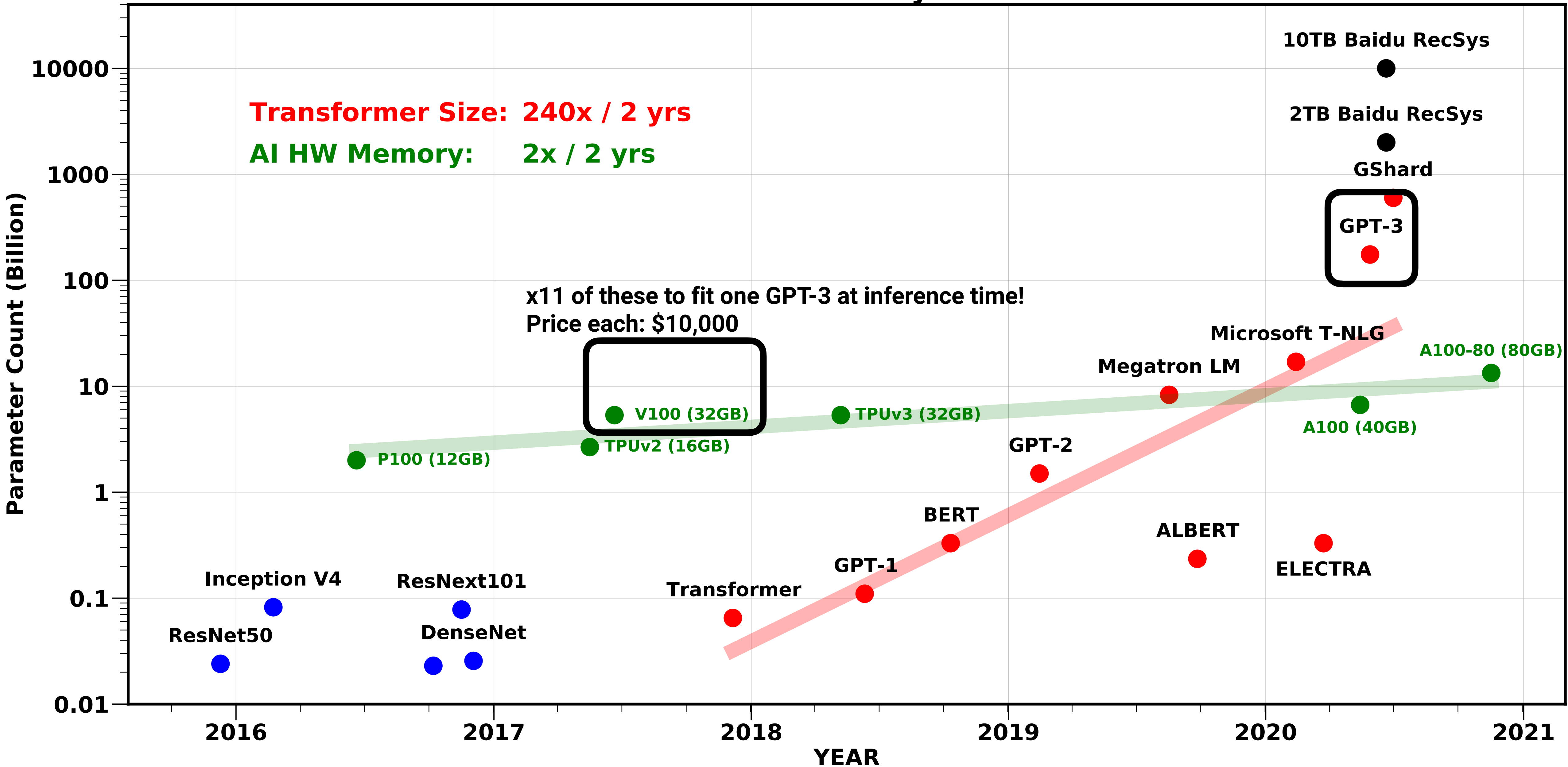
1. Classification of particles: Machine learning algorithms, particularly deep learning algorithms, have been successfully used to classify different types of particles based on their properties and characteristics. For example, they can be used to identify and distinguish between different types of hadrons (such as protons and neutrons) or leptons (such as electrons and muons).
2. Event reconstruction: Machine learning algorithms have also been used to improve the accuracy of event reconstruction in particle physics experiments. Event reconstruction refers to the process of reconstructing the collision events that occurred in a particle accelerator from the raw data collected by detectors. Machine learning algorithms can be used to identify patterns and correlations in the data that can help scientists more accurately reconstruct the events that occurred.
3. Particle identification: Machine learning algorithms have been used to identify and classify particles based on their properties and characteristics. This can be particularly useful in the context of high-energy particle colliders, where large numbers of particles are produced in each collision event.
4. Simulation and modeling: Machine learning algorithms have also been used to improve the accuracy of simulations and models in particle physics. For example, they have been used to model the interactions between particles and the underlying physical processes that take place during collisions.
5. Data analysis and interpretation: Machine learning algorithms have been used to analyze and interpret large datasets generated by particle physics experiments. For example, they have been used to identify patterns and correlations in the data that can help scientists better understand the underlying physical processes at play.

Overall, machine learning has made significant contributions to particle physics and is expected to continue to play a major role in this field in the future.

Inference (GPT-3):

- ?

AI and Memory Wall



Resources: 11 interconnected GPUs

Latency: 10¹ seconds



We're experiencing exceptionally high demand. Please hang tight as we work on scaling our systems. ✕

**ChatGPT is at
capacity right now**

[Get notified when we're back](#)

Write a rap about the status of ChatGPT.

Yeah, yo, what's up ChatGPT fam
A lot of people trying to jam
But don't worry, we got your back
Just check back soon, we'll get on track

ChatGPT's the place to be
For all your AI chat needs
We're working hard to keep up the pace
So hold tight, we'll be back in this space

Resources: 11 interconnected GPUs
Latency: 10^1 seconds

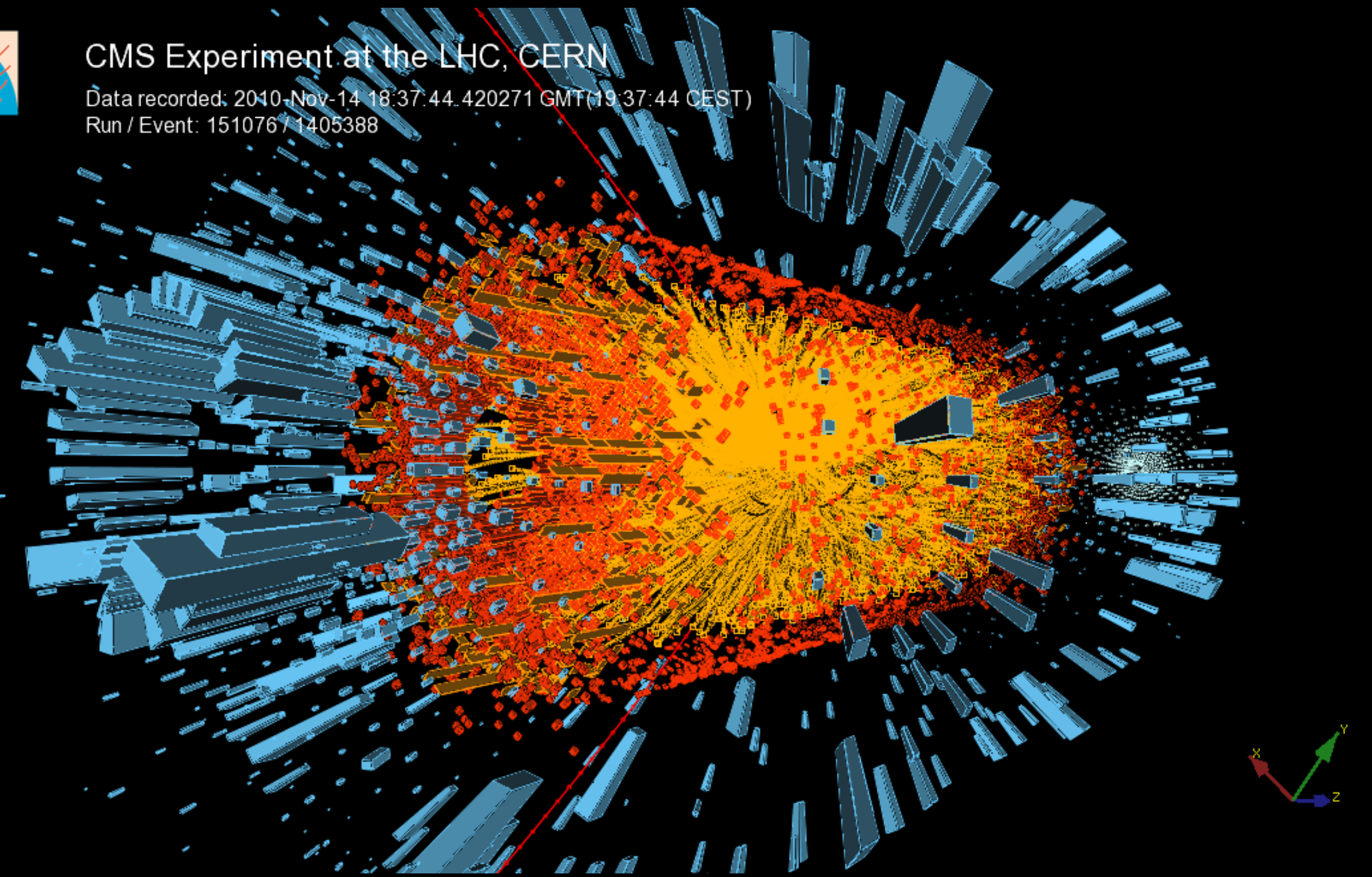


Resources: One single chip
Latency: 10^{-9} seconds



CMS Experiment at the LHC, CERN

Data recorded: 2010-Nov-14 18:37:44.420271 GMT(19:37:44 CEST)
Run / Event: 151076 / 1405388



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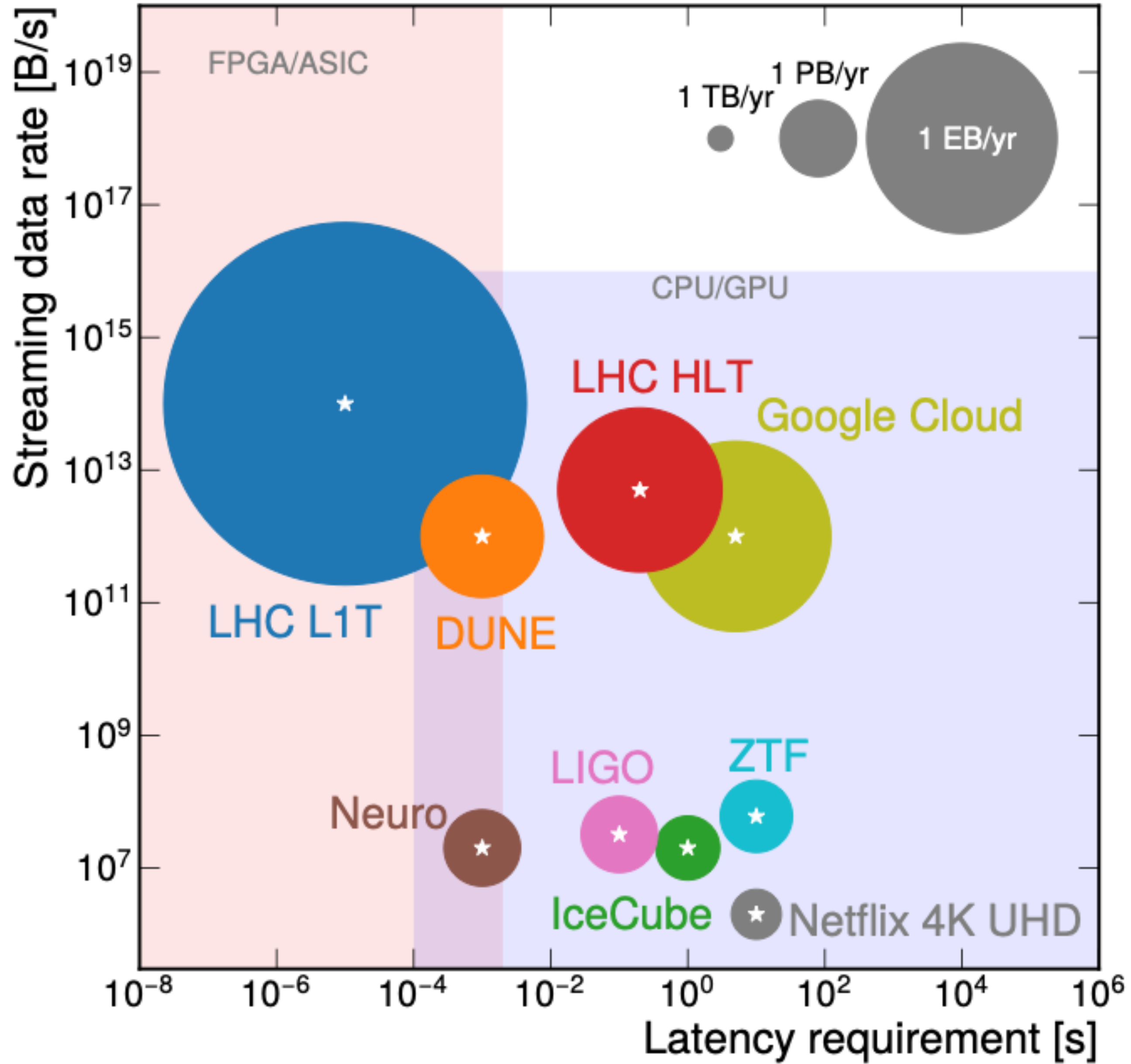
ChatGPT is at
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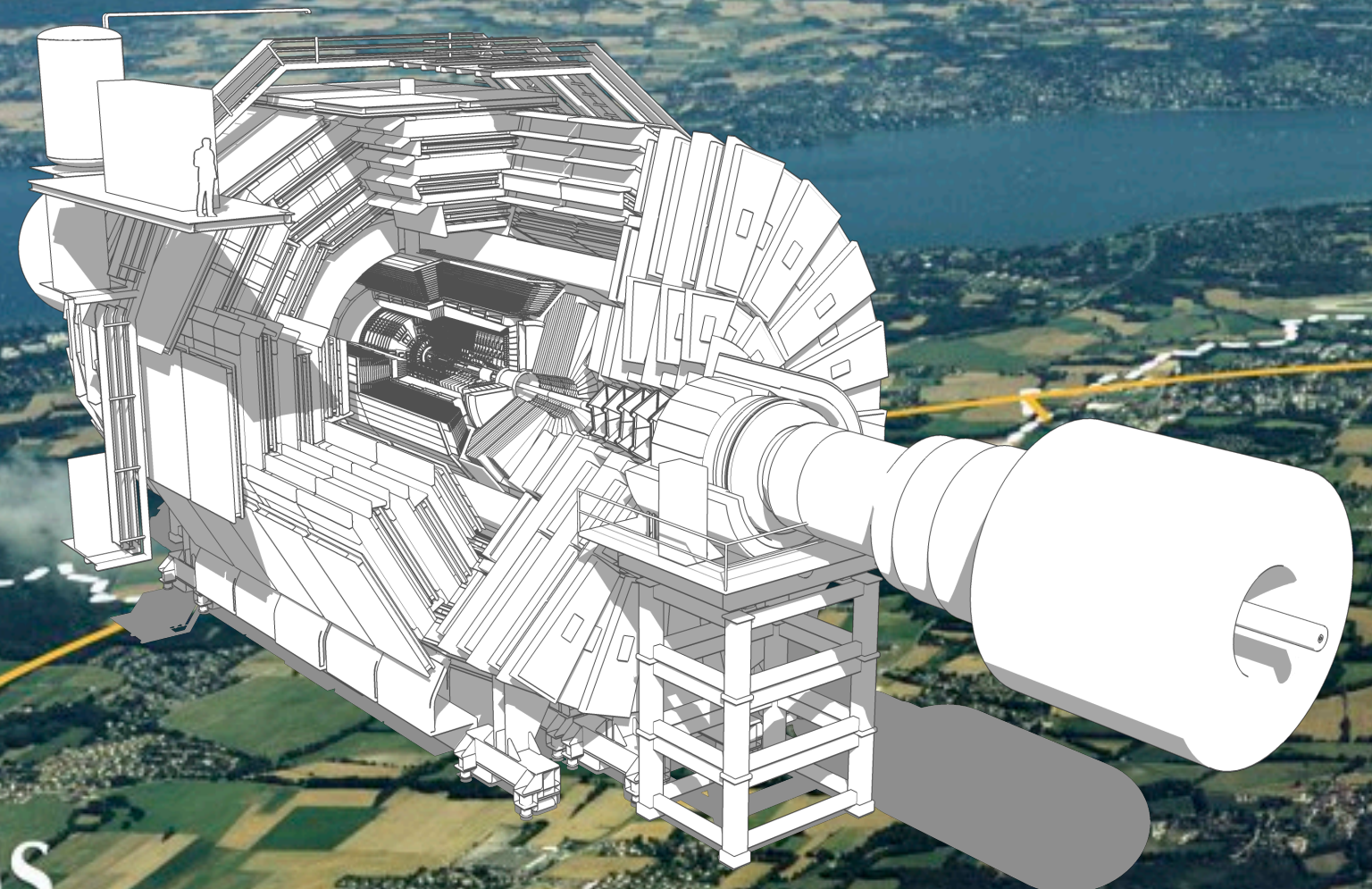
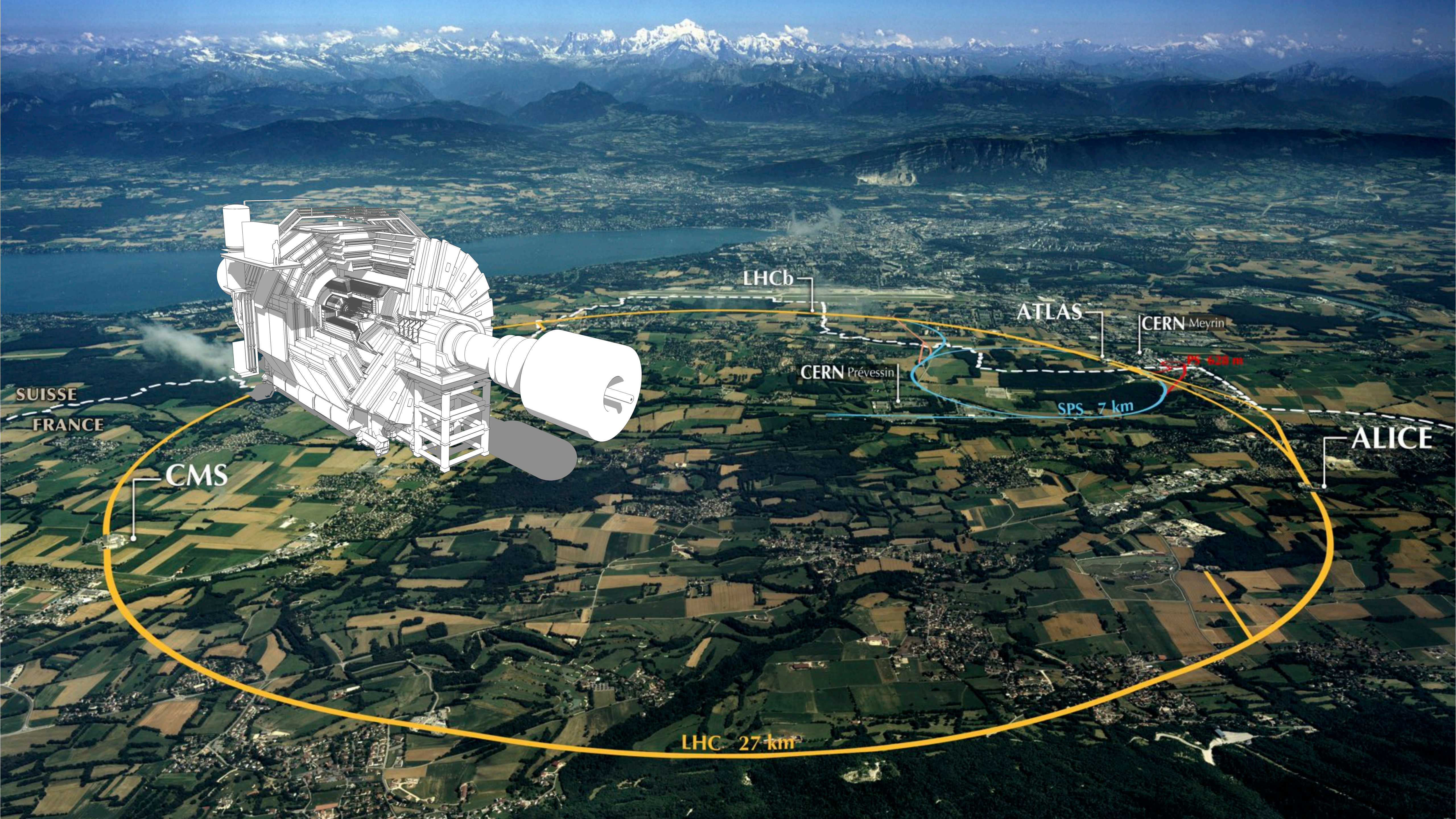
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LHCb

ATLAS

CERN Meyrin

CERN Prévessin

SPS 7 km

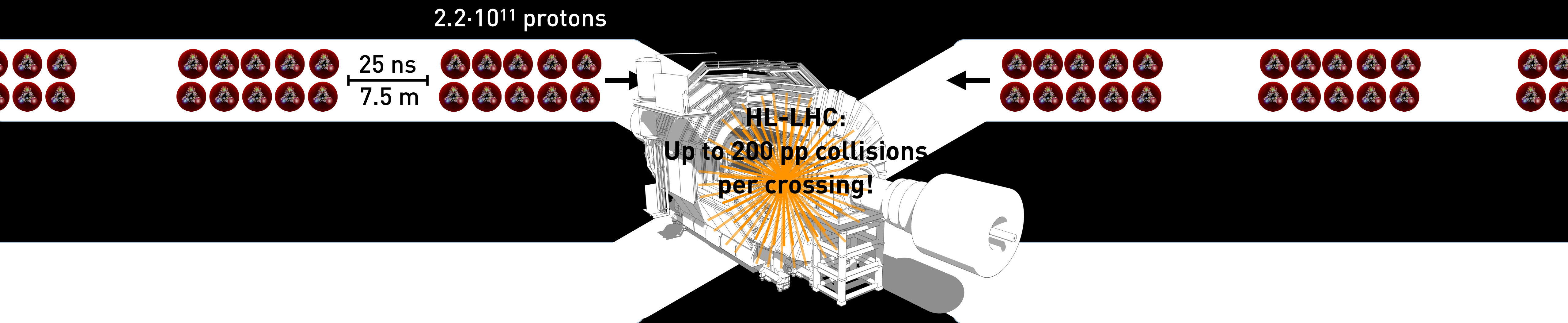
PS 6.28 m

ALICE

SUISSE
FRANCE

CMS

LHC 27 km



$2.2 \cdot 10^{11}$ protons

25 ns
7.5 m

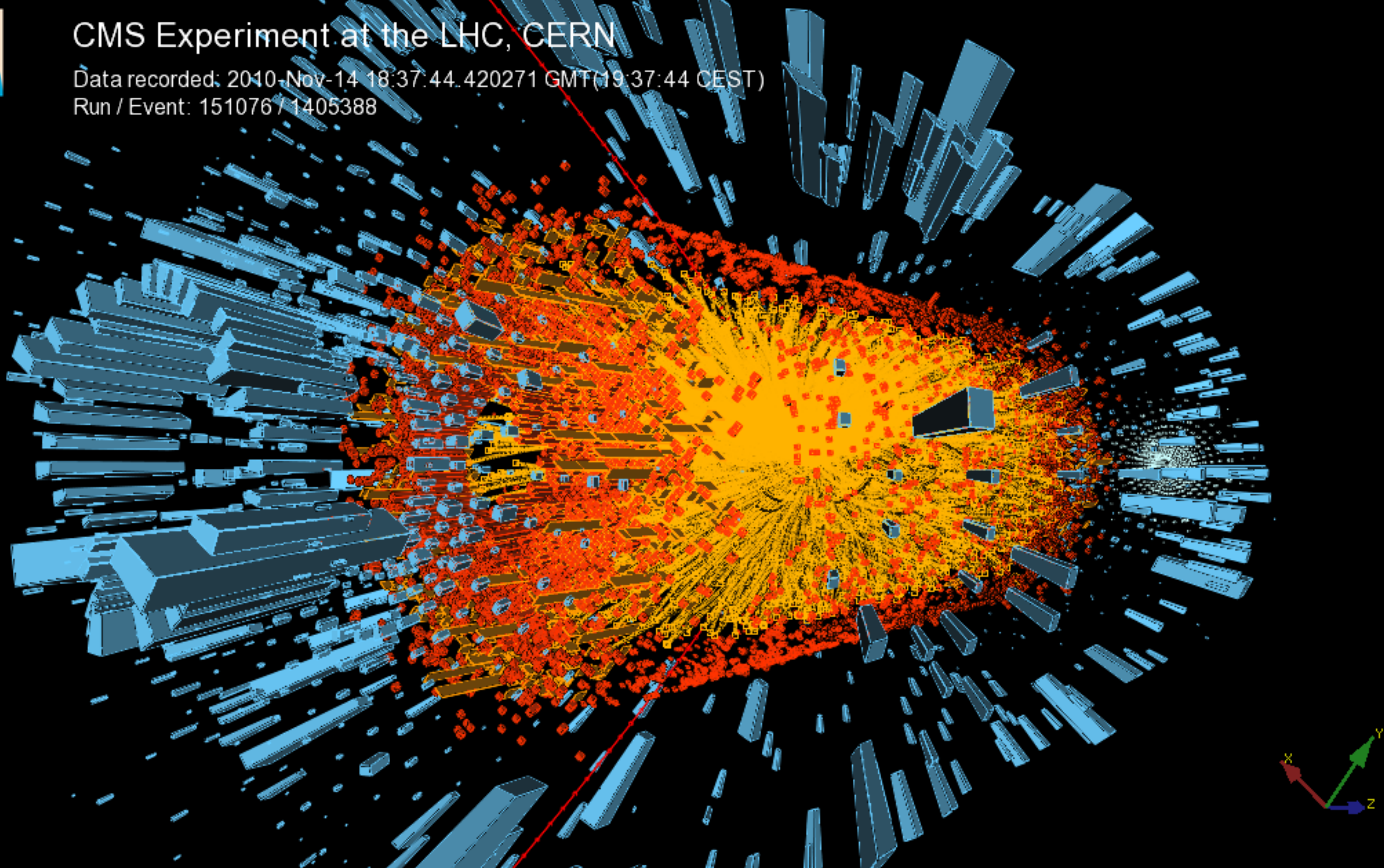
HL-LHC:
Up to 200 pp collisions
per crossing!



CMS Experiment at the LHC, CERN

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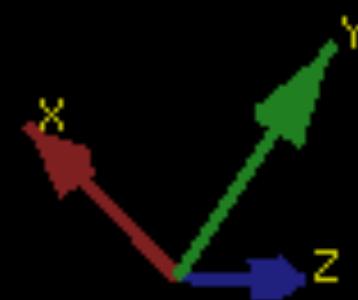


CMS Experiment at the LHC, CERN

Data recorded: 2010-Nov-14 18:37:44.420271 GMT(19:37:44 CEST)

Run / Event: 151076 / 1405388

Up to 8 billion collisions per second
~10 PB of data per second





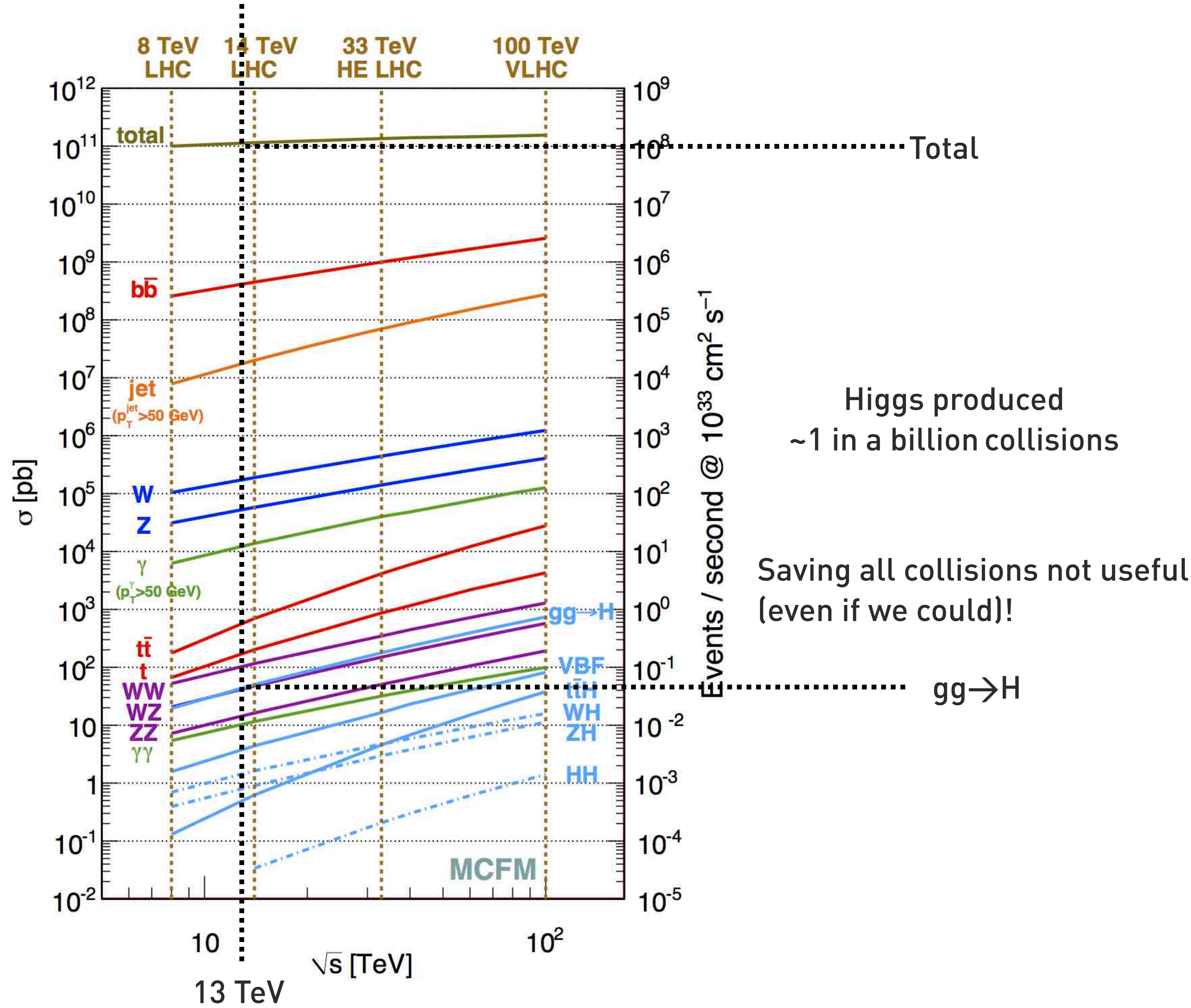
CMS Experiment at the LHC, CERN

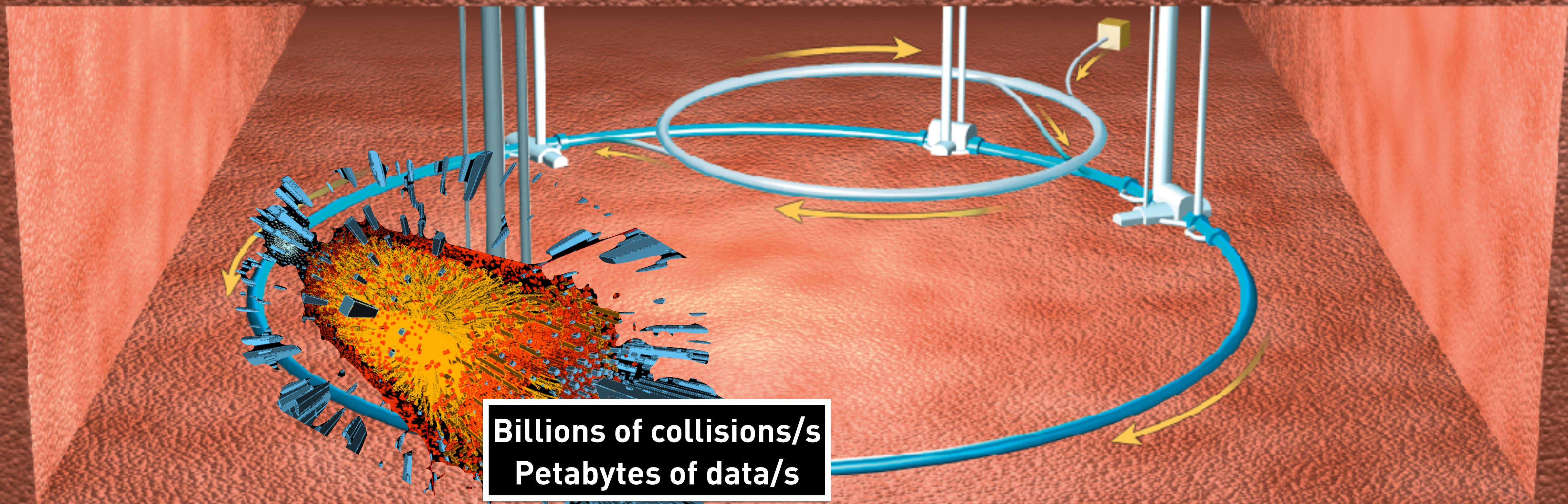
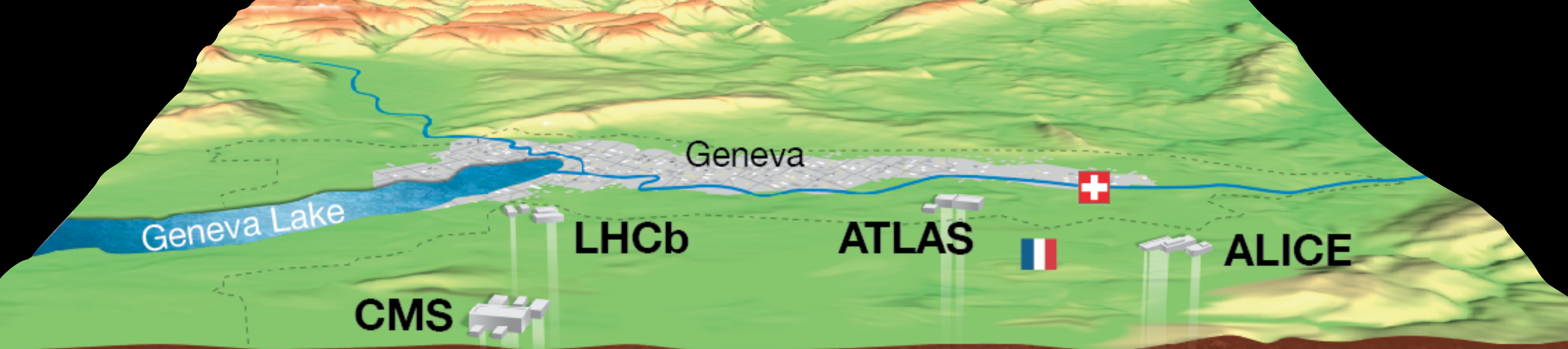
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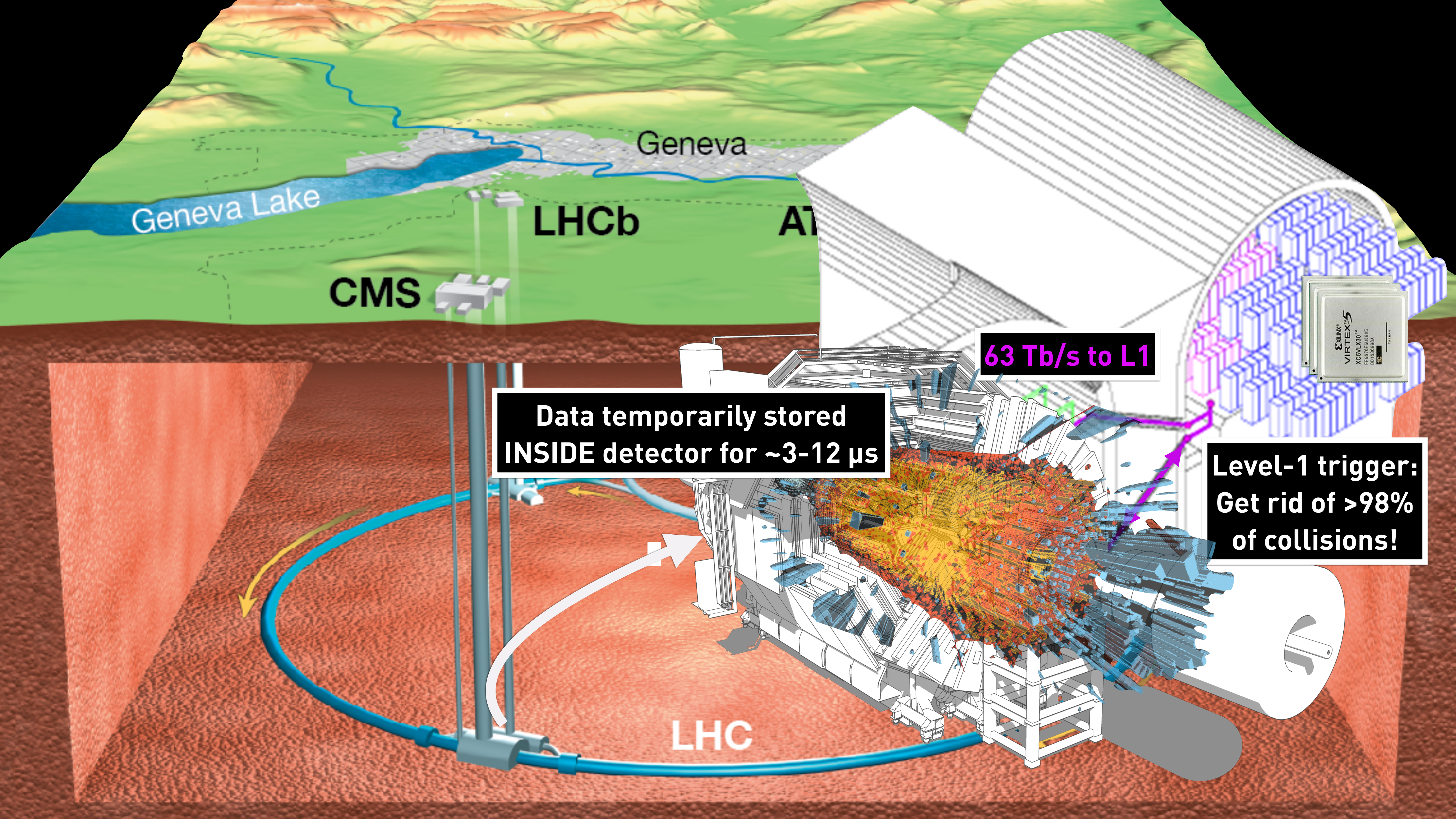
Up to 8 billion collisions per second
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Billions of collisions/s
Petabytes of data/s



Geneva Lake

Geneva

CMS

LHCb

ATLAS

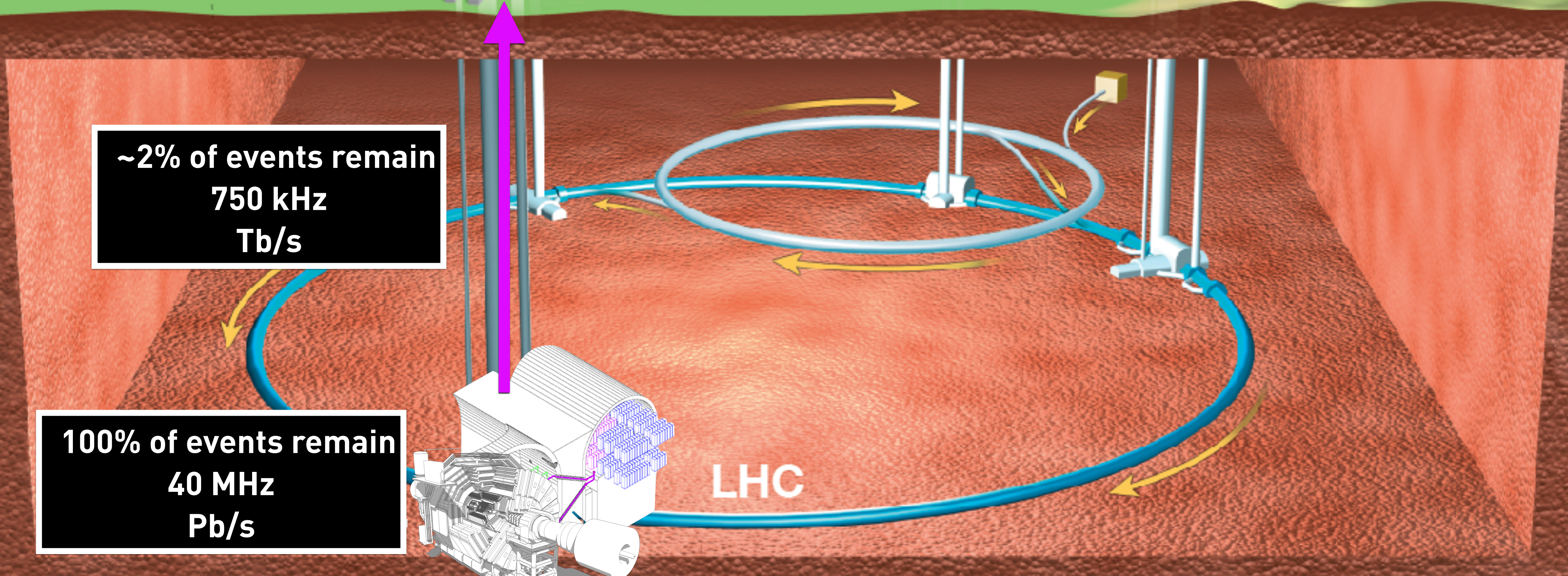
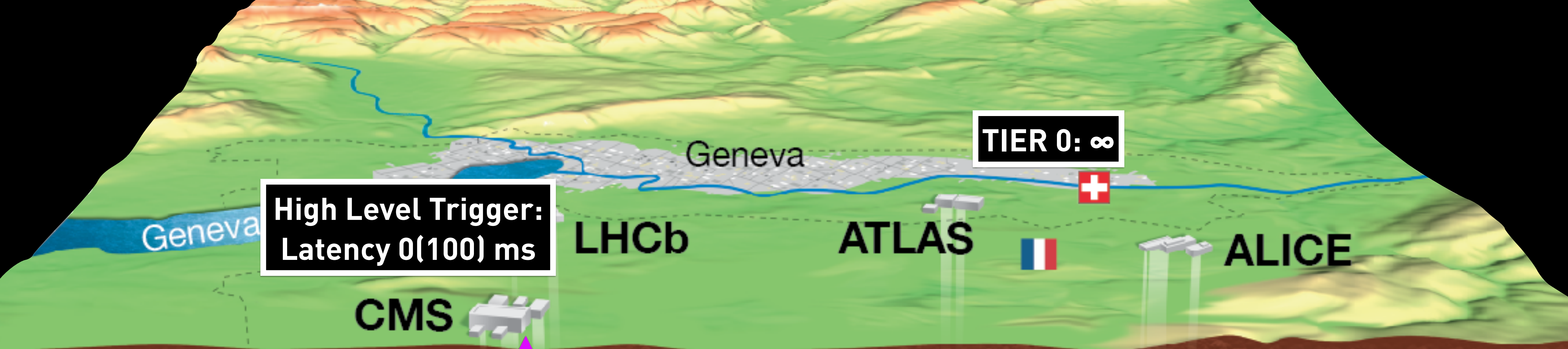
63 Tb/s to L1

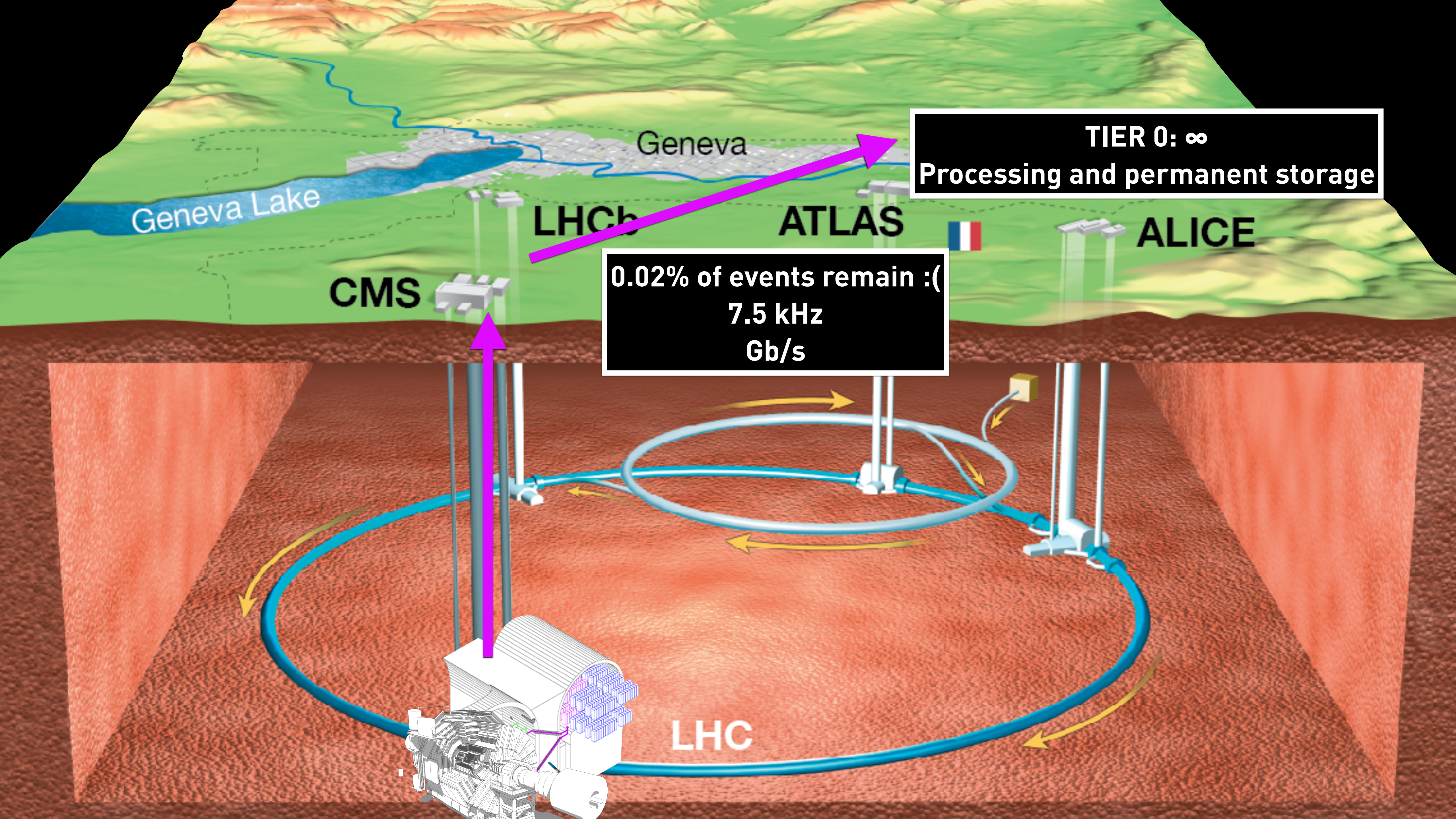
Data temporarily stored
INSIDE detector for ~3-12 μ s

Level-1 trigger:
Get rid of >98%
of collisions!

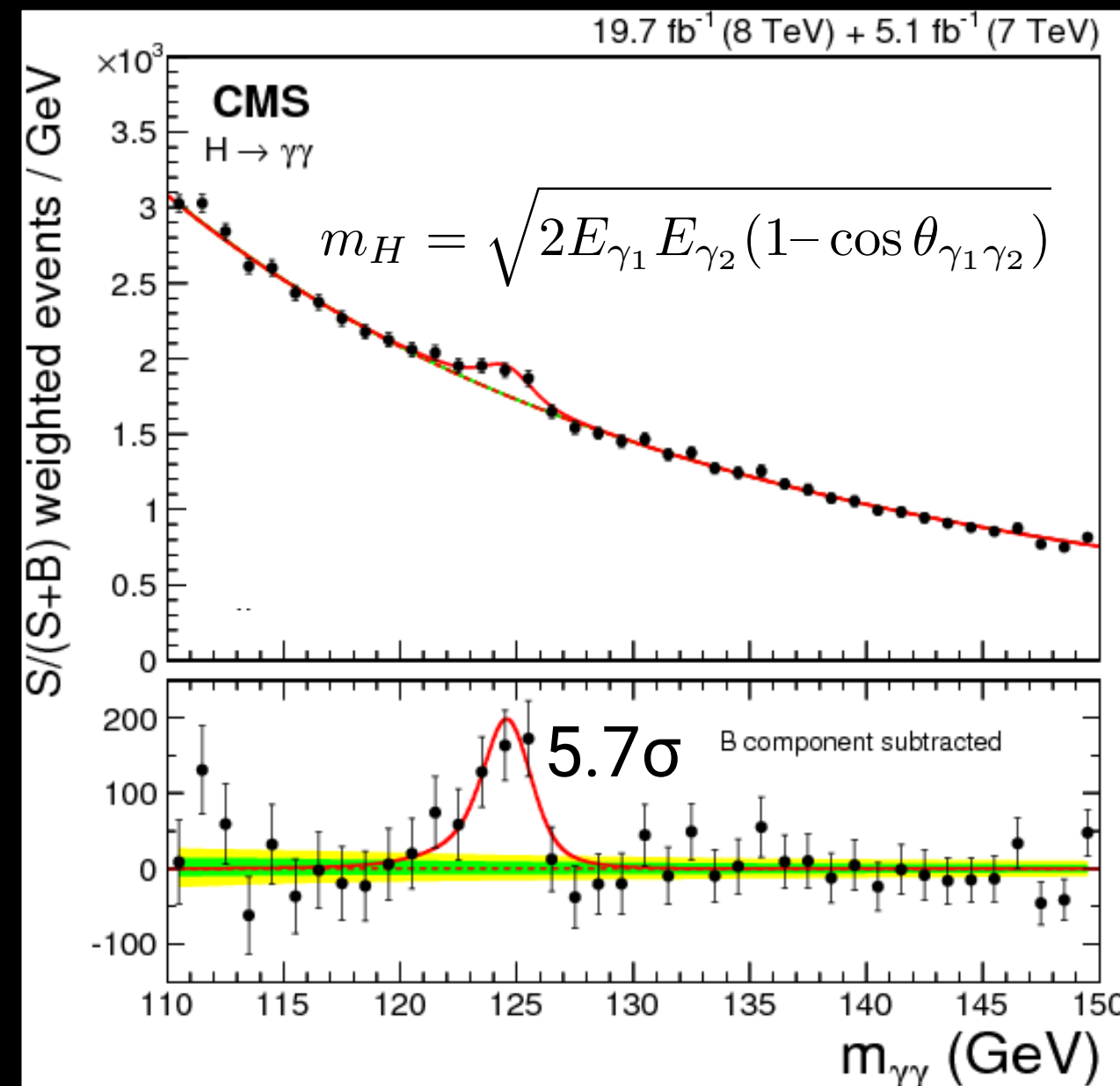
LHC







ALL OF OUR PHYSICS RESULTS USE ONLY ~0.02% OF COLLISION DATA!



To make sure we select “the right” 0.02%, algorithms must be

- **Fast (get more data through)**
- **Accurate (select the right data)**

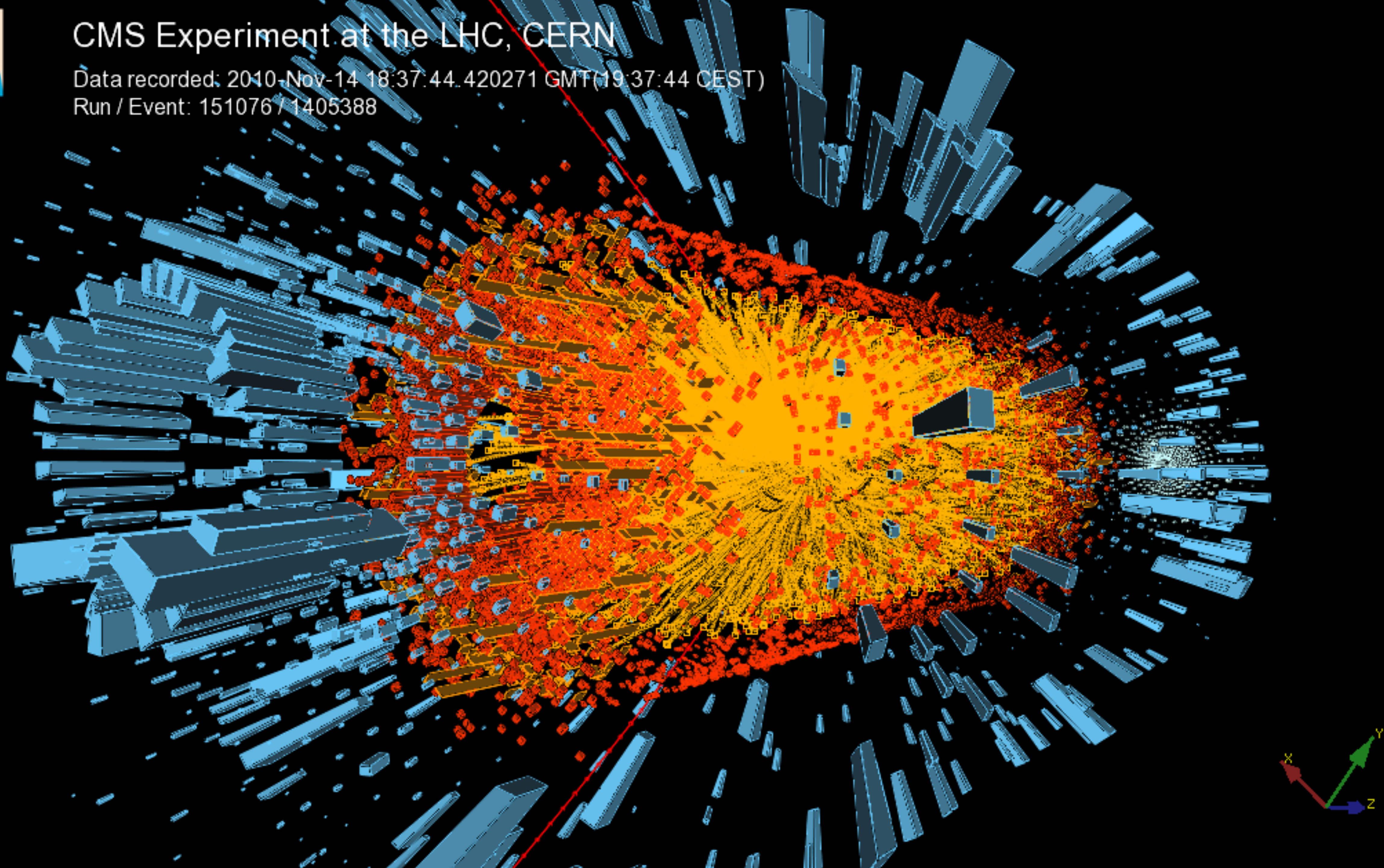
LHC



CMS Experiment at the LHC, CERN

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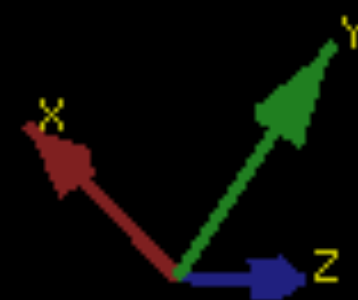


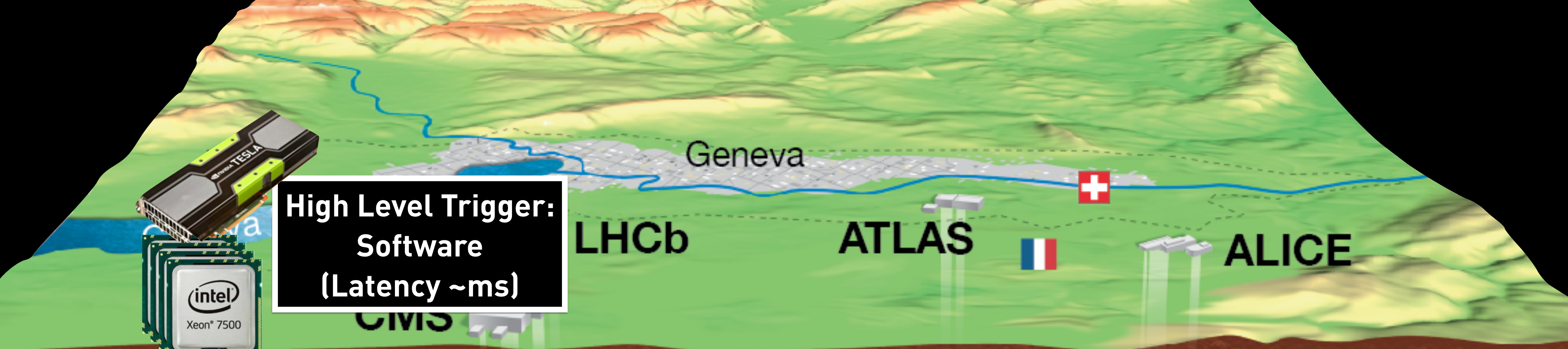
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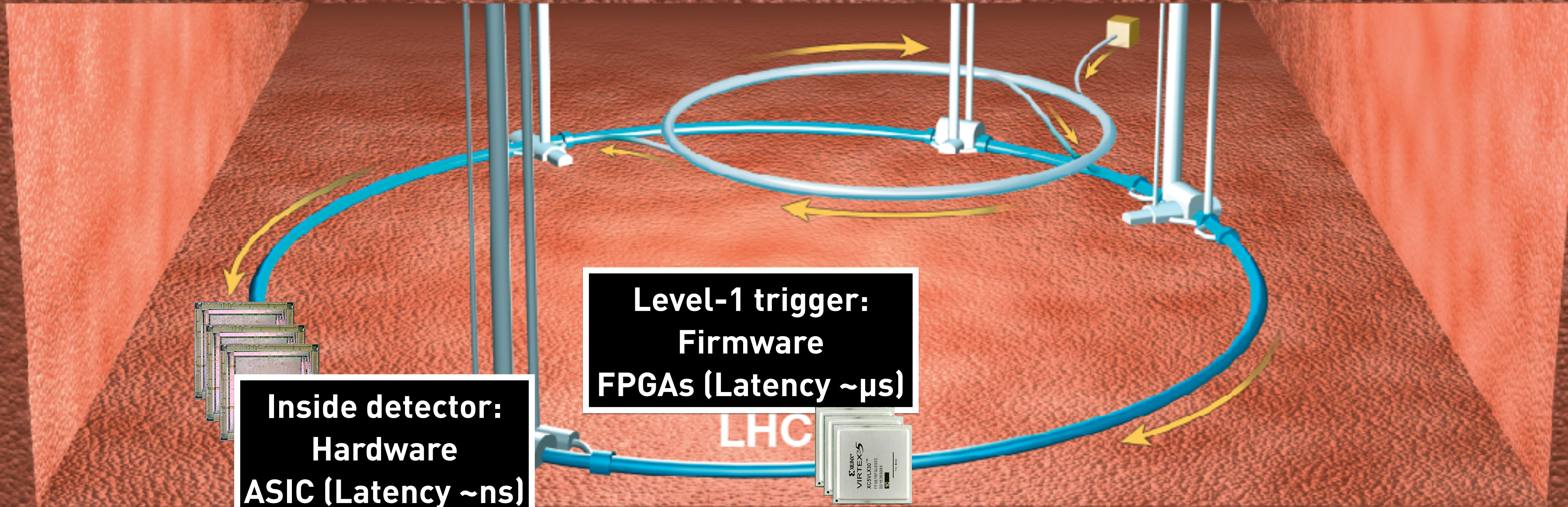
Run / Event: 151076 / 1405388

→ Utilise modern Machine Learning to become
faster
better
and do more



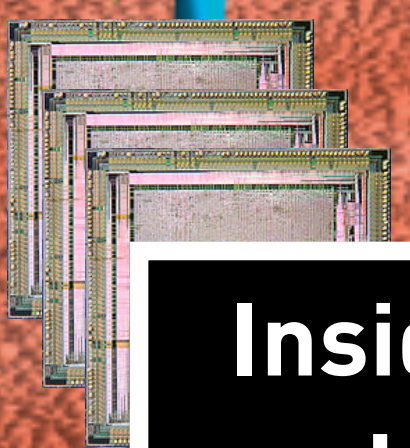


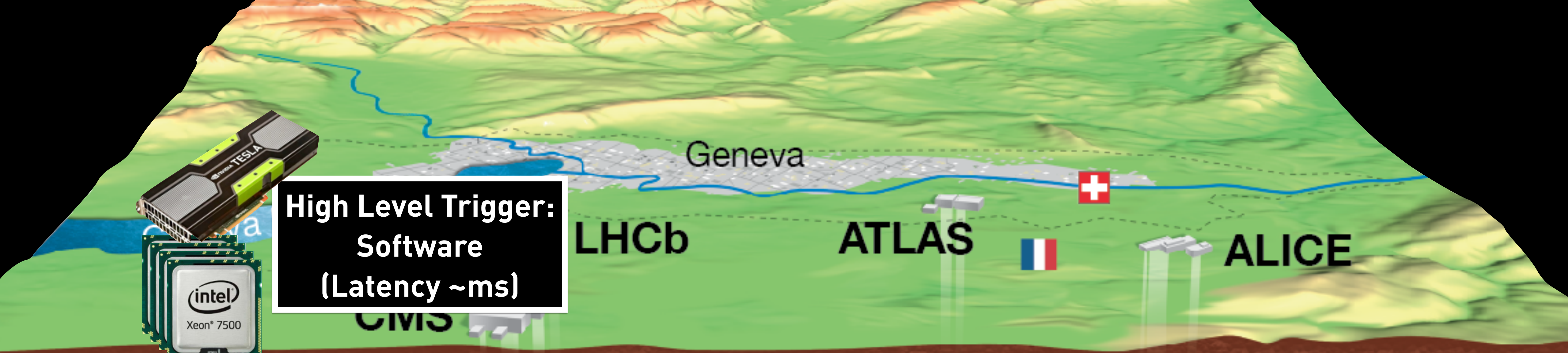
**High Level Trigger:
Software
(Latency ~ms)**



**Level-1 trigger:
Firmware
FPGAs (Latency ~ μ s)**

**Inside detector:
Hardware
ASIC (Latency ~ns)**





**High Level Trigger:
Software
(Latency ~ms)**



LHCb

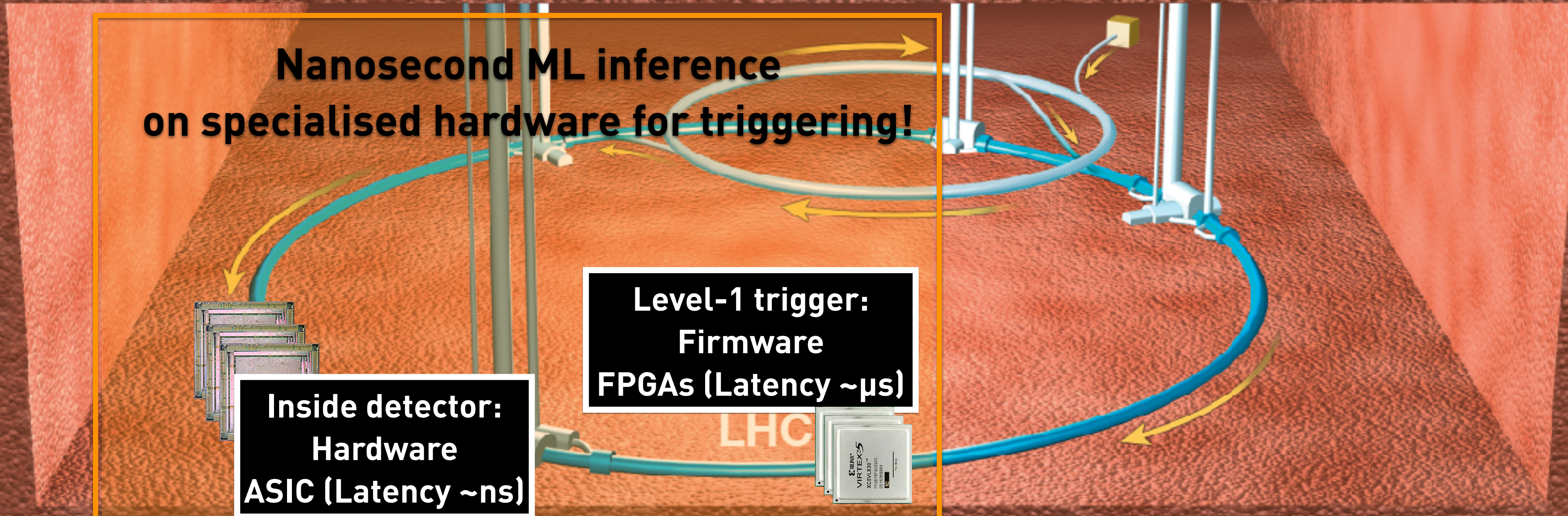
ATLAS

ALICE

**Nanosecond ML inference
on specialised hardware for triggering!**

**Level-1 trigger:
Firmware
FPGAs (Latency ~μs)**

**Inside detector:
Hardware
ASIC (Latency ~ns)**



LHC



Not covered in this talk. Great work here by S. Hasan (IPA)

**High Level Trigger:
Software
(Latency ~ms)**

LHCb

ATLAS

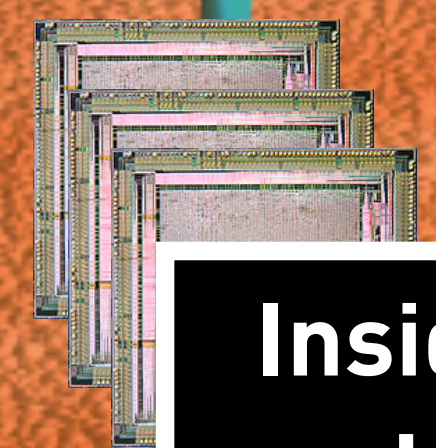
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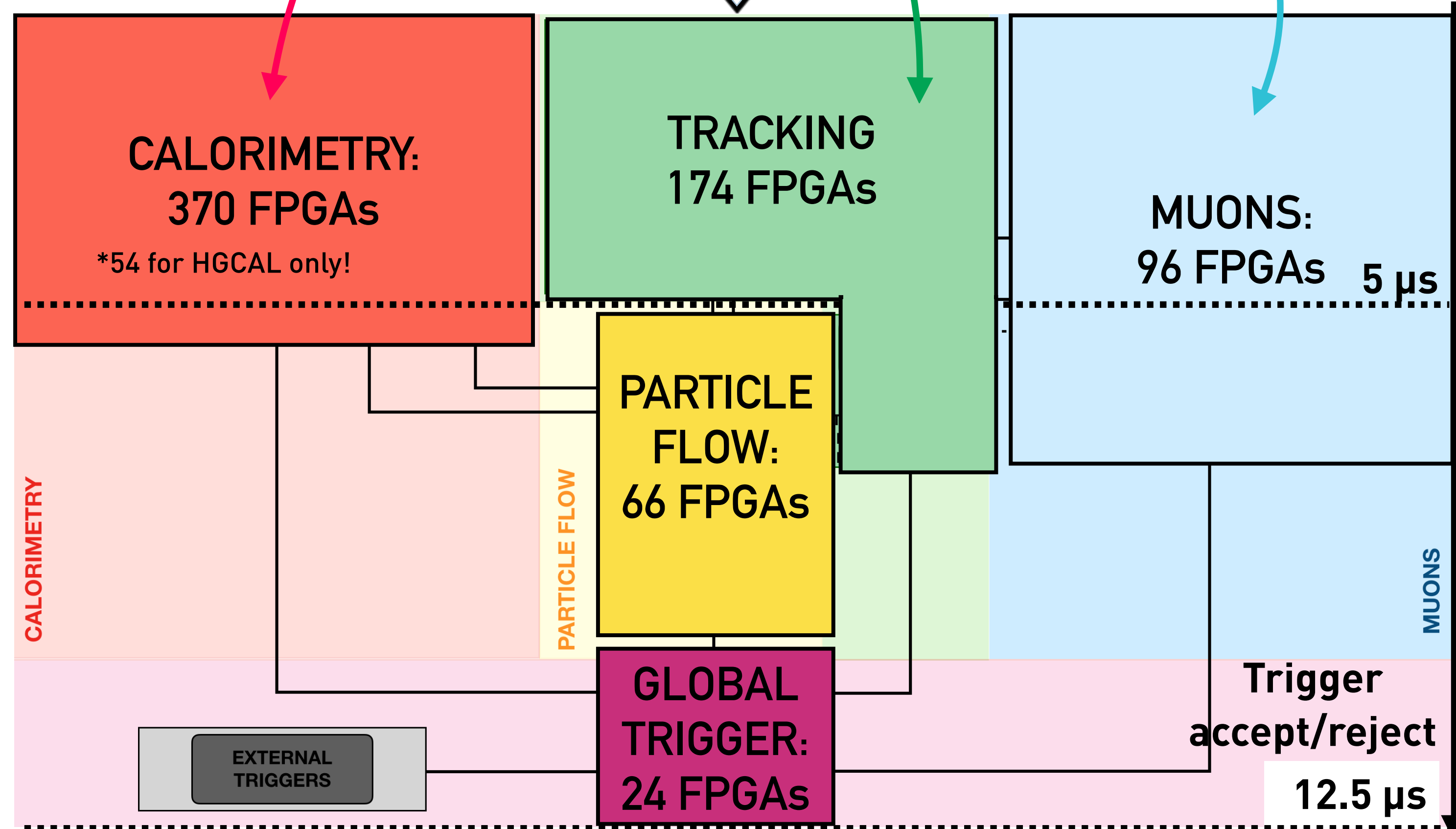
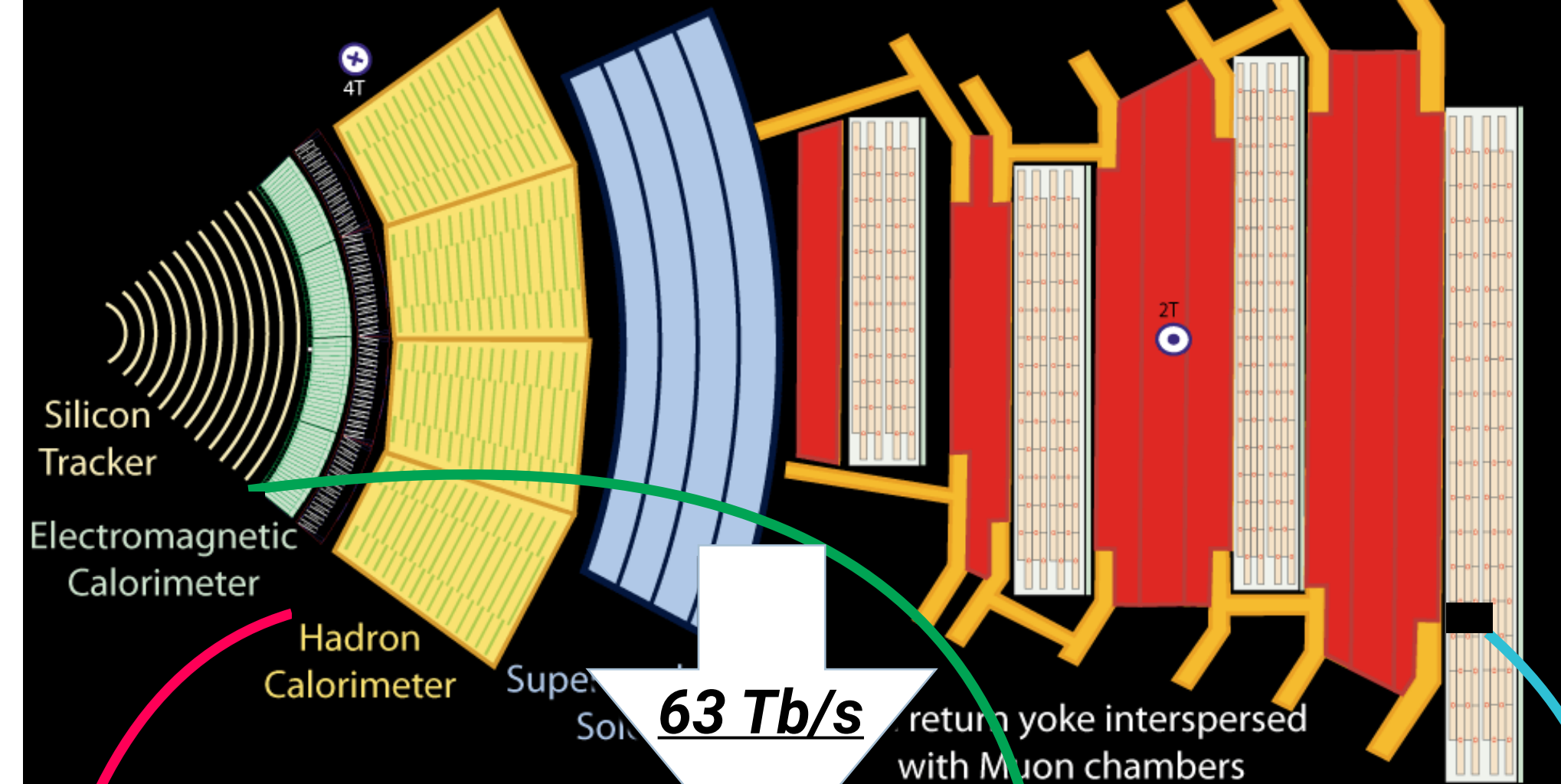
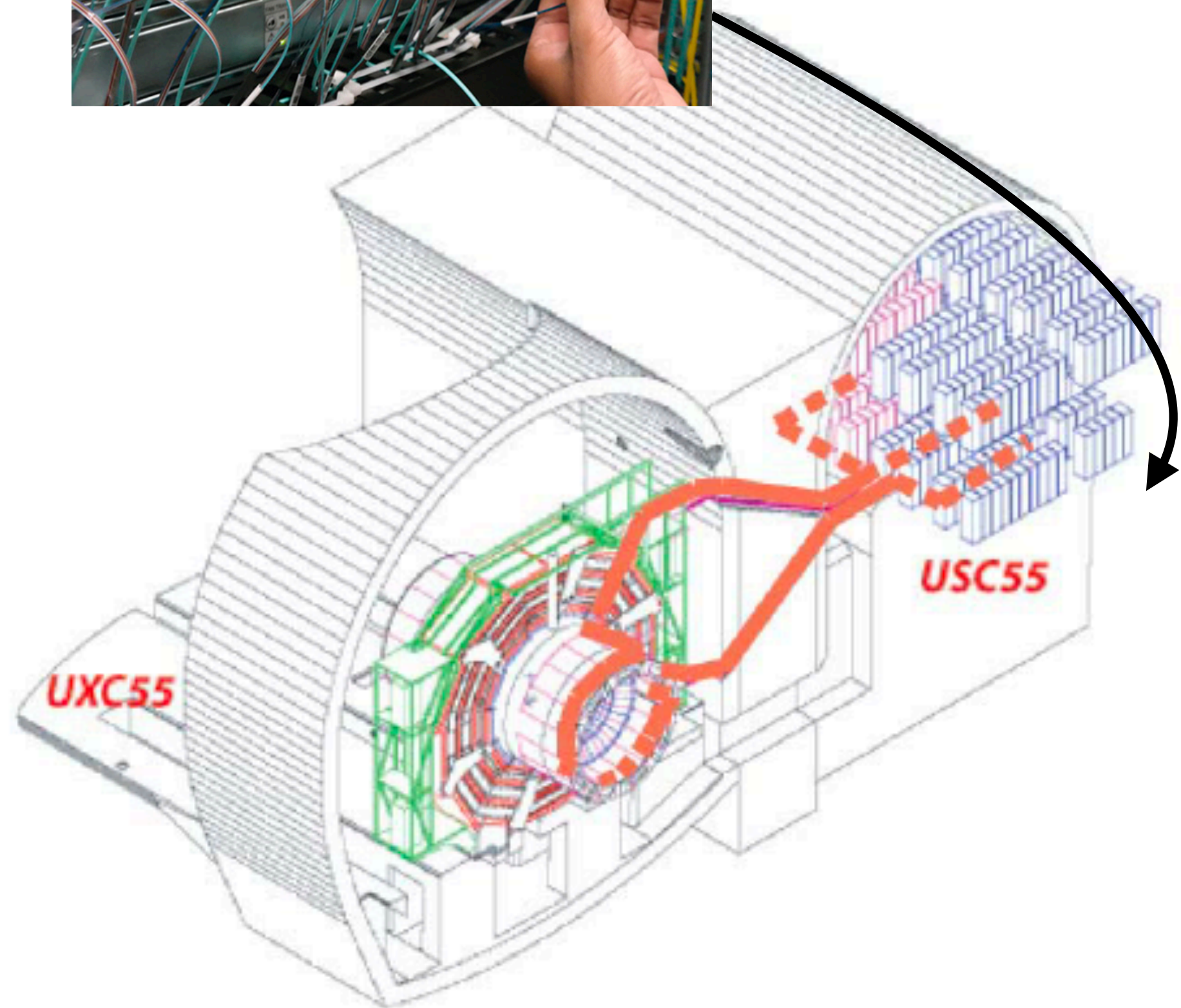
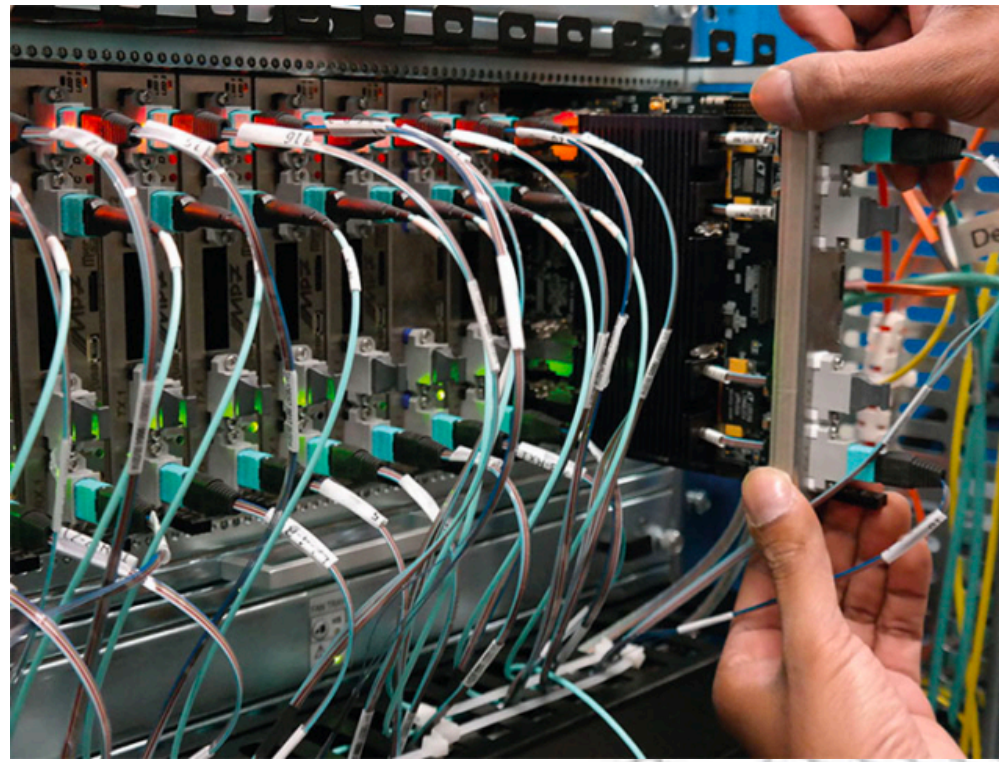
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Firmware
FPGAs (Latency ~ μ s)**

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ASIC (Latency ~ns)**



LHC

The Level-1 trigger



Low latency

- Strictly limited by collisions occurring every 25 ns



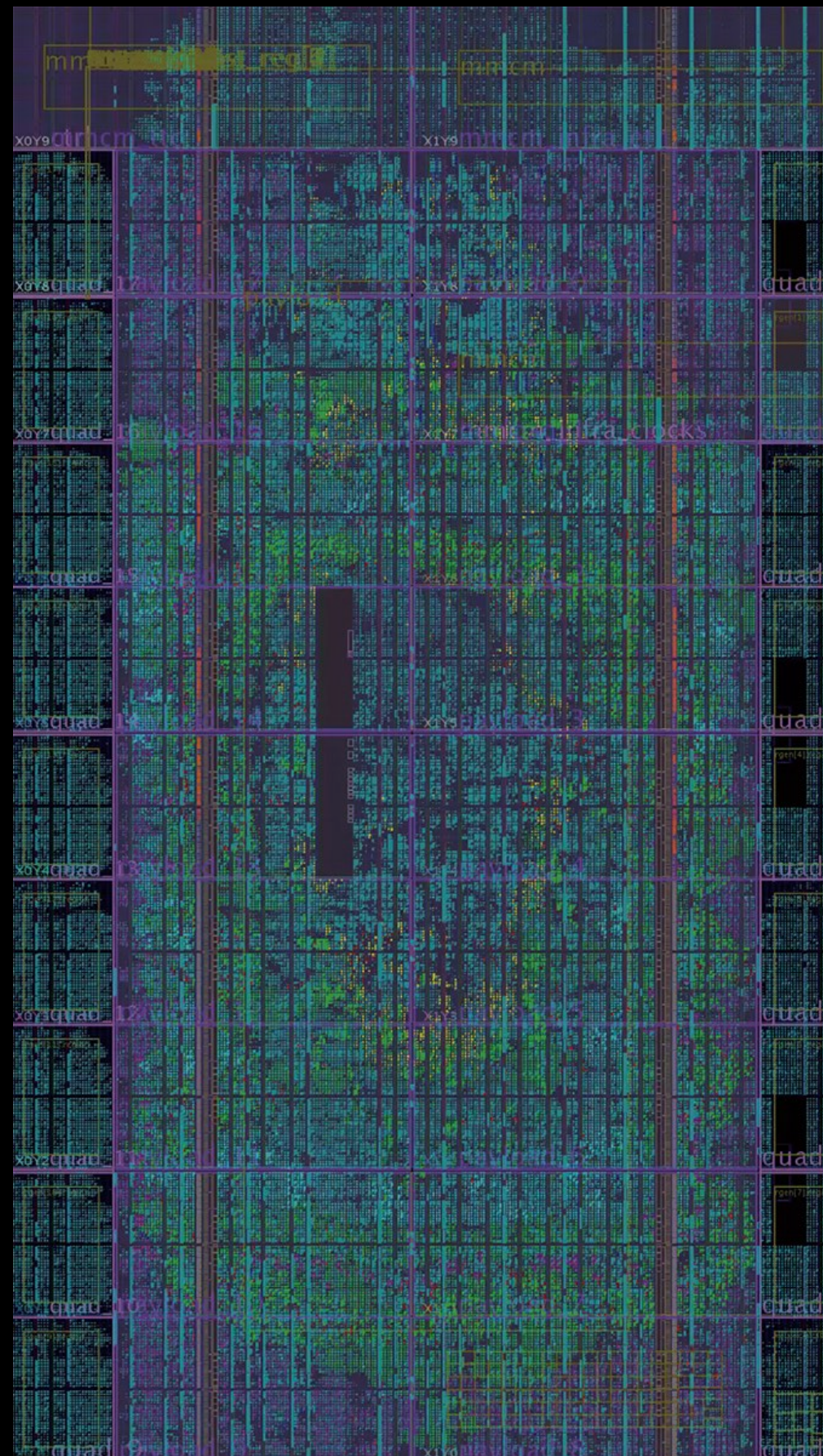
Low latency

- Strictly limited by collisions occurring every 25 ns



Low resource usage

- Several algorithms in parallel on single device



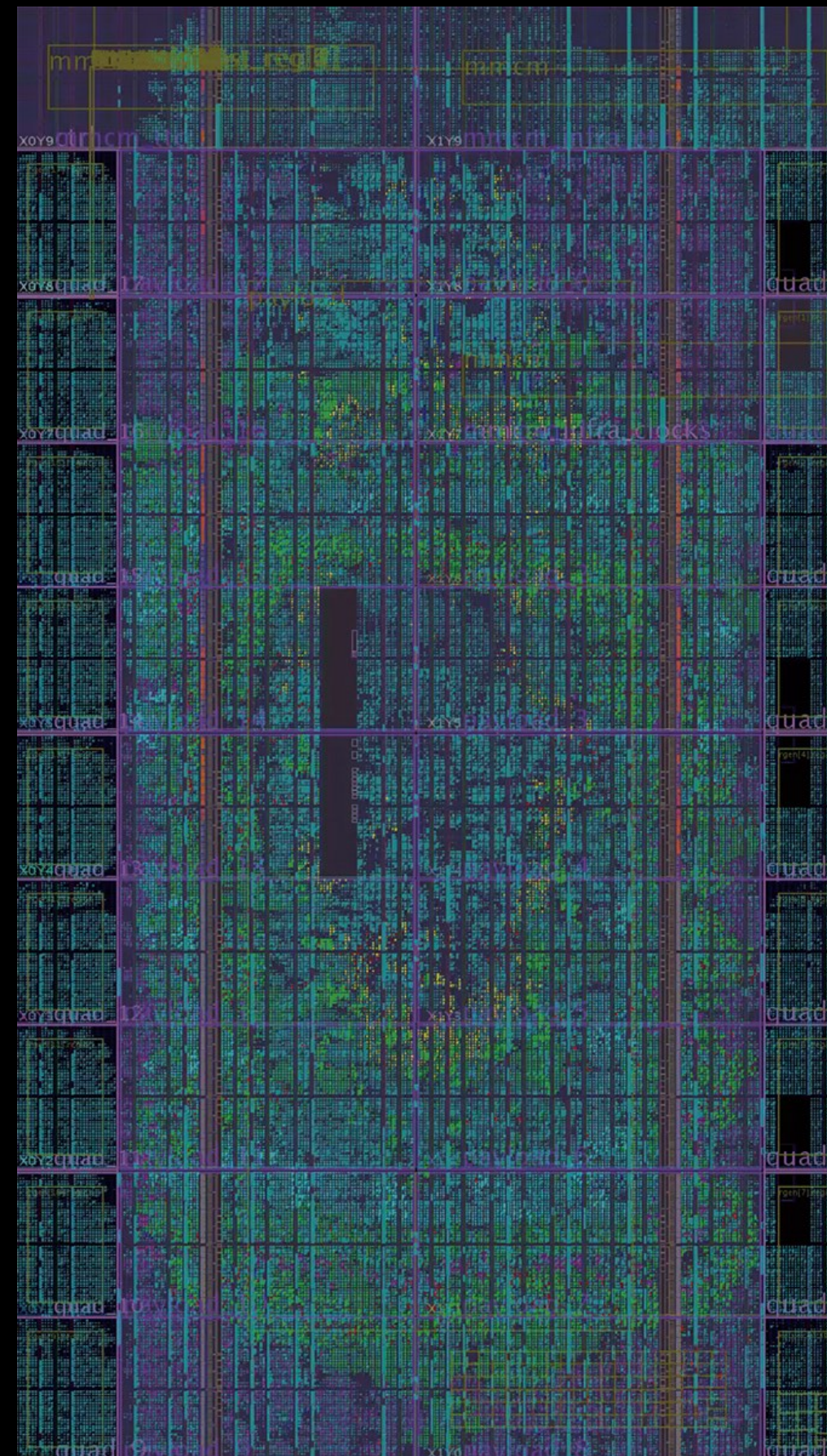
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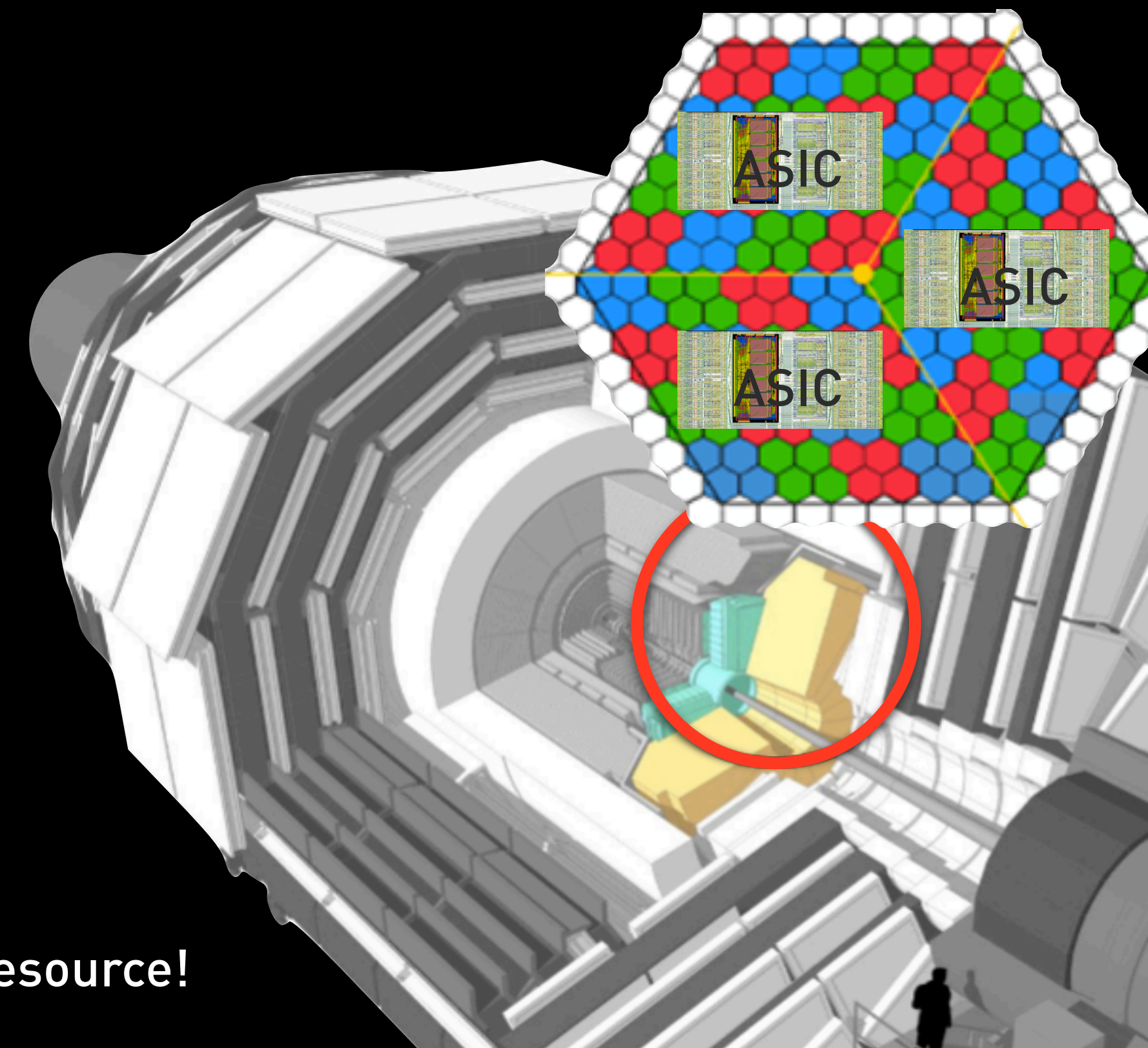
Low resource usage

- Several algorithms in parallel on single device



Power efficient

- On detector: Detector is cooled!
Limited to mW



ML algorithms here must be low power, low latency, low resource!

Why FPGAs at LHC?



Why FPGAs at LHC?



High parallelism = Low latency

- Can work on different data simultaneously (pipelining)! **High bandwidth**

Why FPGAs at LHC?



High parallelism = Low latency

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Power efficient

- FPGAS ~x10 more power efficient than GPUs
(even our FPGAs dissipate heat of $\sim 7\text{W}/\text{cm}^2$ while processing 5% of total internet traffic!)

Why FPGAs at LHC?



High parallelism = Low latency

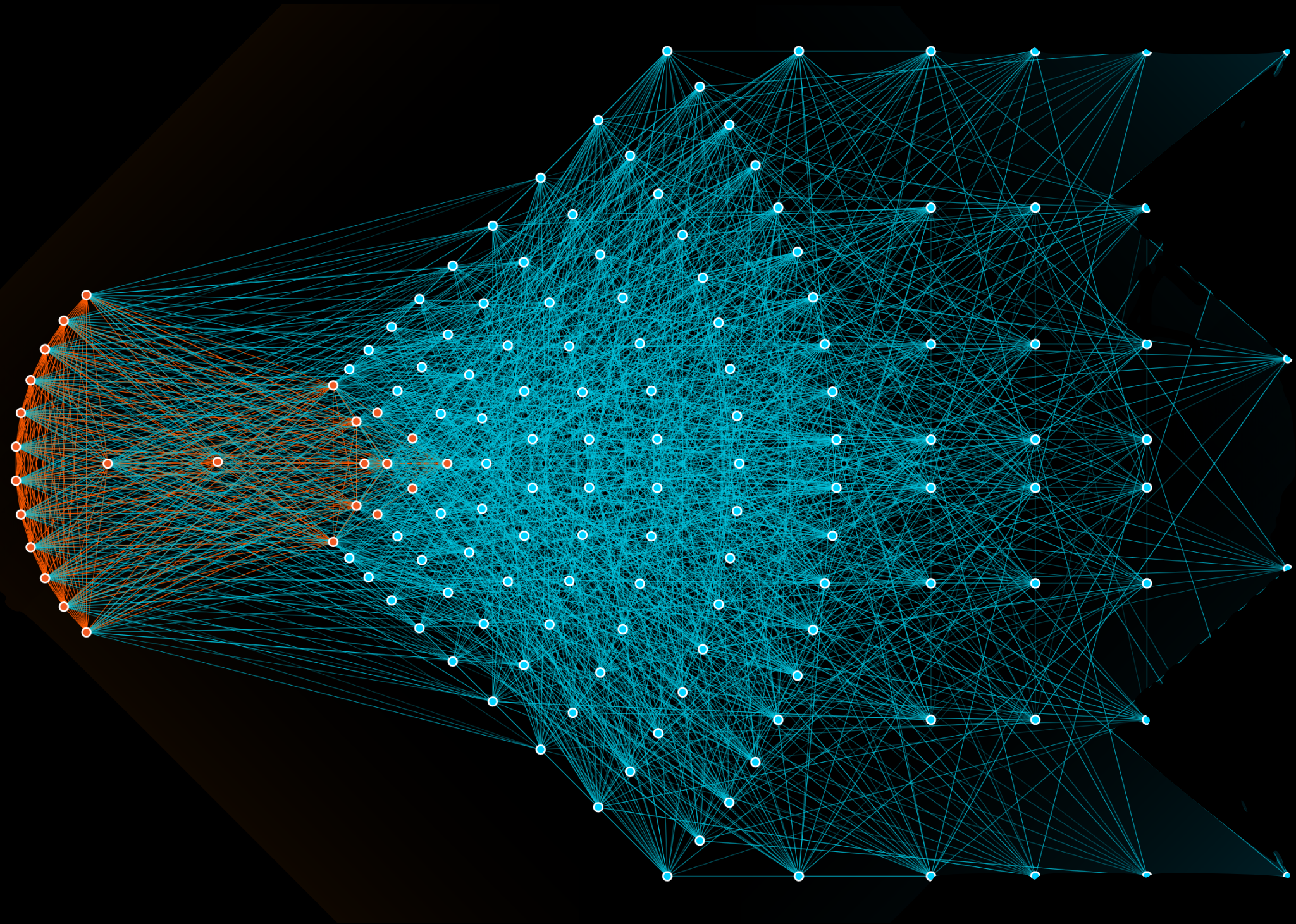
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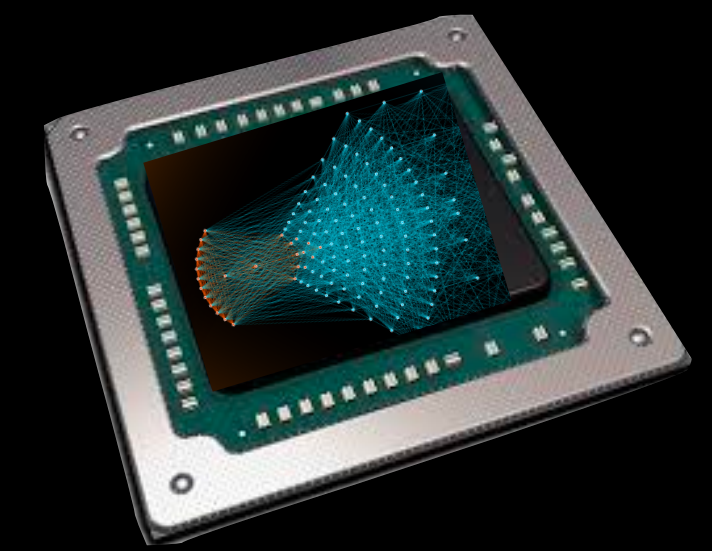
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(even our FPGAs dissipate heat of $\sim 7\text{W}/\text{cm}^2$ while processing 5% of total internet traffic!)

Latency deterministic

- CPU/GPU has processing randomness, FPGAs **repeatable and predictable latency**



Ideally



Reality

Edge inference

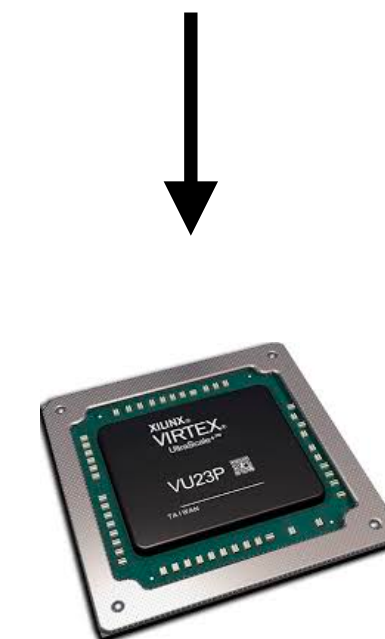
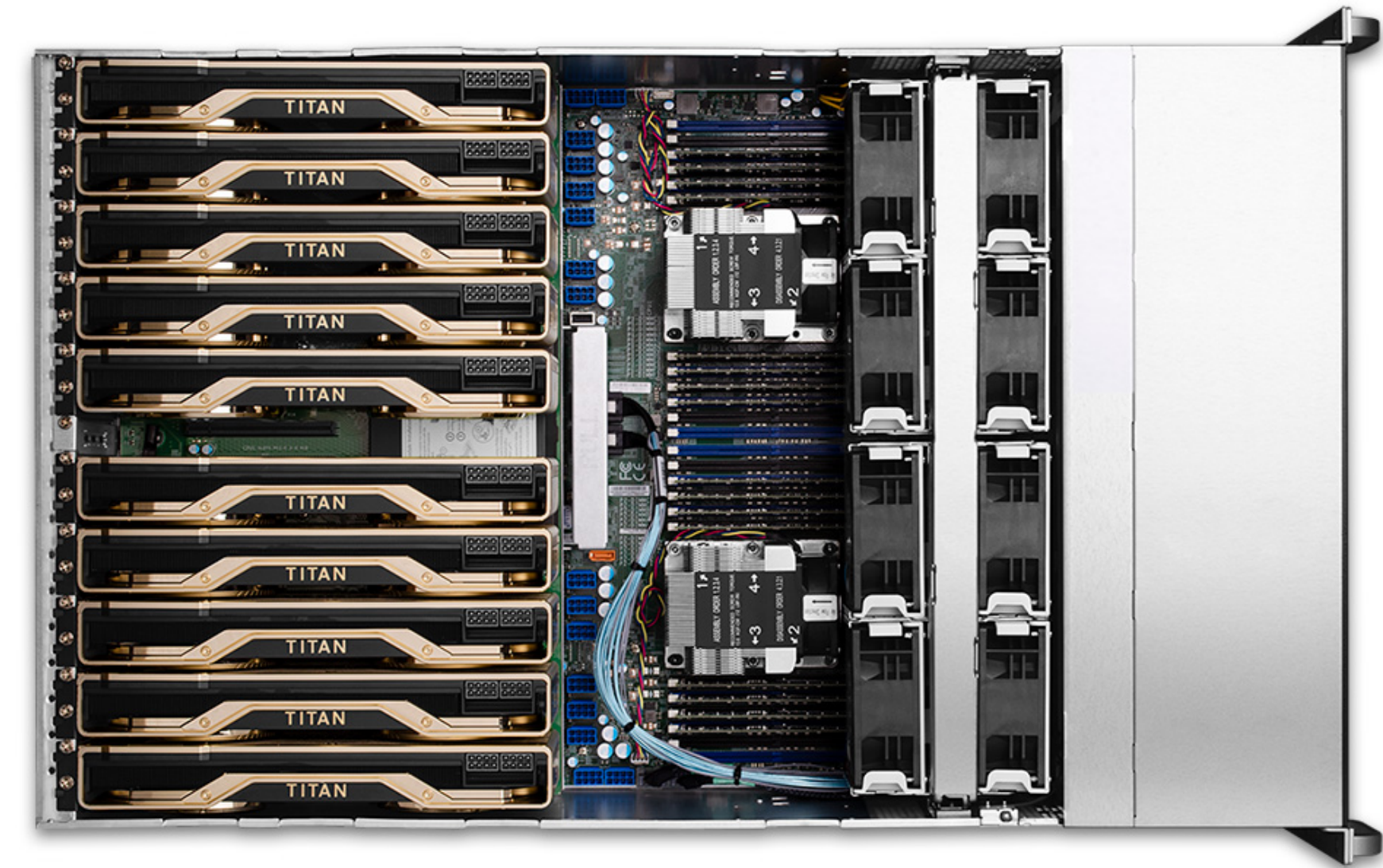
Before deploying any DNN on the edge, must make it efficient!

During training

- **Quantization:** do you really need 32-bit FP precision?
- **Pruning:** removal insignificant synapses
- **Knowledge distillation** (see Patrick Odagiu talk tomorrow!)

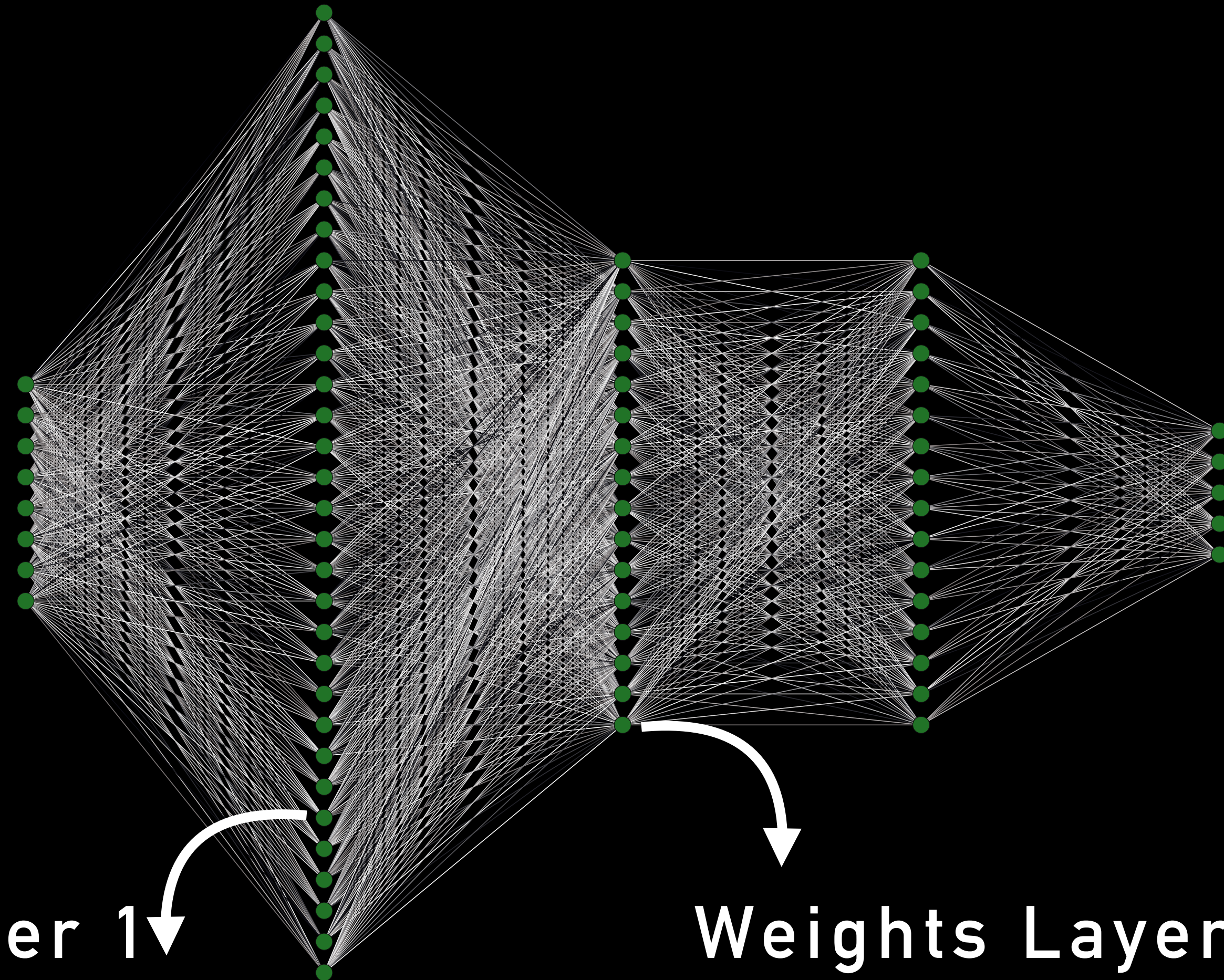
Post-training

- **Parallelise:**
all computation that can be done in parallel, do in parallel!

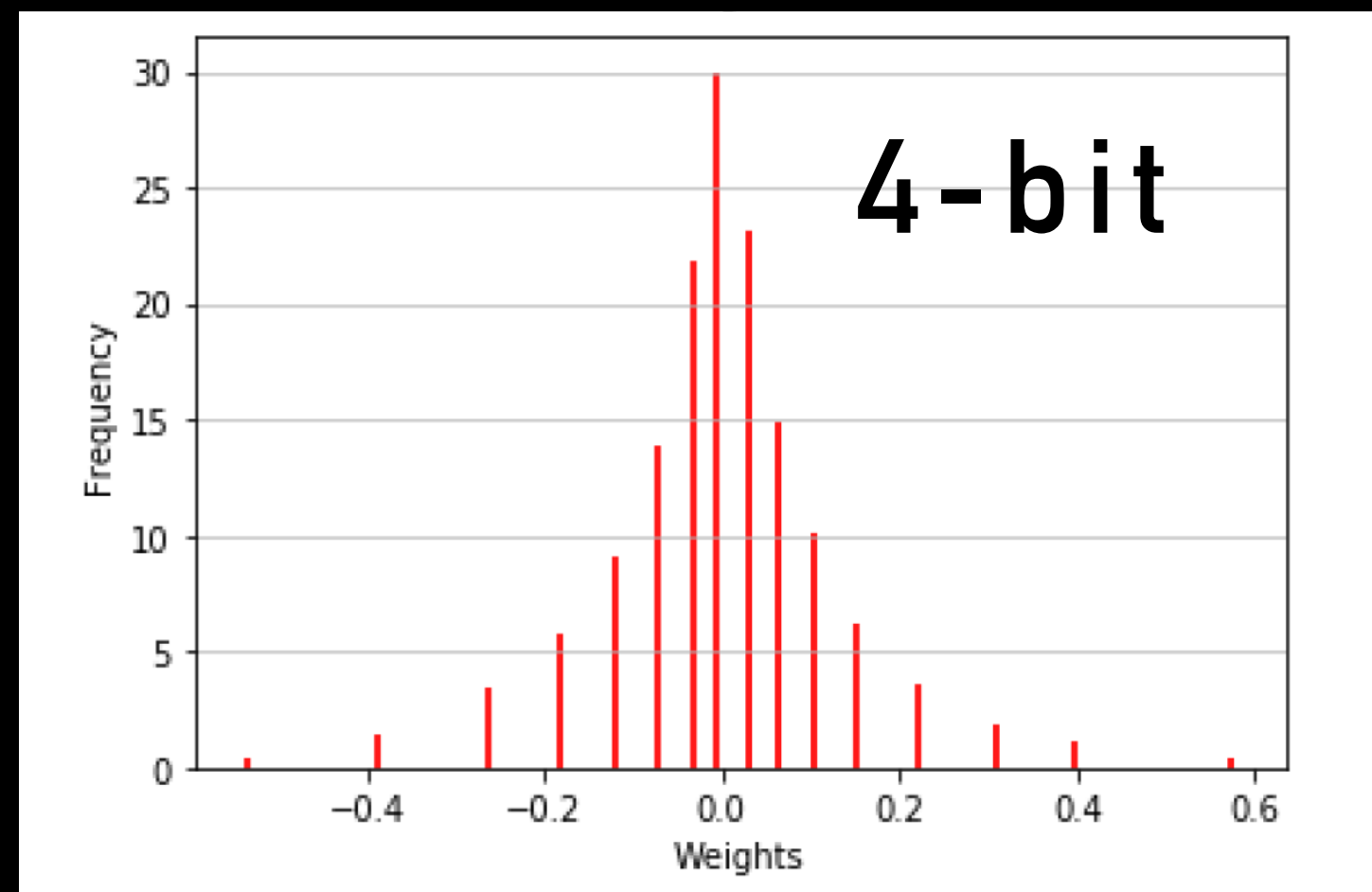


Quantization

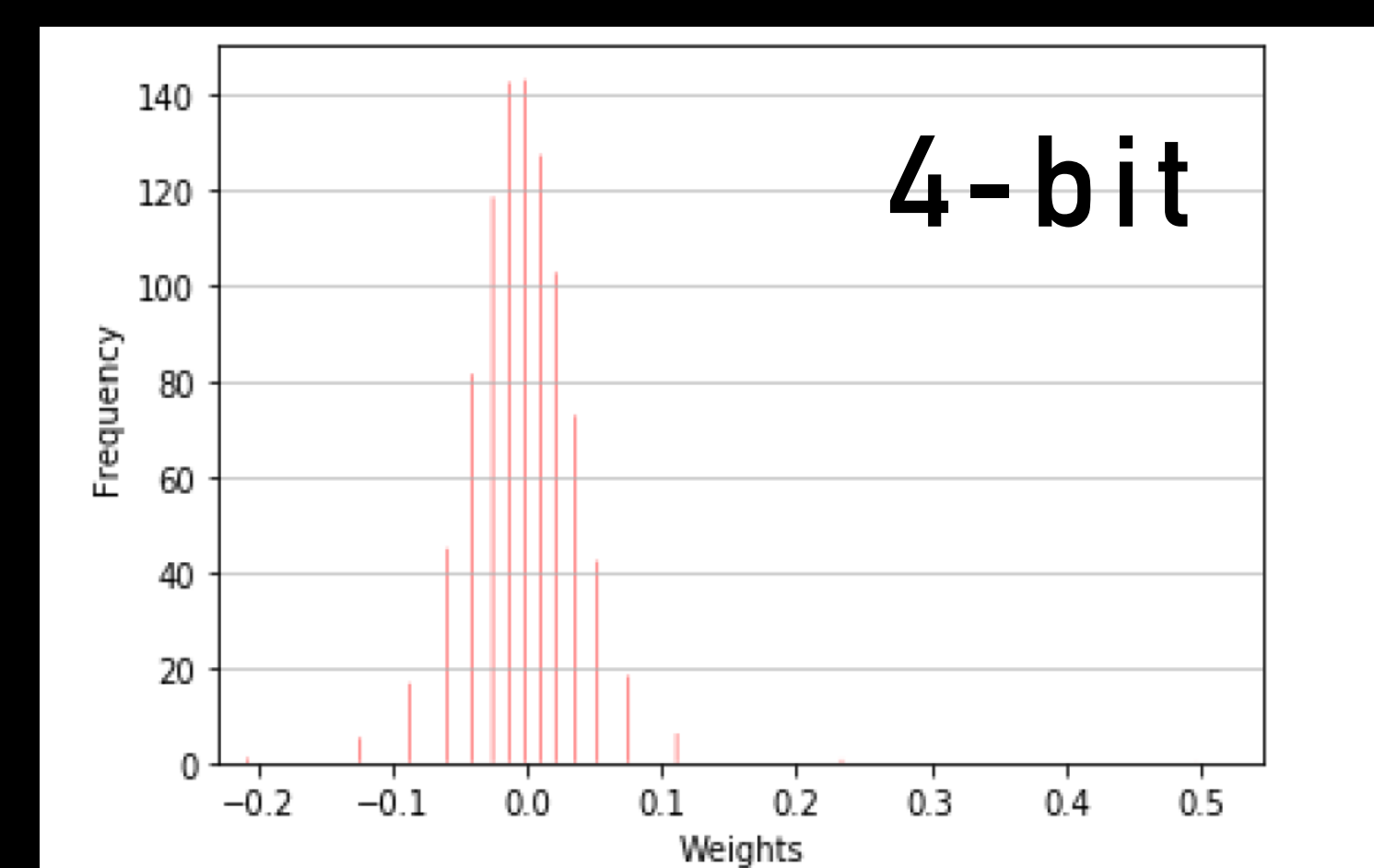
Fixed point



Weights Layer 1



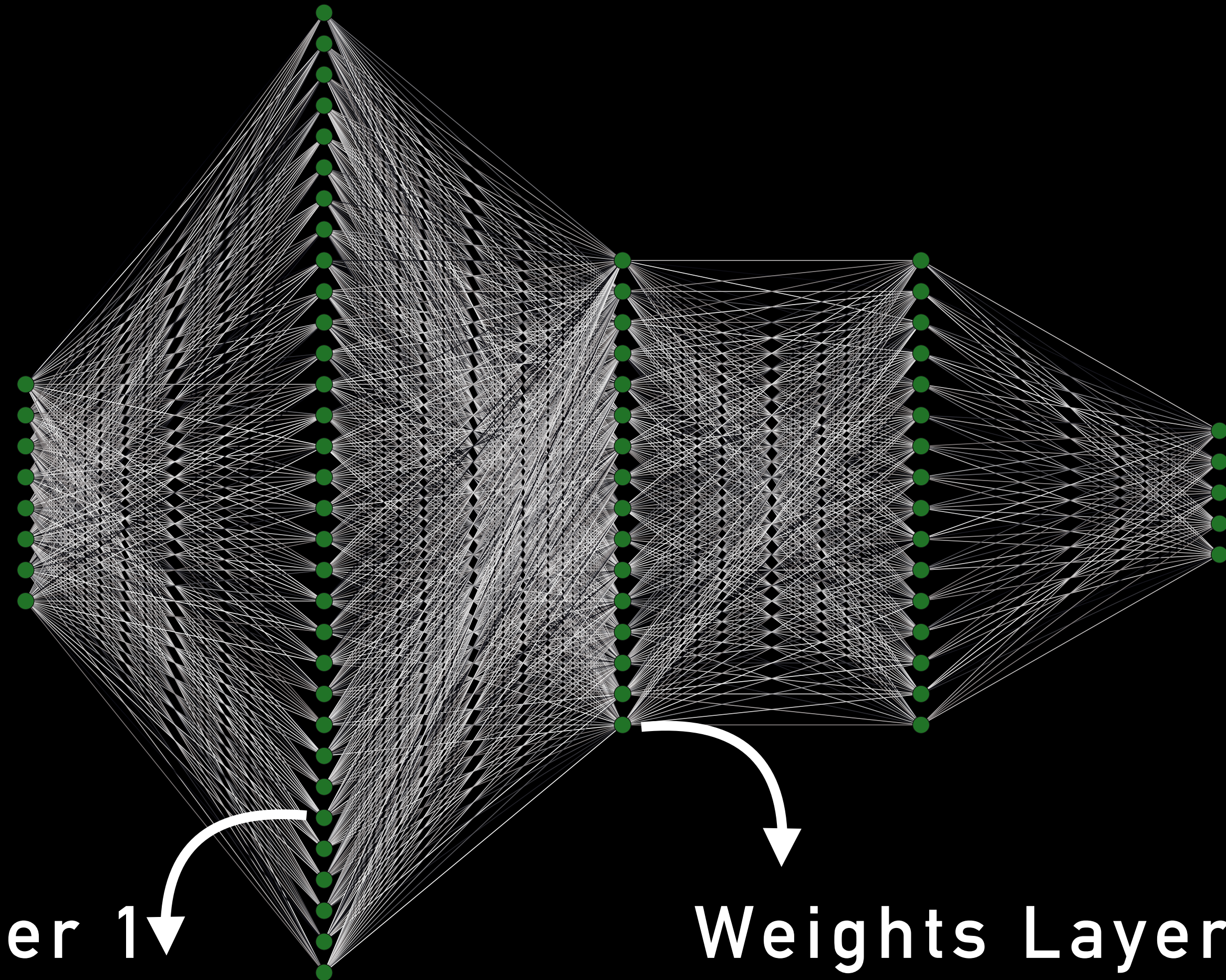
Weights Layer 2



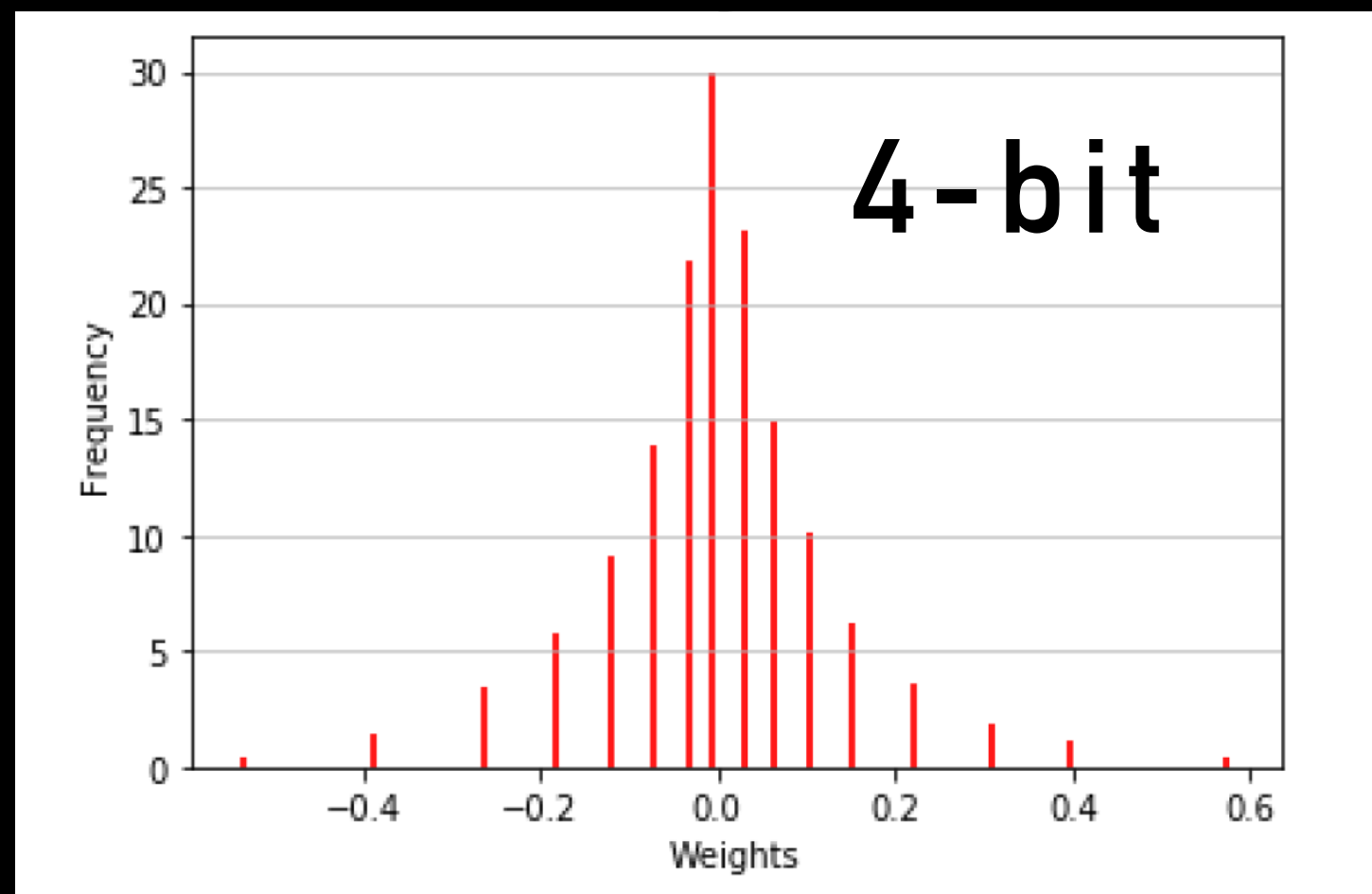
Quantization

Fixed point

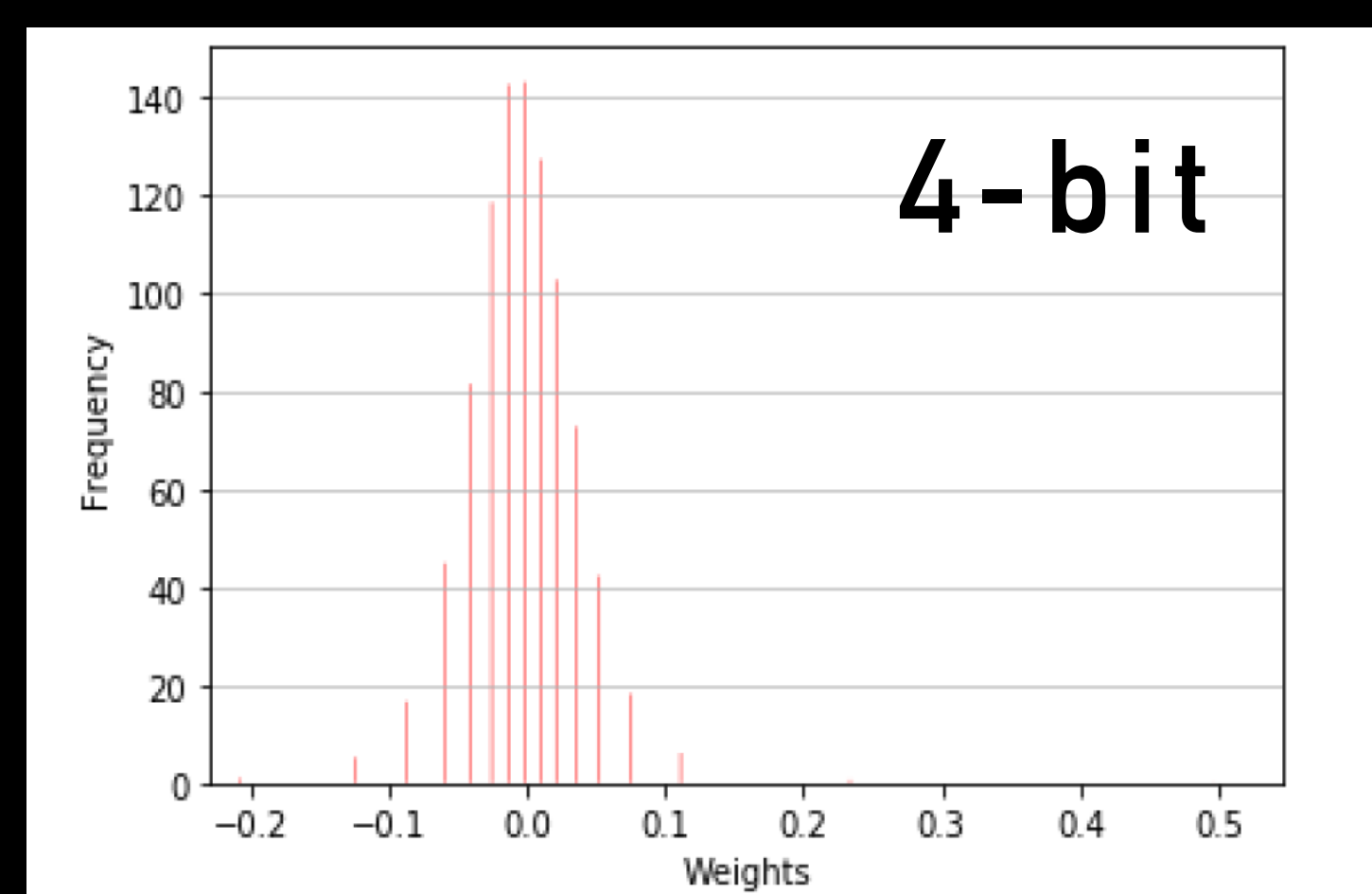
0101.1011101010



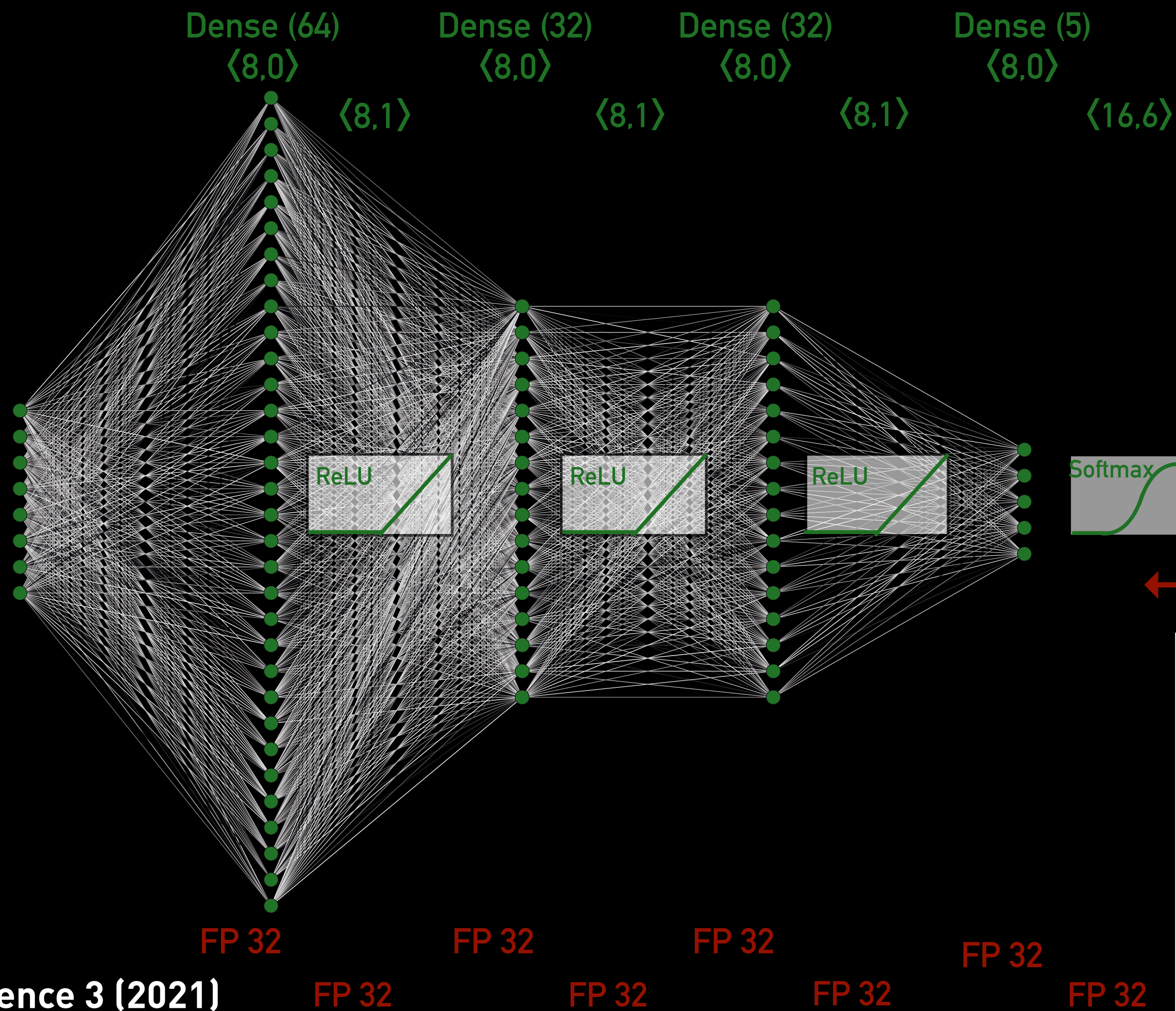
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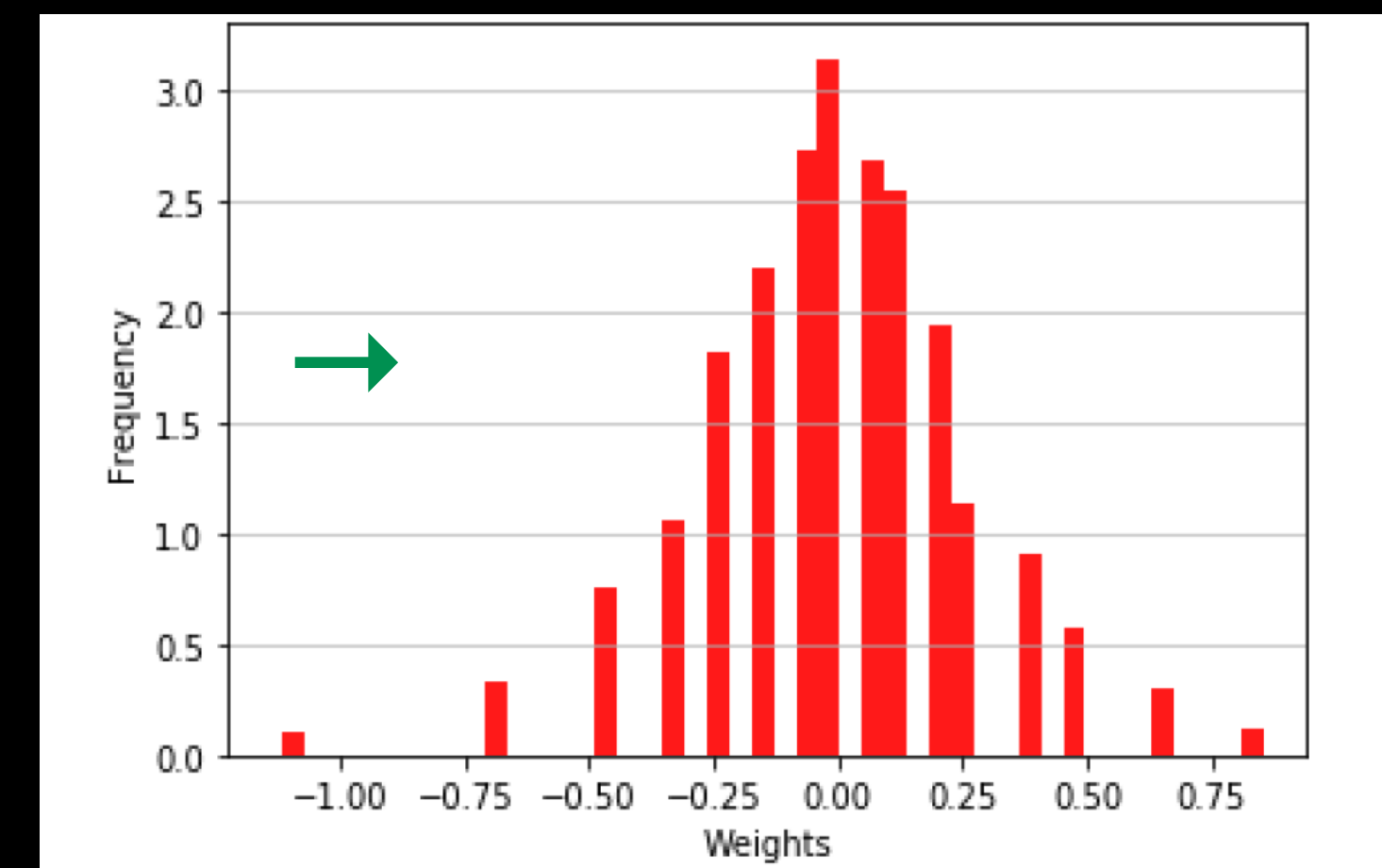
Weights Layer 2



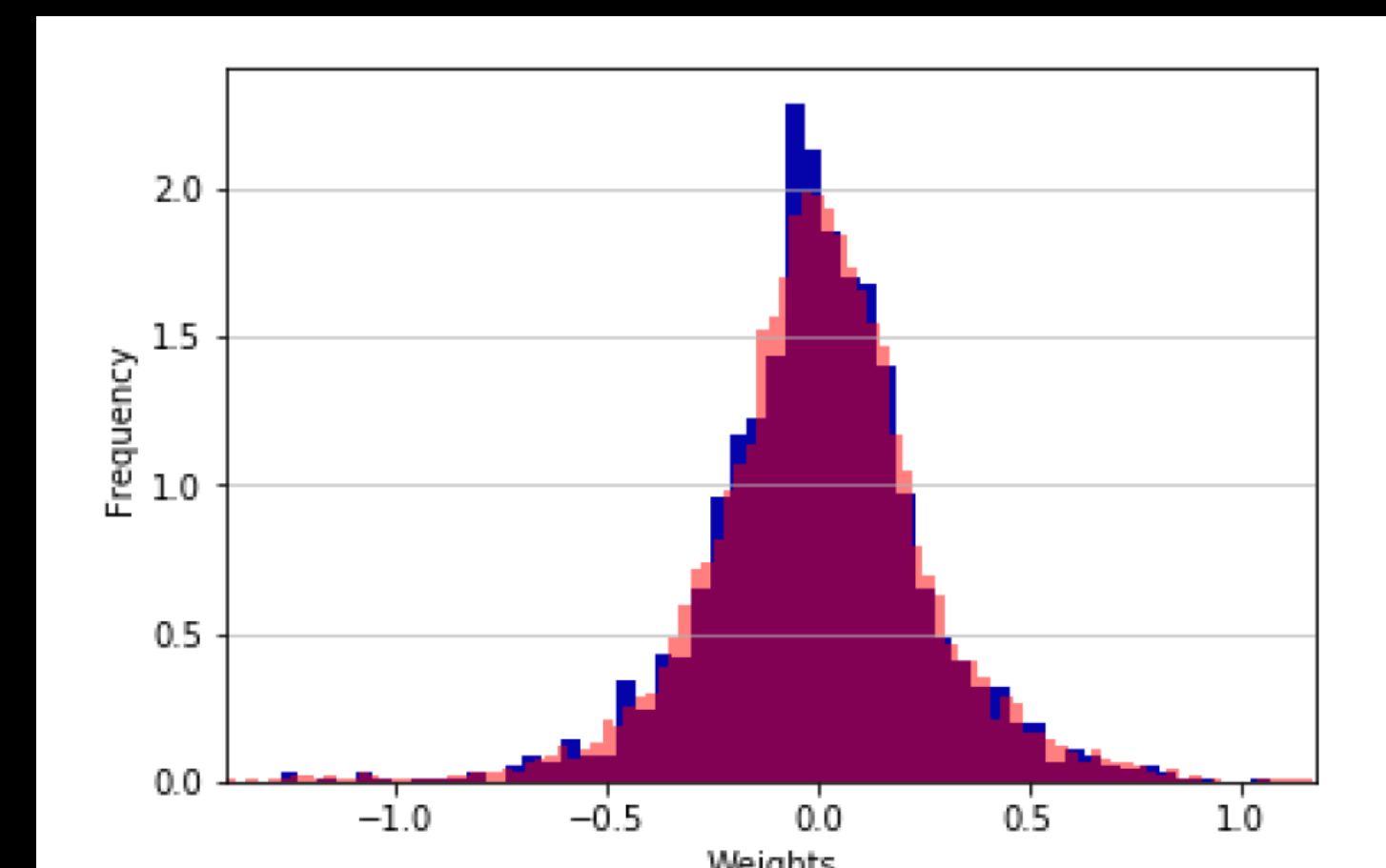
Quantization-aware training



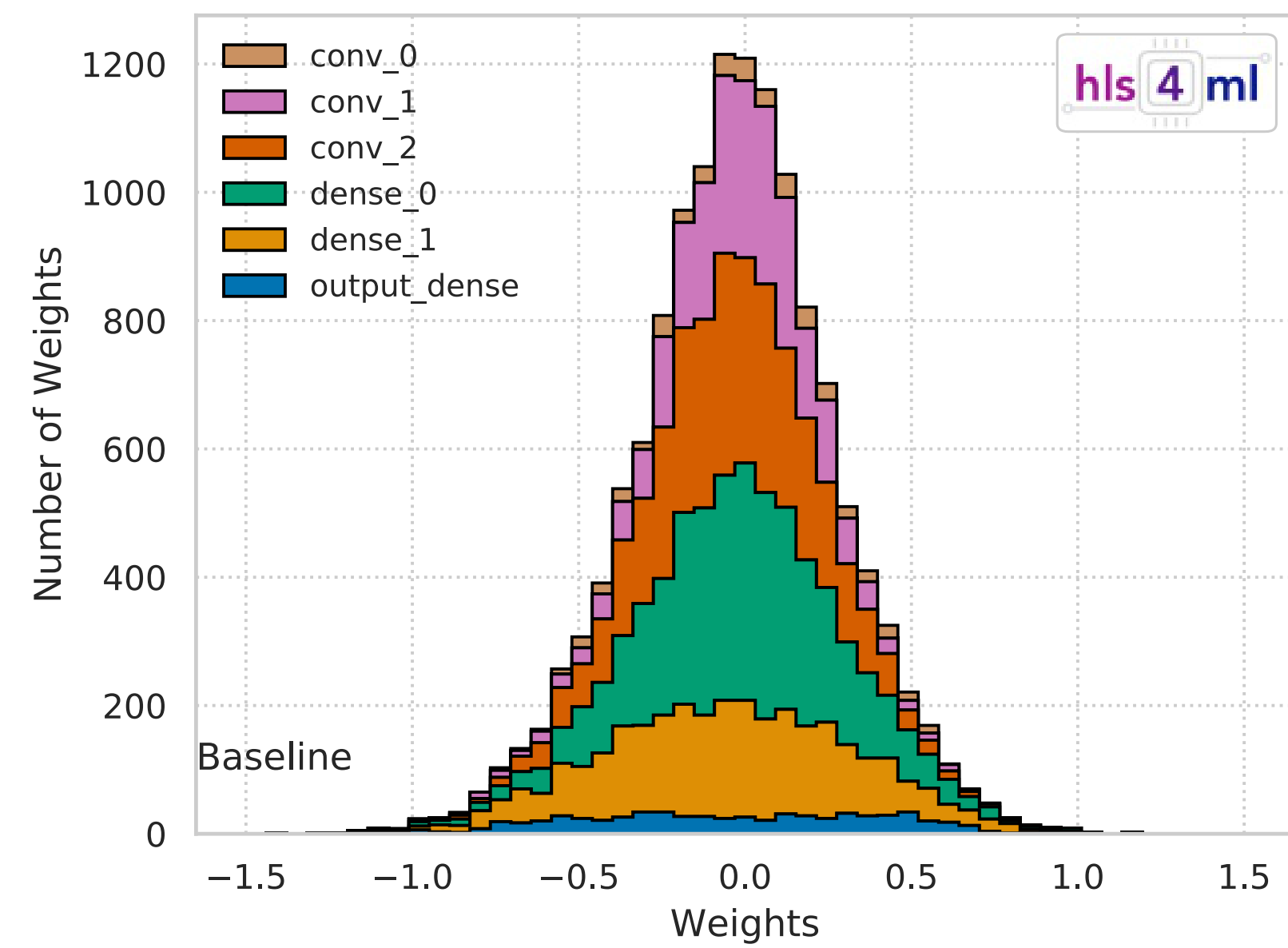
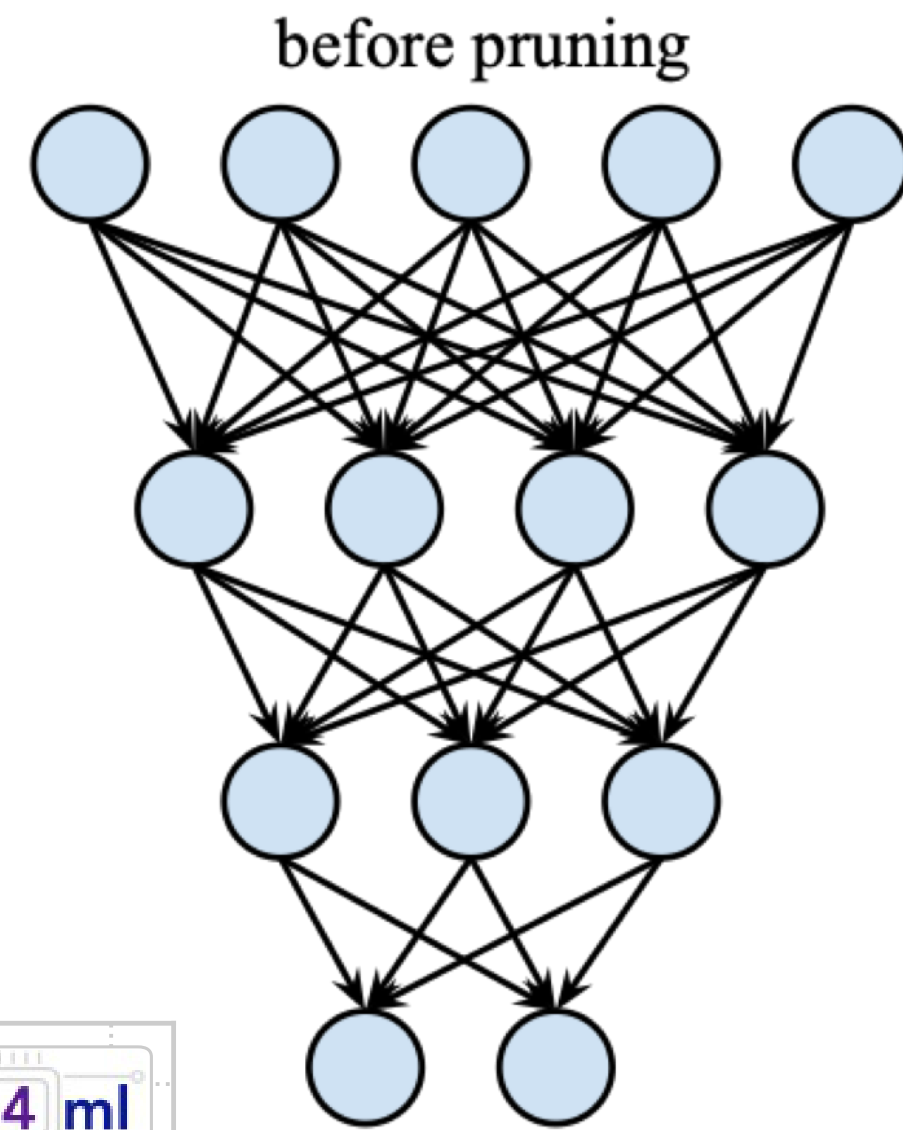
Forward pass →



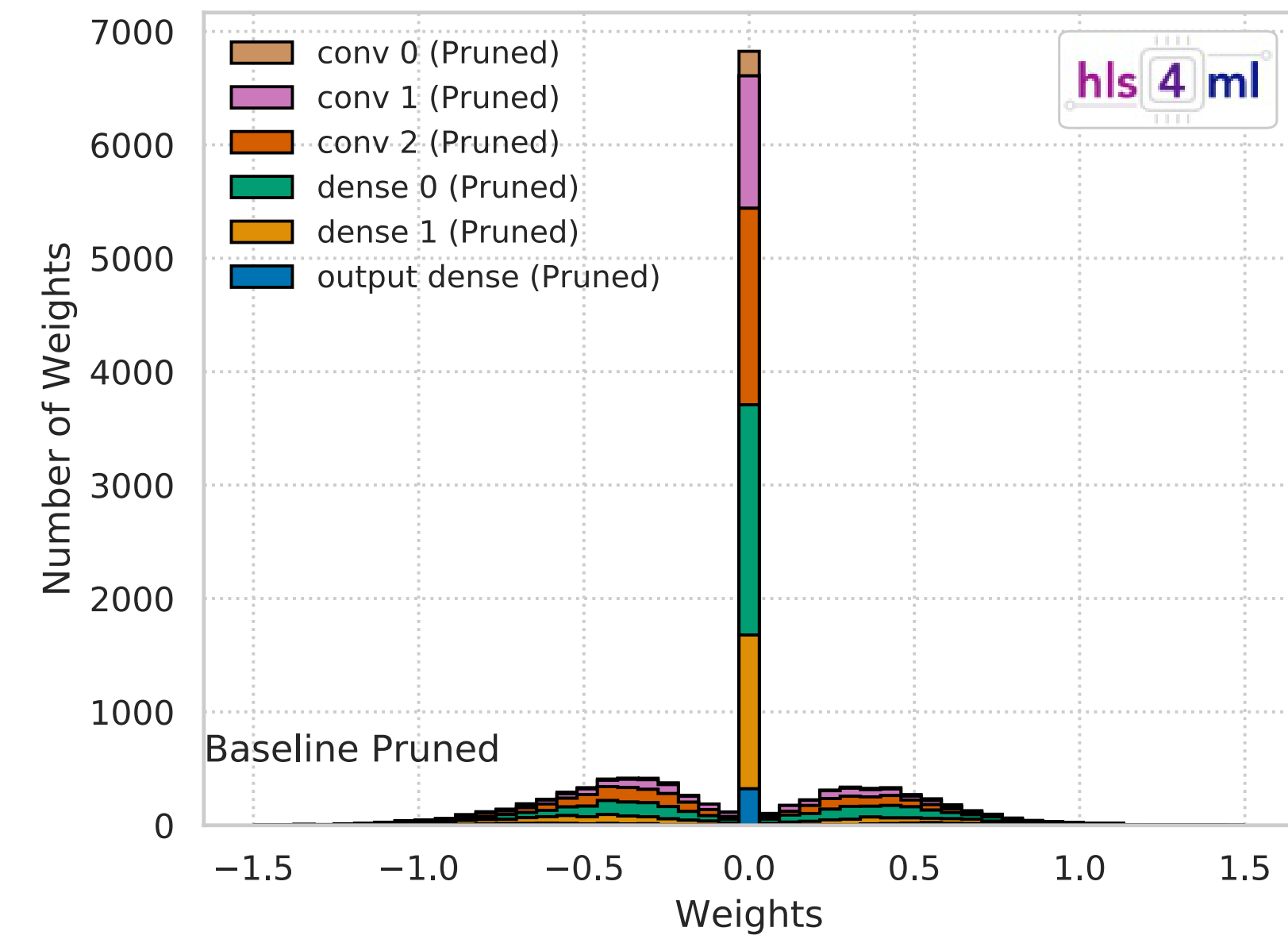
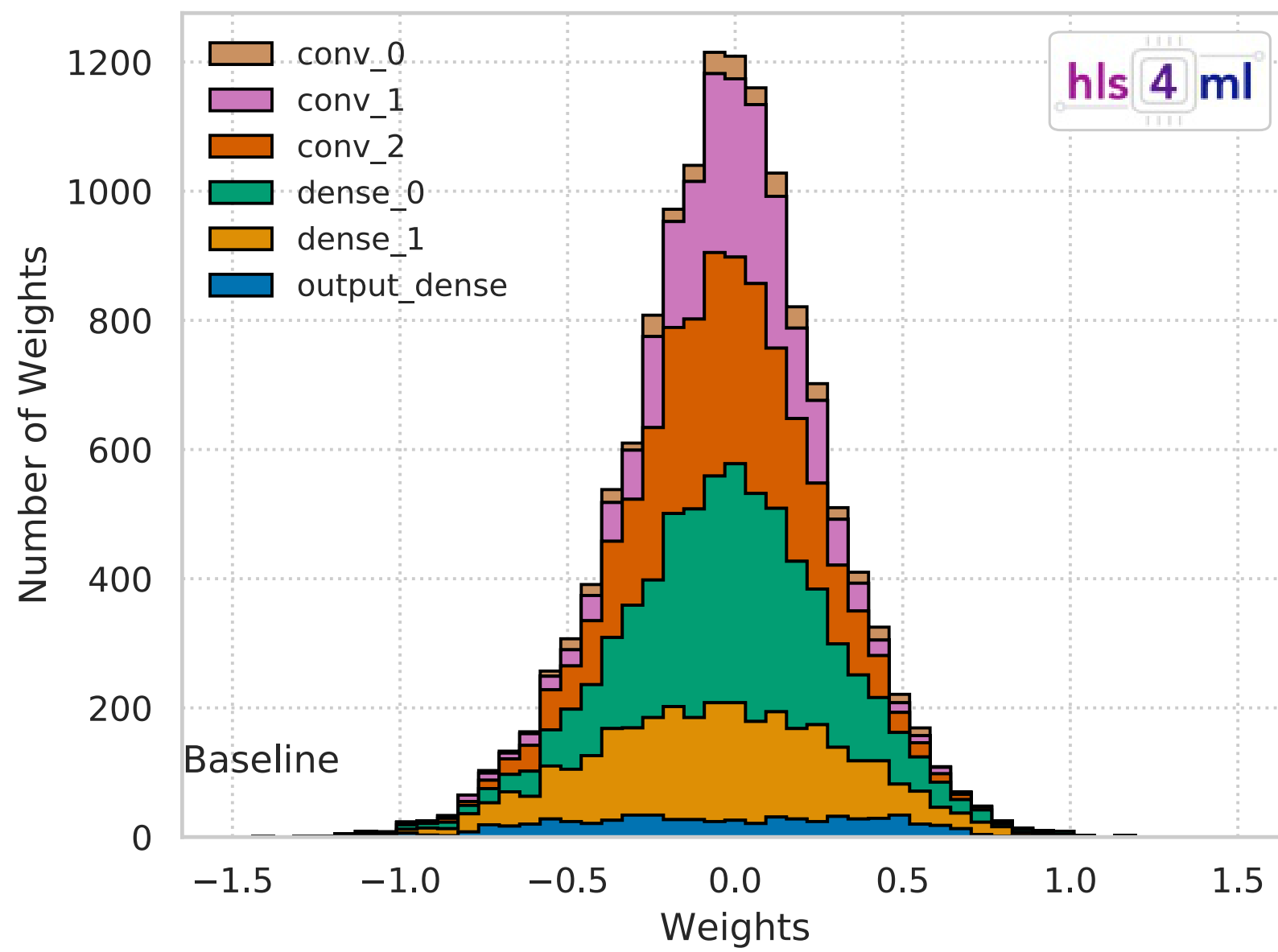
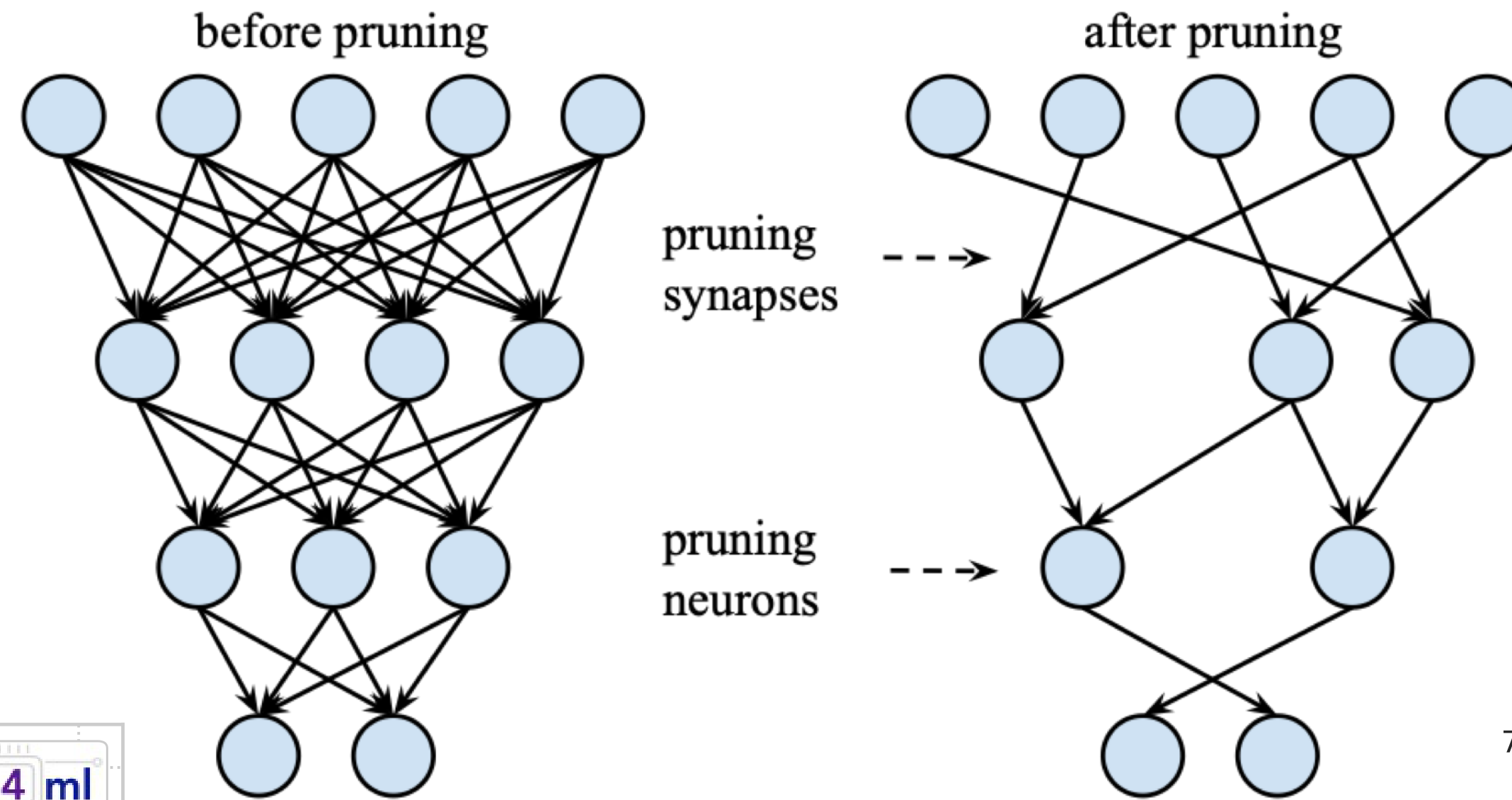
← Back propagation



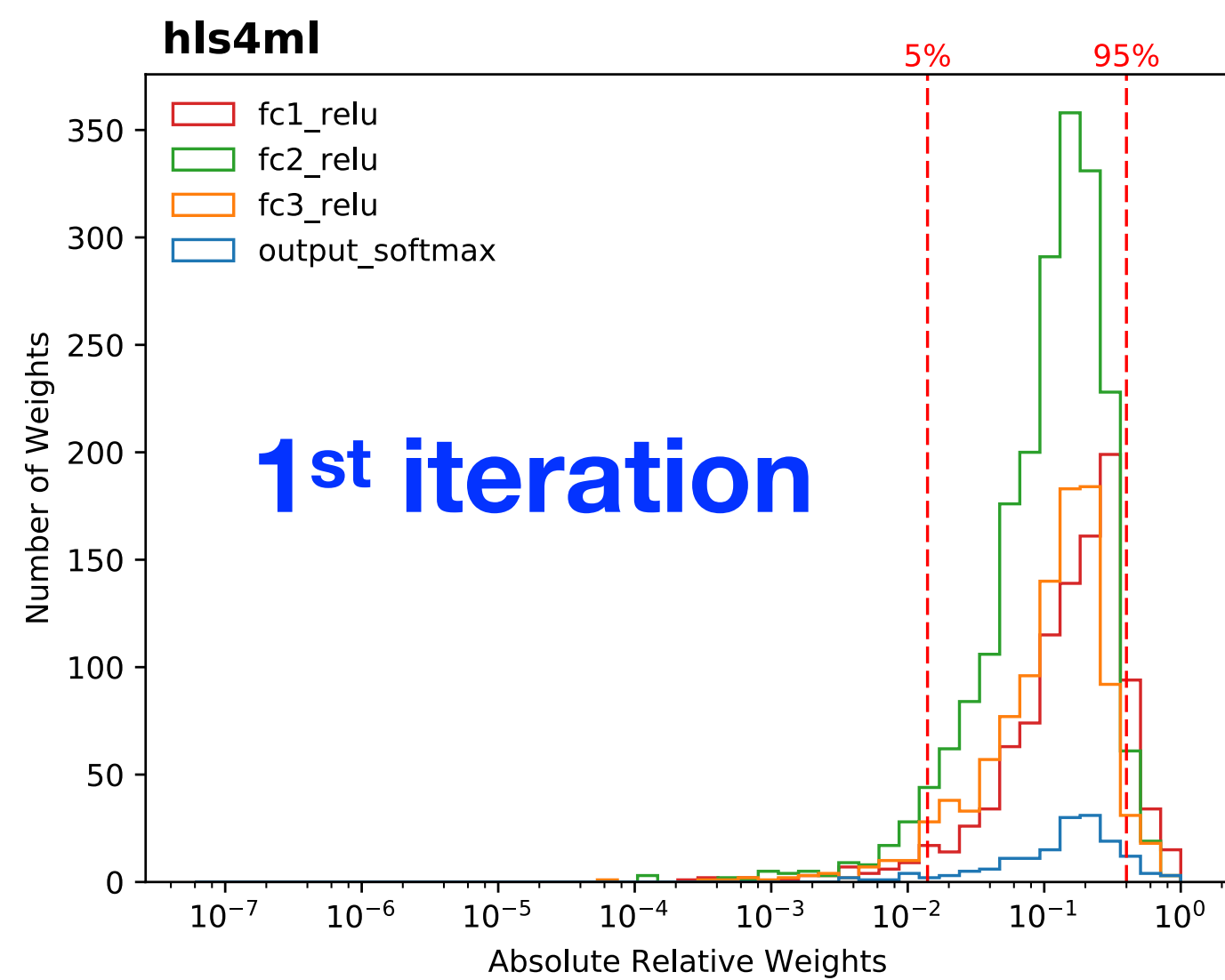
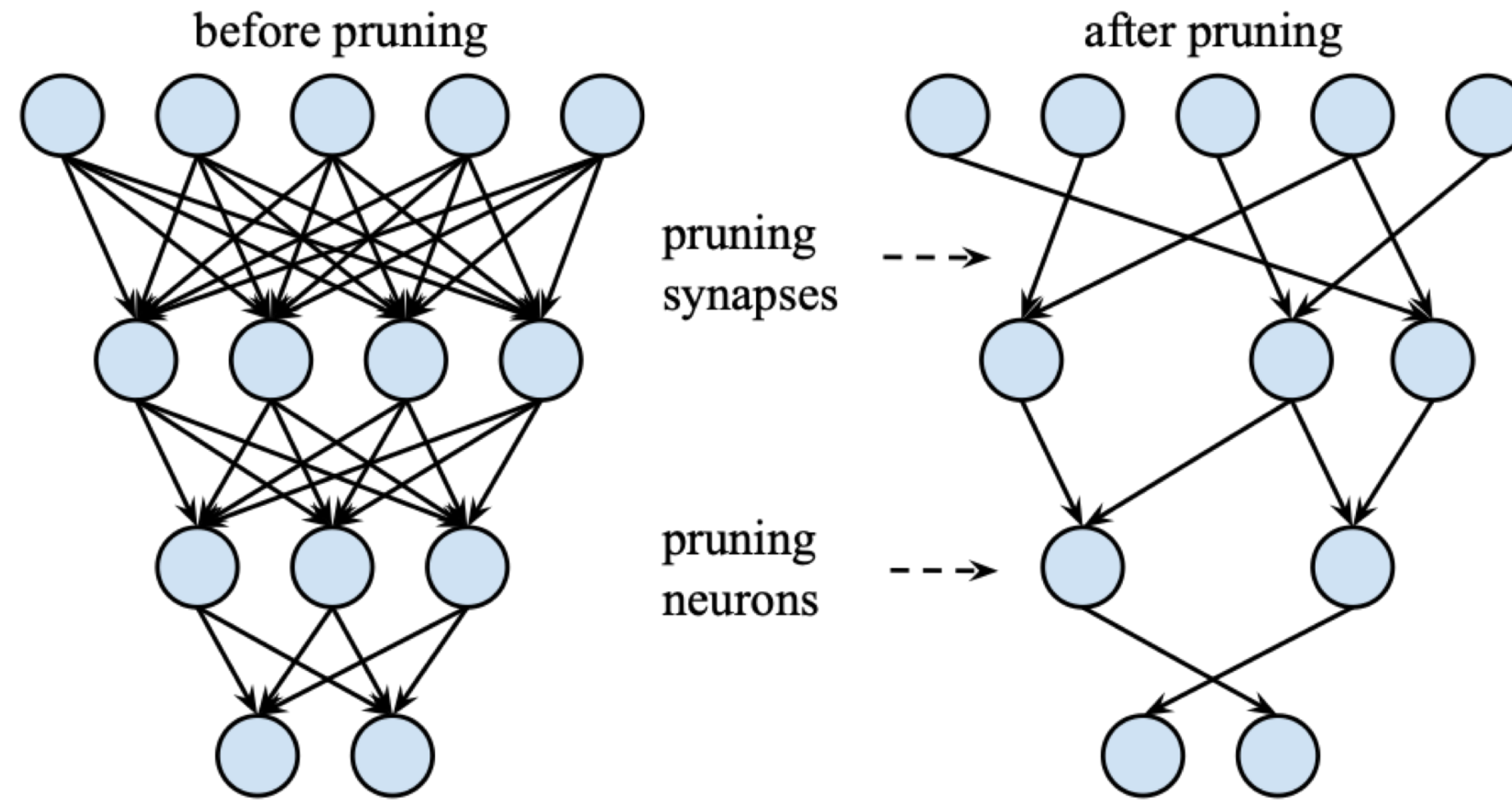
Pruning



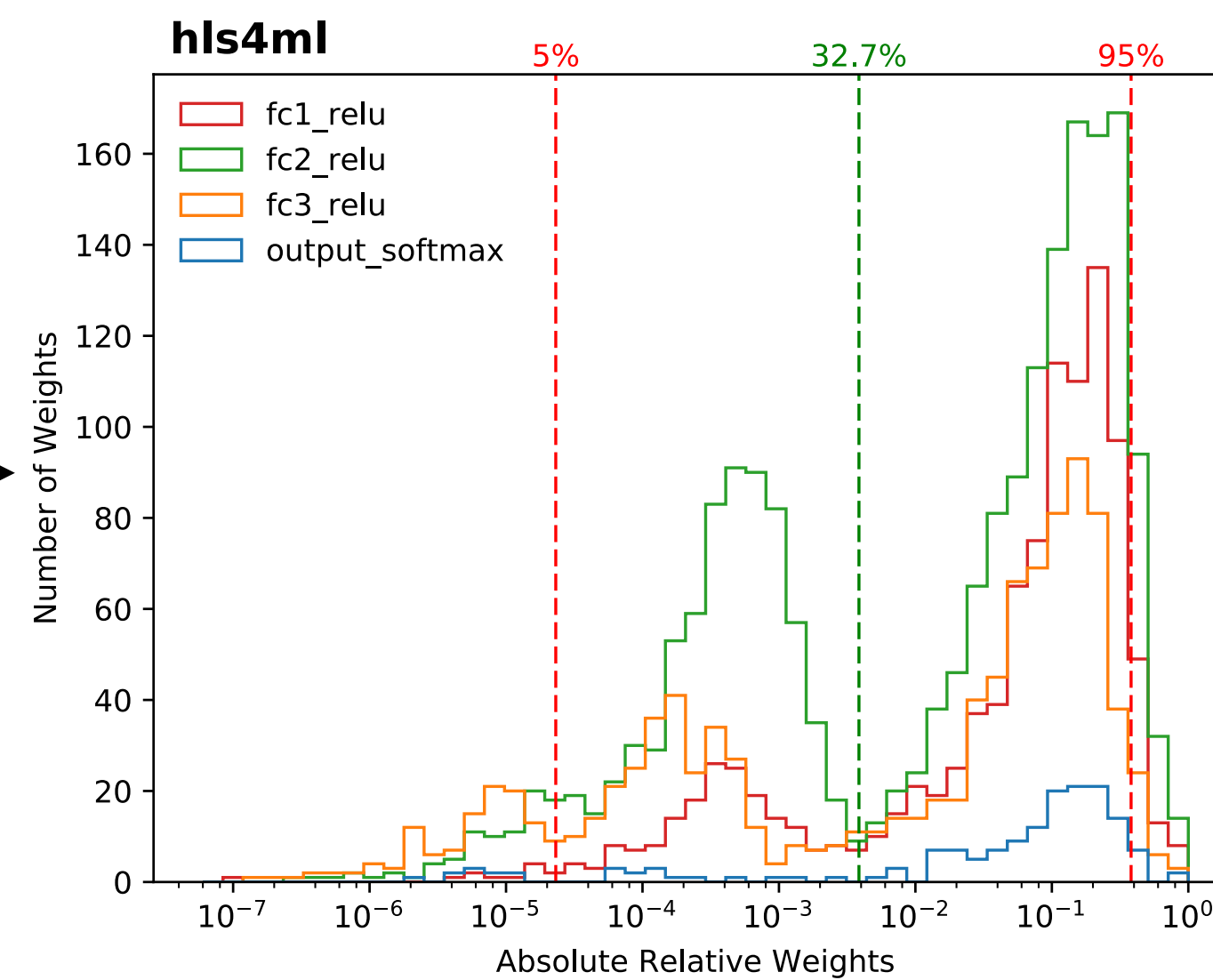
Pruning



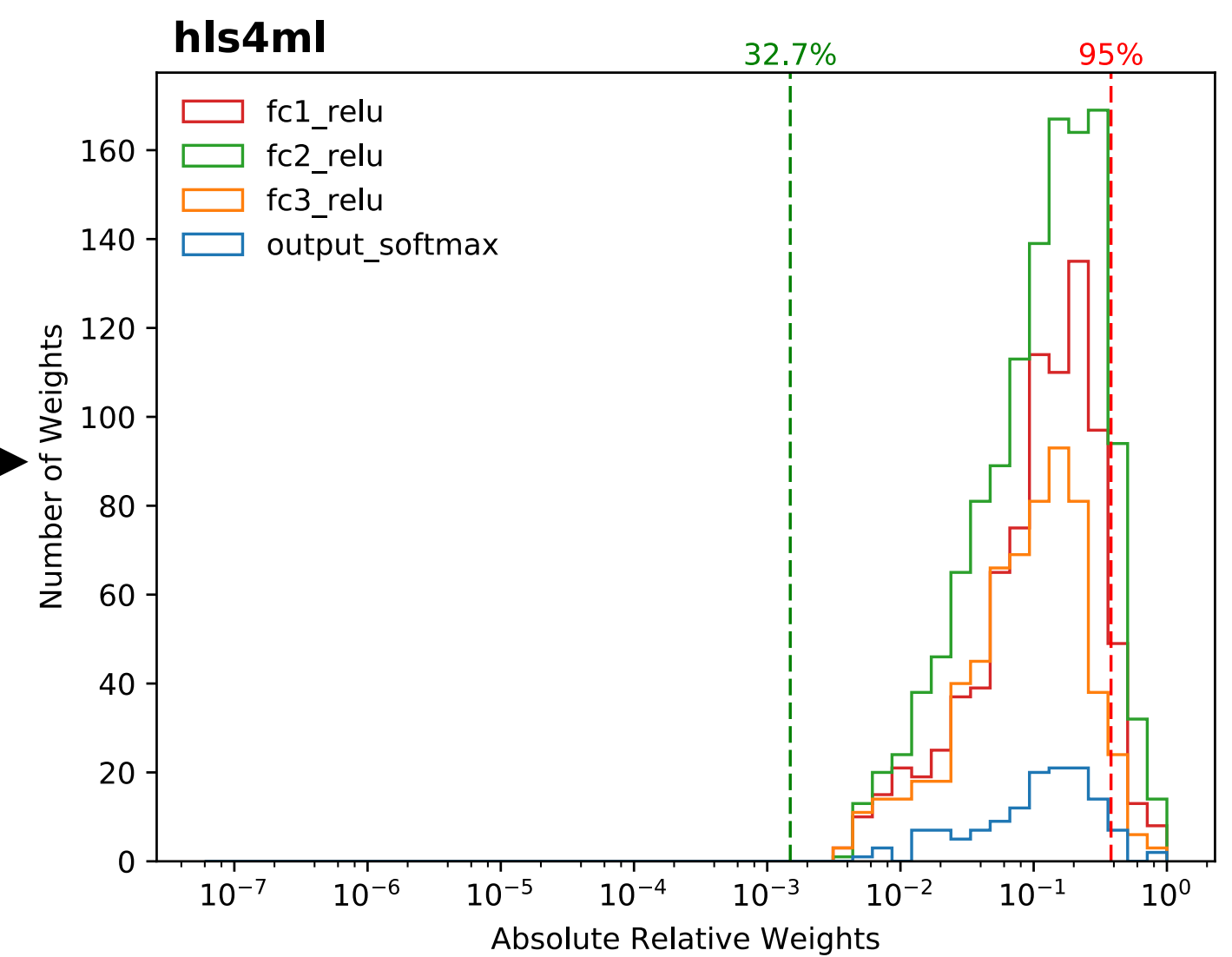
Pruning



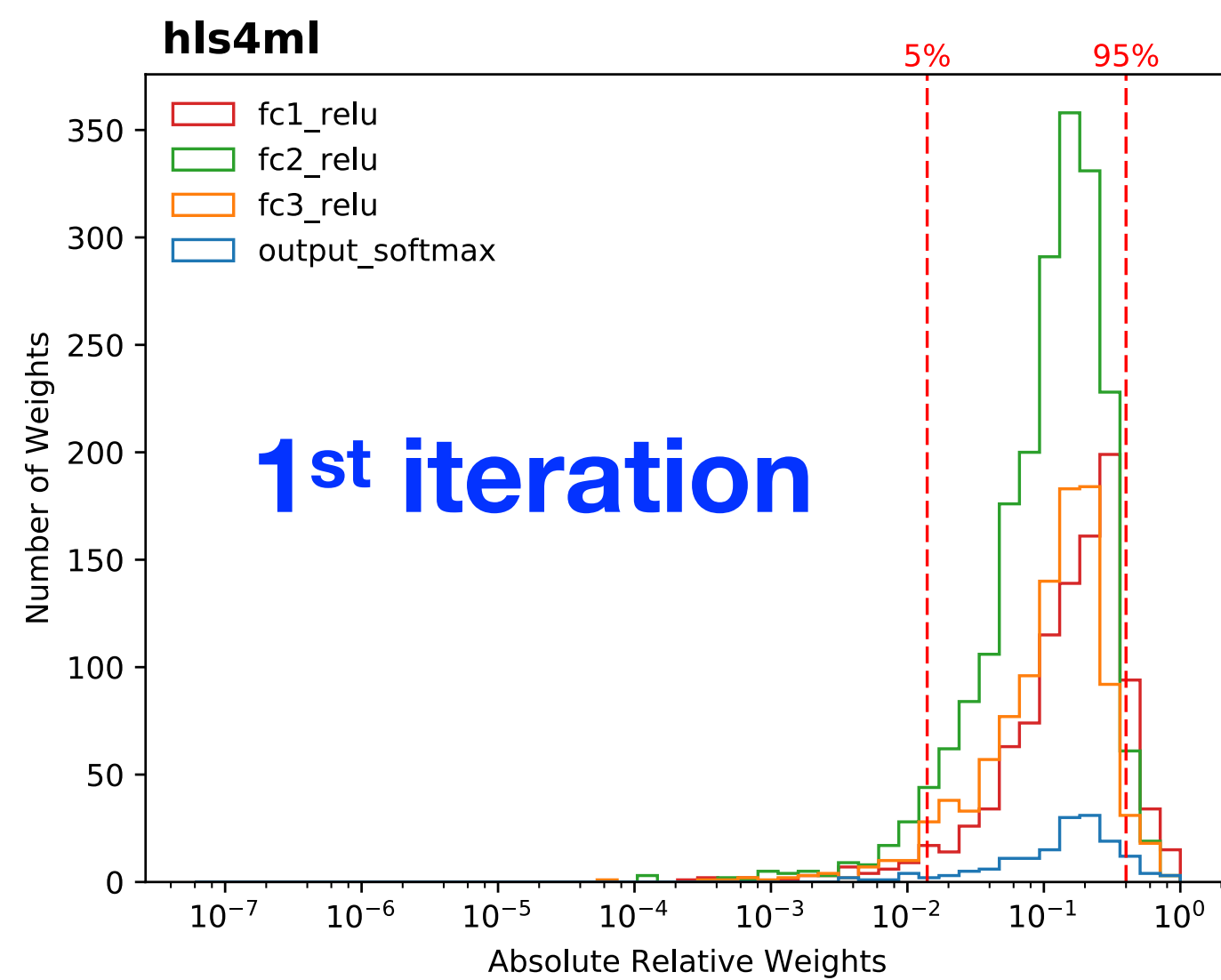
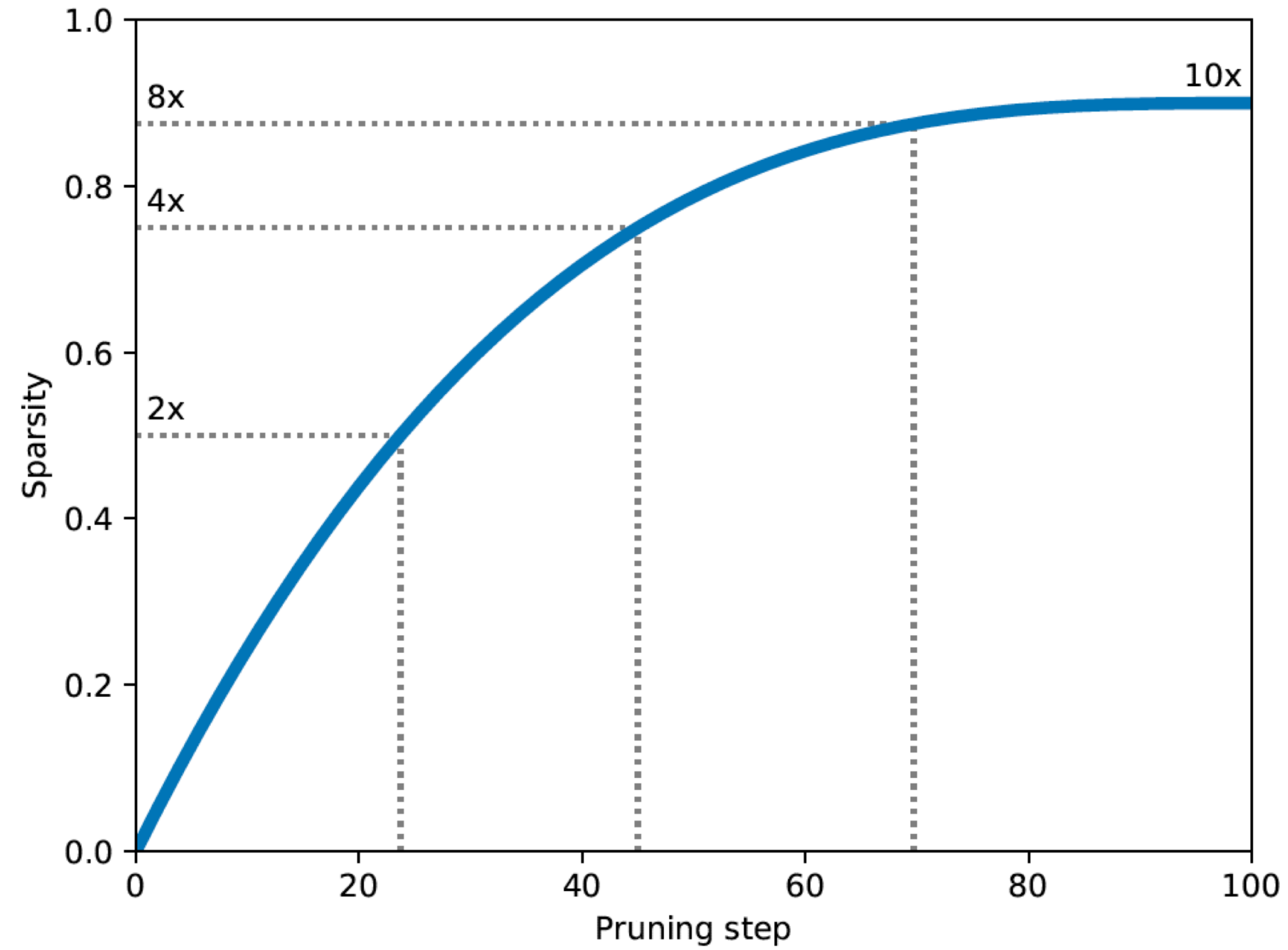
Train with L₁



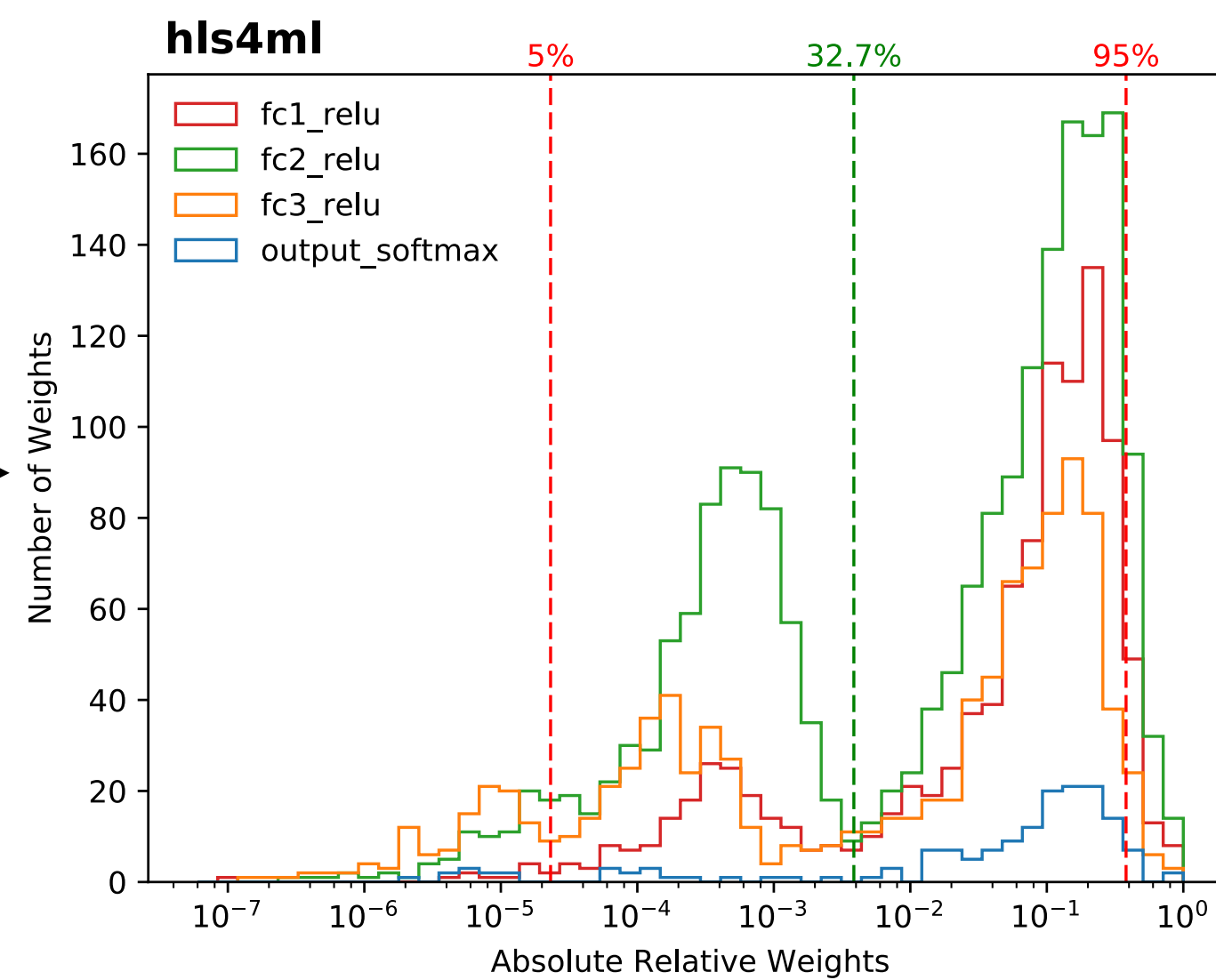
Prune



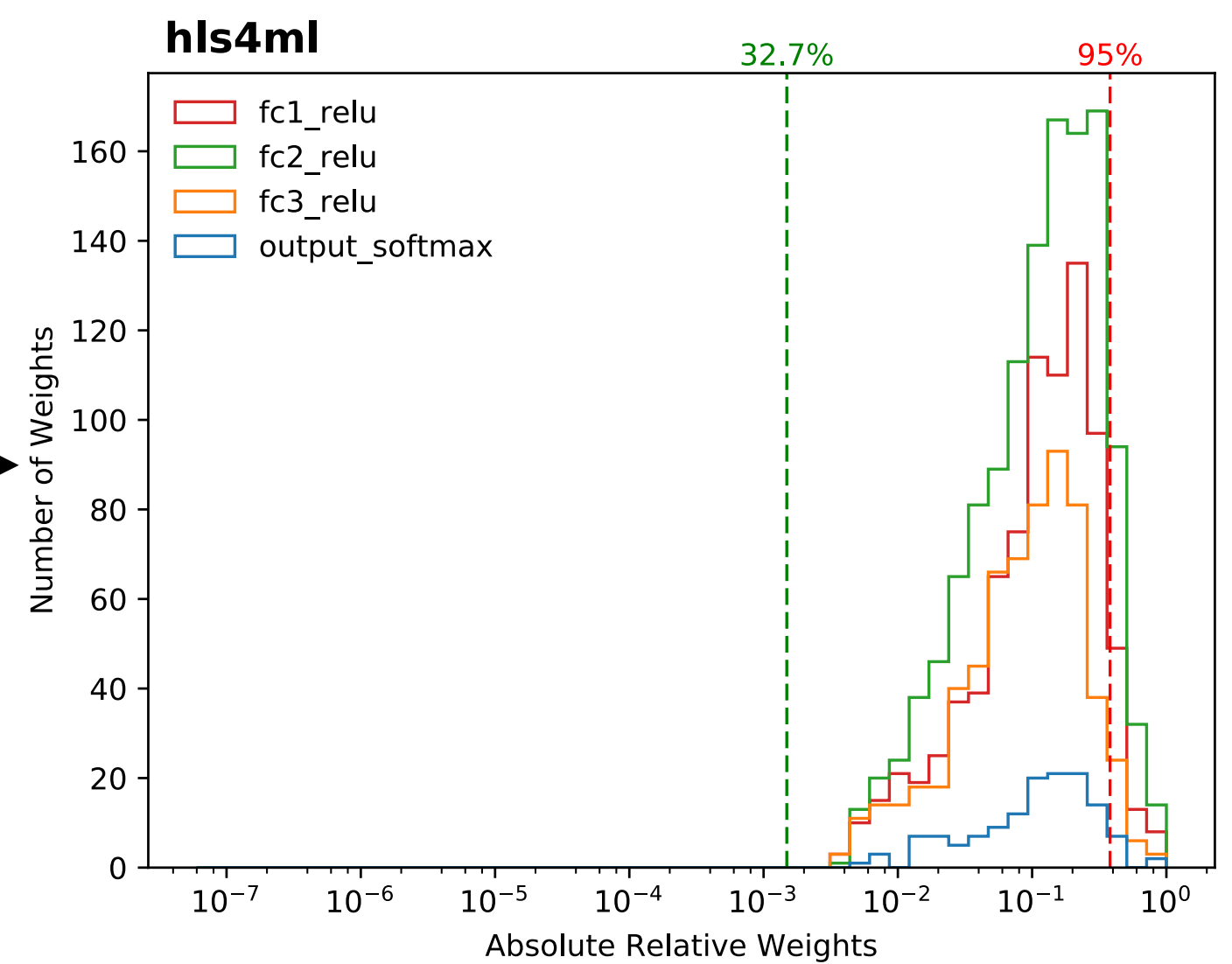
Pruning



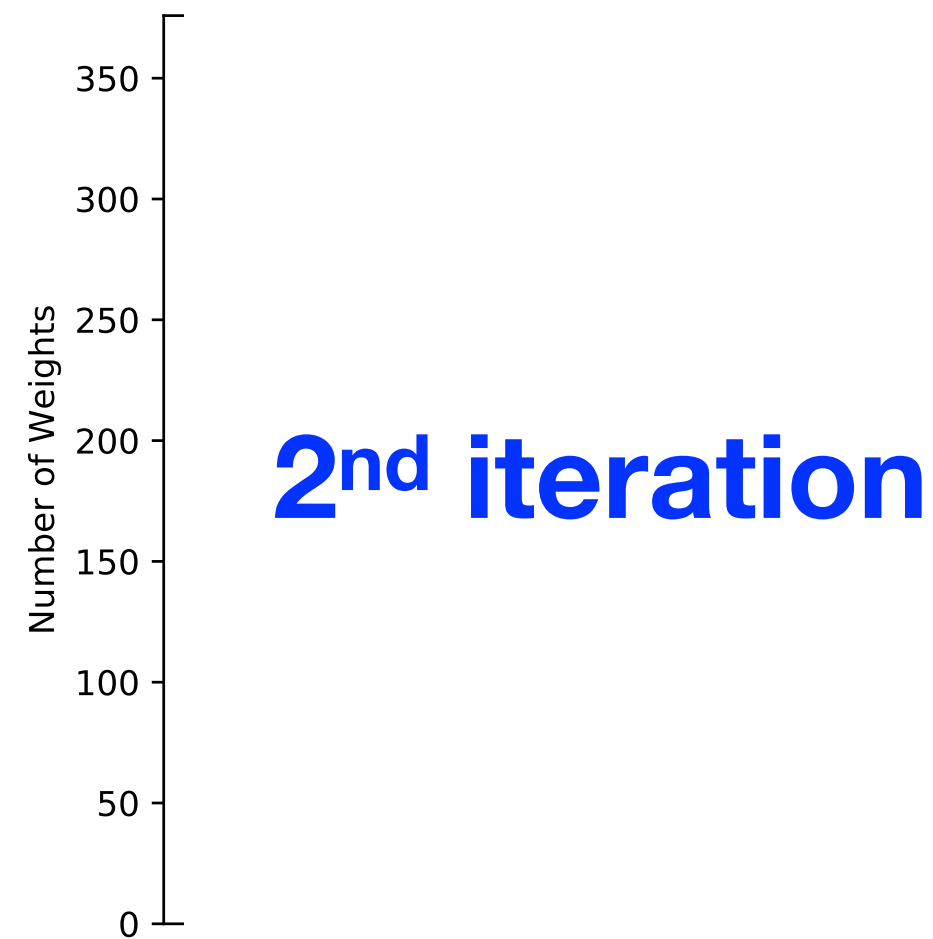
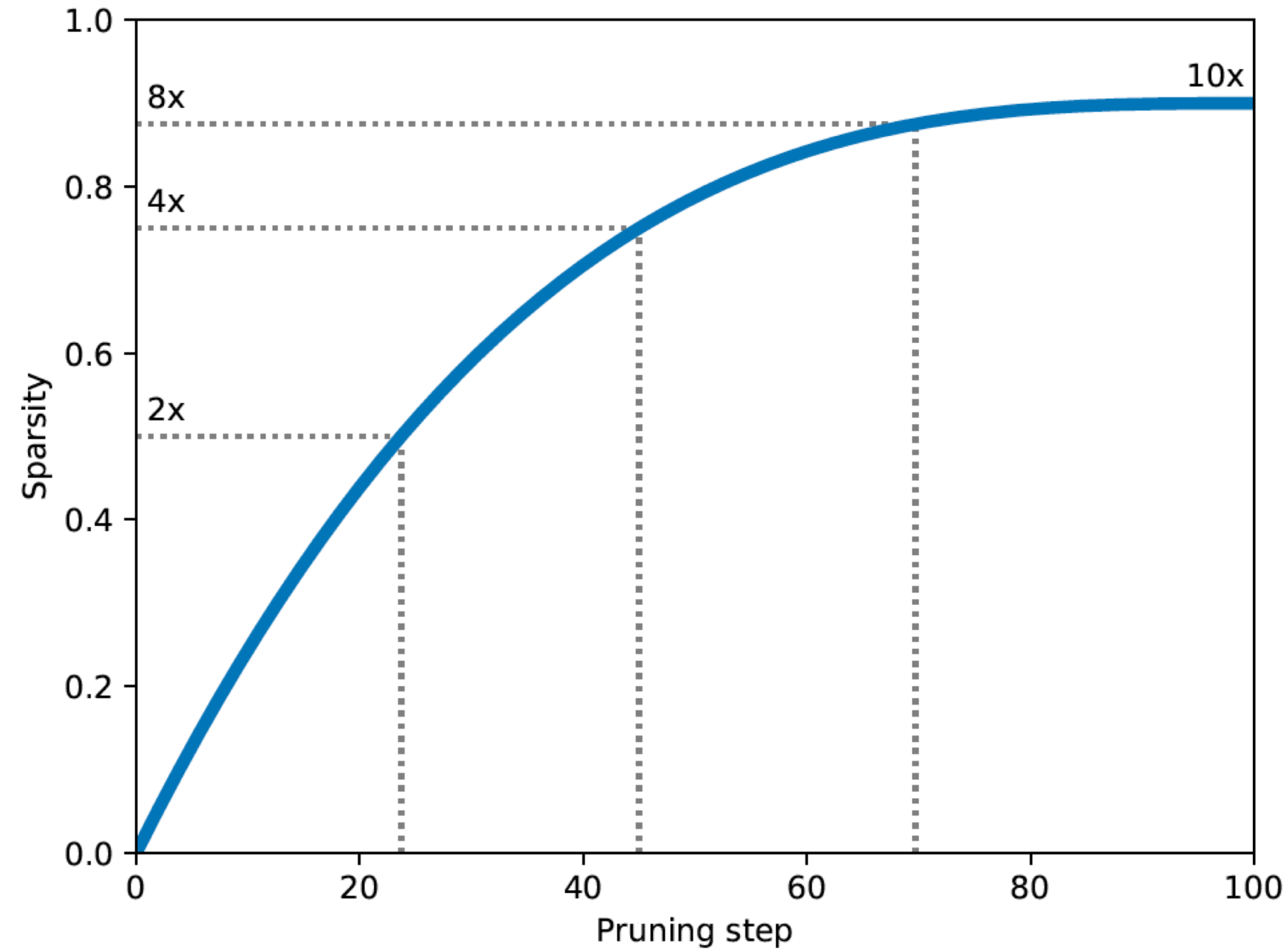
Train with L₁



Prune

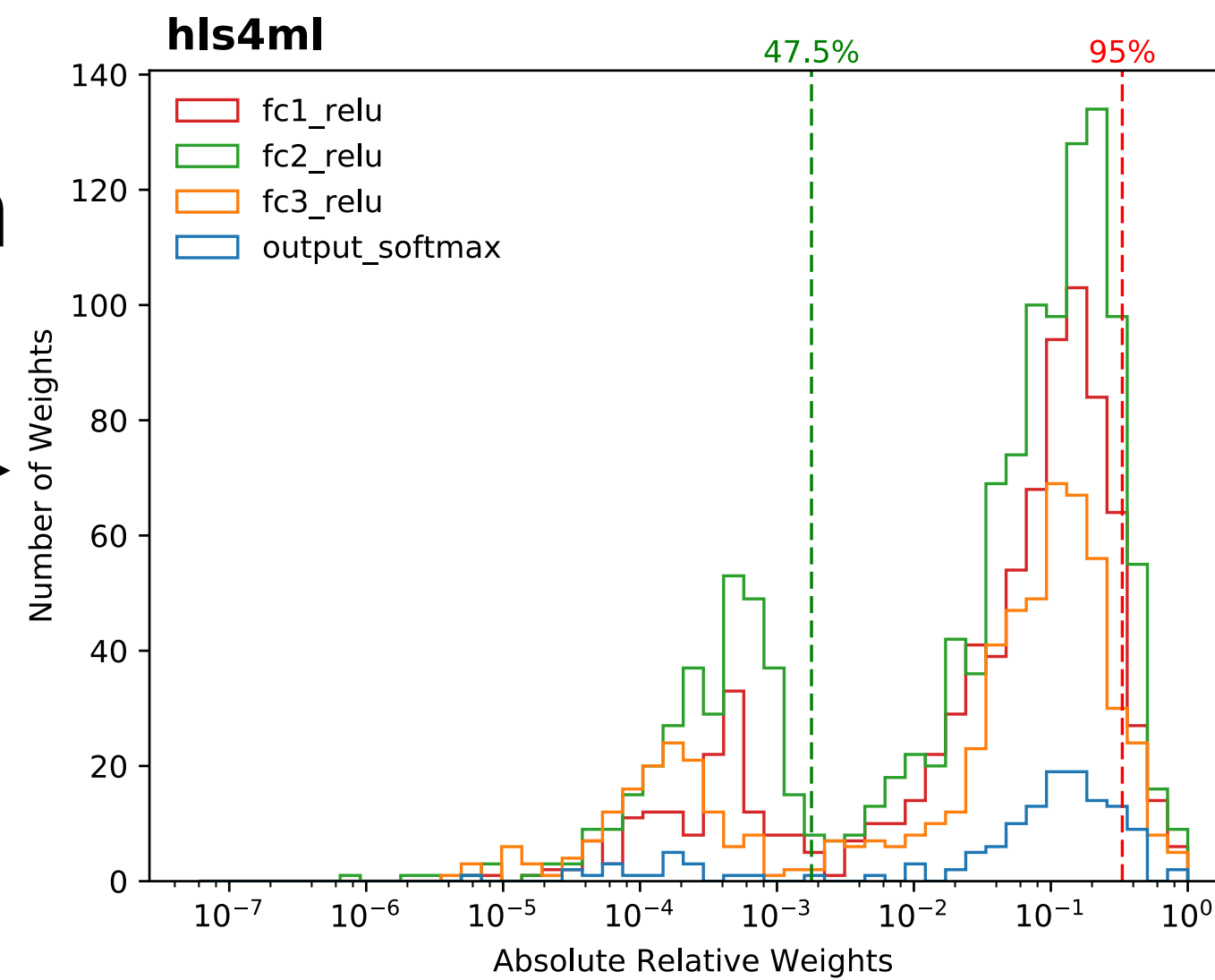


Pruning

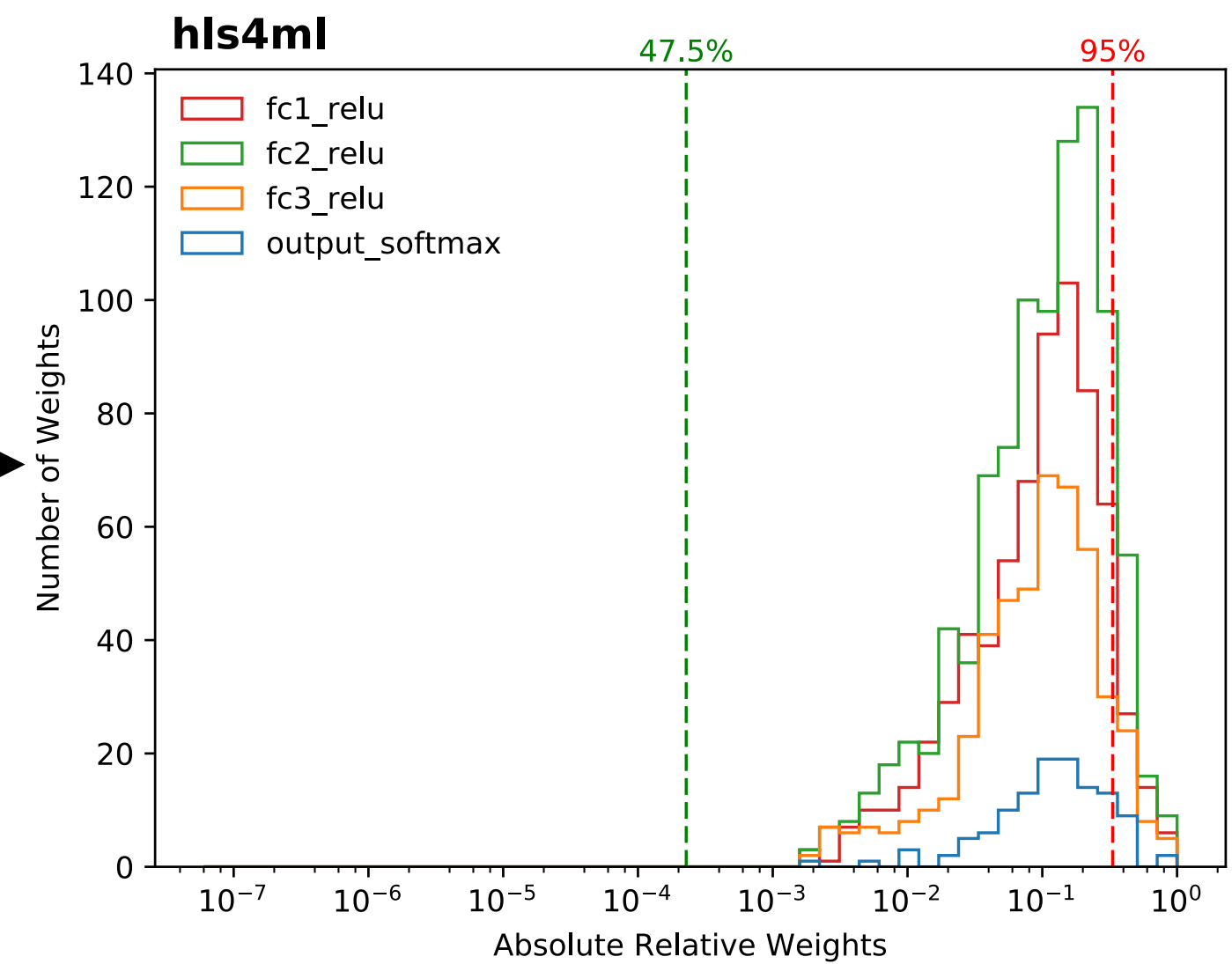


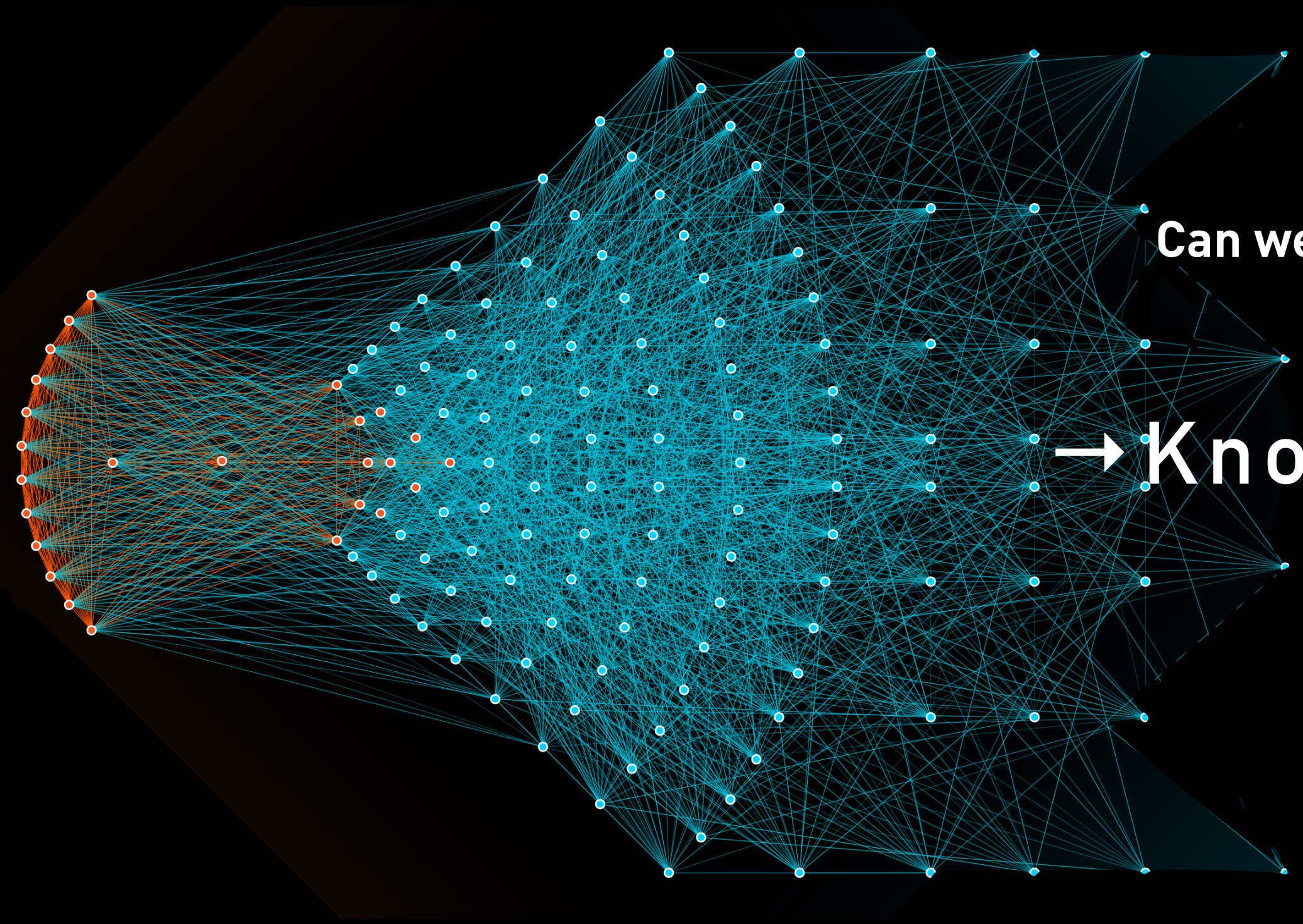
2nd iteration

Retrain
with L₁



Prune

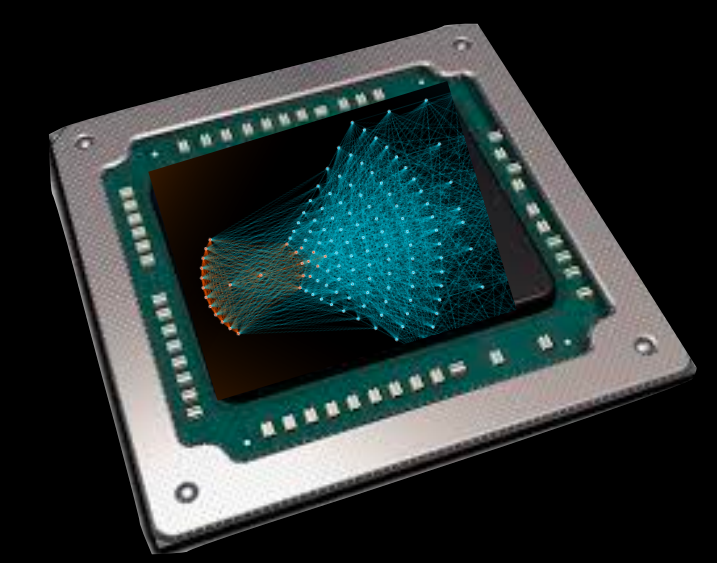




Train

Can we have the best of both worlds?

→ Knowledge Distillation



Inference

See talk by Patrick Odagiu (IPA) tomorrow!

FPGA trigger code

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_unsigned.all;
use ieee.std_logic_arith.all;

use work.gtl_pkg.all;

entity invariant_mass is
  generic (
    >> upper_limit: real := 15.0;
    >> lower_limit: real := 10.0;
    >> pt1_width: positive := 12;
    >> pt2_width: positive := 12;
    >> cosh_cos_width: positive := 28;
    >> INV_MASS_PRECISION : positive := 1;
    >> INV_MASS_COSH_COS_PRECISION : positive := 3
  );
  port(
    >> pt1 : in std_logic_vector(pt1_width-1 downto 0);
    >> pt2 : in std_logic_vector(pt2_width-1 downto 0);
    >> cosh_delta : in std_logic_vector(cosh_cos_width-1 downto 0); -- cosh of eta1 - eta2
    >> cos_dphi : in std_logic_vector(cosh_cos_width-1 downto 0); -- cos of phi1 - phi2
    inv_mass_comp : out std_logic;
    sim_inv_mass_sq_div2 : out std_logic_vector(pt1_width+pt2_width+cosh_cos_width-1 downto 0)
  );
end invariant_mass;

architecture rtl of invariant_mass is

  constant INV_MASS_VECTOR_WIDTH : positive := pt1_width+pt2_width+cosh_cos_width;
  constant INV_MASS_PRECISION_FACTOR : real := real(10**INV_MASS_PRECISION);.pkg.
  constant FACTOR_4_VECTOR : std_logic_vector((INV_MASS_COSH_COS_PRECISION+1)*4-1 downto 0) := conv_std_logic_vector(10**(INV_MASS_COSH_COS_PRECISION+1),(INV_MAS

  signal inv_mass_sq_div2 : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);
  signal upper_limit_vector : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);
  signal lower_limit_vector : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);

begin

  -- Converting the boundary value for the comparison
  upper_limit_vector <= conv_std_logic_vector((integer(upper_limit*INV_MASS_PRECISION_FACTOR)),INV_MASS_VECTOR_WIDTH-FACTOR_4_VECTOR'length)*FACTOR_4_VECTOR;
  lower_limit_vector <= conv_std_logic_vector((integer(lower_limit*INV_MASS_PRECISION_FACTOR)),INV_MASS_VECTOR_WIDTH-FACTOR_4_VECTOR'length)*FACTOR_4_VECTOR;

  -- Calculation of invariant mass with the formula: M**2/2 = pt1*pt2 * (cosh(eta1 - eta2) - cos(phi1 - phi2))
  inv_mass_sq_div2 <= pt1 * pt2 * (cosh_delta - cos_dphi);
  sim_inv_mass_sq_div2 <= inv_mass_sq_div2;

  -- Comparison with boundary values
  inv_mass_comp <= '1' when (inv_mass_sq_div2 >= lower_limit_vector and inv_mass_sq_div2 <= upper_limit_vector) else '0';

end architecture rtl;
```


FPGA trigger code

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_unsigned.all;
use ieee.std_logic_arith.all;

use work.gtl_pkg.all;

entity invariant_mass is
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    >> upper_limit: real := 15.0;
    >> lower_limit: real := 10.0;
    >> pt1_width: positive := 12;
    >> pt2_width: positive := 12;
    >> cosh_cos_width: positive := 28;
    >> INV_MASS_PRECISION : positive := 1;
    >> INV_MASS_COSH_COS_PRECISION : positive := 3
  );
  port(
    >> pt1 : in std_logic_vector(pt1_width-1 downto 0);
    >> pt2 : in std_logic_vector(pt2_width-1 downto 0);
    >> cosh_delta : in std_logic_vector(cosh_cos_width-1 downto 0); -- cosh of eta1 - eta2
    >> cos_dphi : in std_logic_vector(cosh_cos_width-1 downto 0); -- cos of phi1 - phi2
    inv_mass_comp : out std_logic;
    sim_inv_mass_sq_div2 : out std_logic_vector(pt1_width+pt2_width+cosh_cos_width-1 downto 0)
  );
end invariant_mass;

architecture rtl of invariant_mass is

  constant INV_MASS_VECTOR_WIDTH : positive := pt1_width+pt2_width+cosh_cos_width;
  constant INV_MASS_PRECISION_FACTOR : real := real(10**INV_MASS_PRECISION); .pkg.
  constant FACTOR_4_VECTOR : std_logic_vector((INV_MASS_COSH_COS_PRECISION+1)*4-1 downto 0) := conv_std_logic_vector(10**(INV_MASS_COSH_COS_PRECISION+1),(INV_MAS

  signal inv_mass_sq_div2 : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);
  signal upper_limit_vector : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);
  signal lower_limit_vector : std_logic_vector(INV_MASS_VECTOR_WIDTH-1 downto 0);

begin

  -- Converting the boundary value for the comparison
  upper_limit_vector <= conv_std_logic_vector((integer(upper_limit*INV_MASS_PRECISION_FACTOR)),INV_MASS_VECTOR_WIDTH-FACTOR_4_VECTOR'length)*FACTOR_4_VECTOR;
  lower_limit_vector <= conv_std_logic_vector((integer(lower_limit*INV_MASS_PRECISION_FACTOR)),INV_MASS_VECTOR_WIDTH-FACTOR_4_VECTOR'length)*FACTOR_4_VECTOR;

  -- Calculation of invariant mass with the formula: M**2/2 = pt1*pt2 * (cosh(eta1 - eta2) - cos(phi1 - phi2))
  inv_mass_sq_div2 <= pt1 * pt2 * (cosh_delta - cos_dphi);
  sim_inv_mass_sq_div2 <= inv_mass_sq_div2;

  -- Comparison with boundary values
  inv_mass_comp <= '1' when (inv_mass_sq_div2 >= lower_limit_vector and inv_mass_sq_div2 <= upper_limit_vector) else '0';

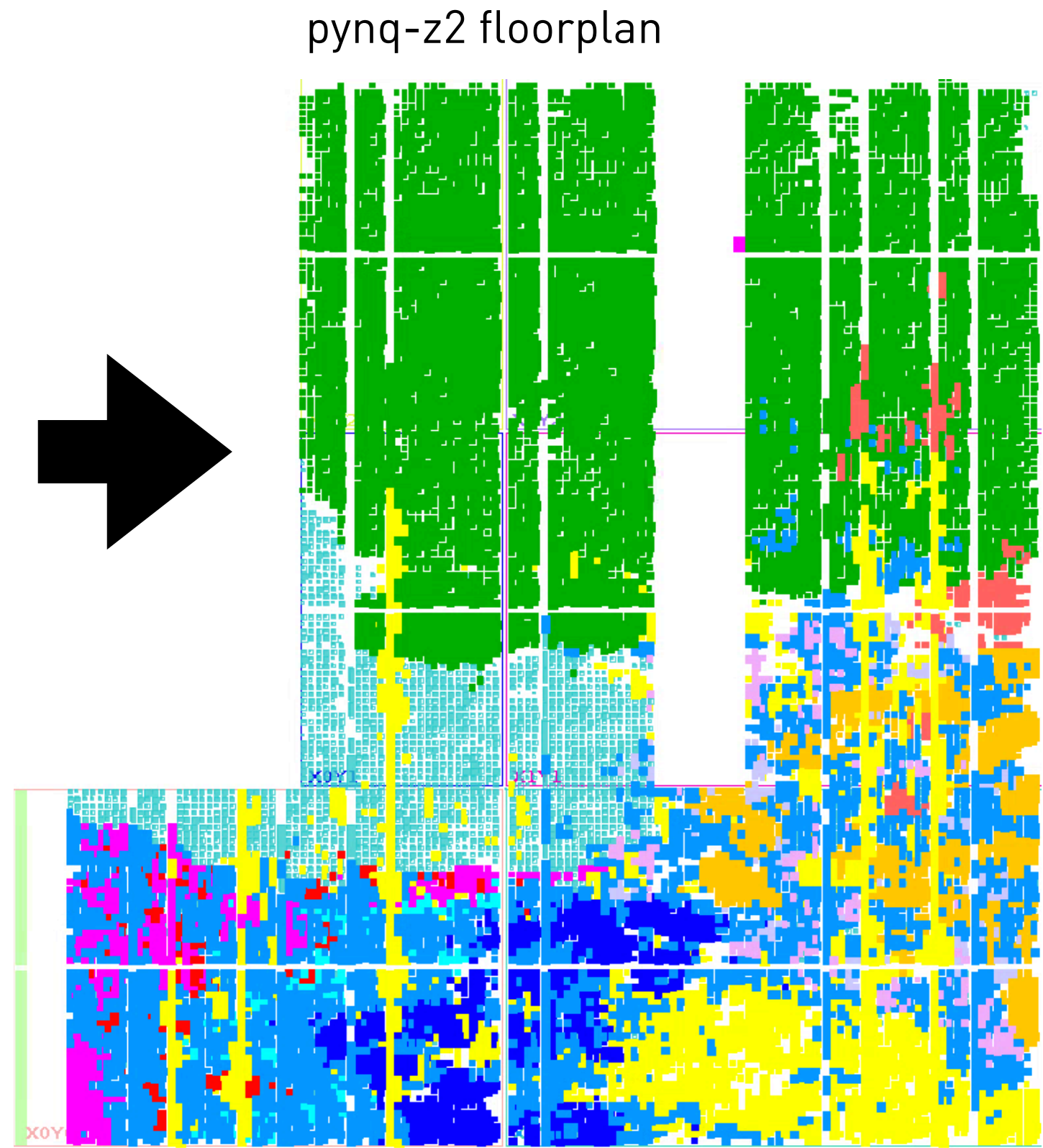
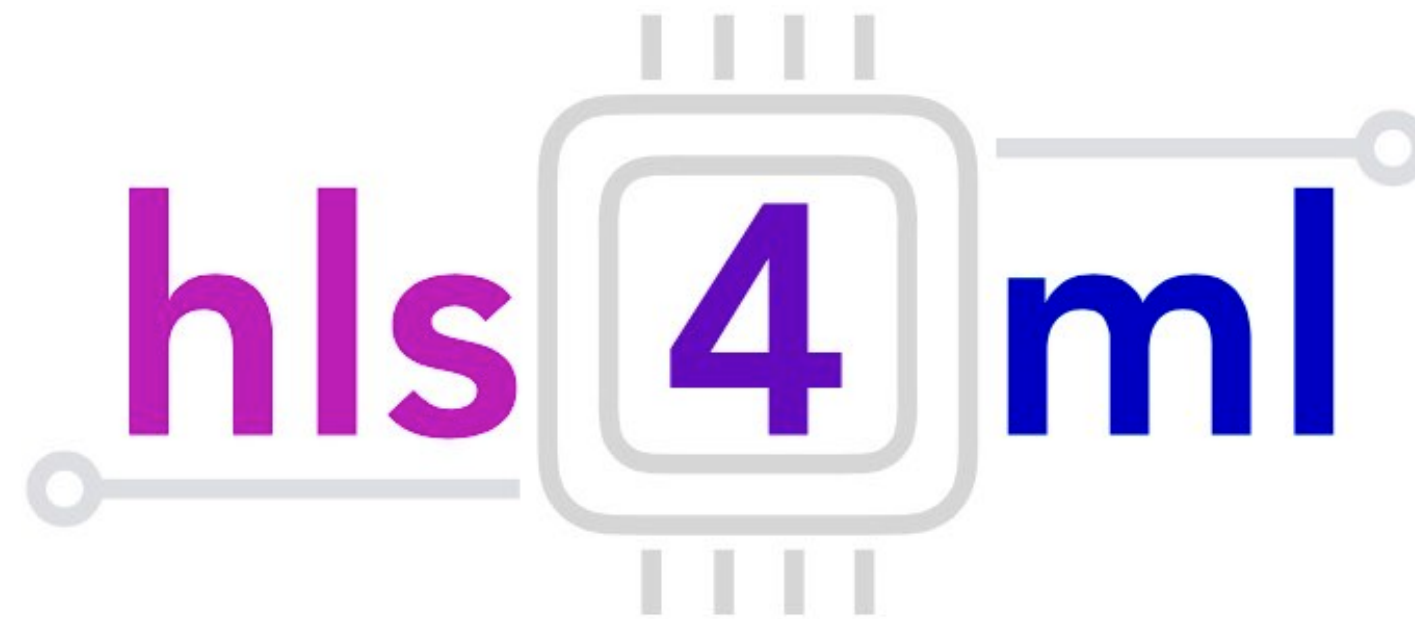
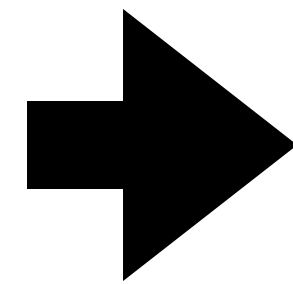
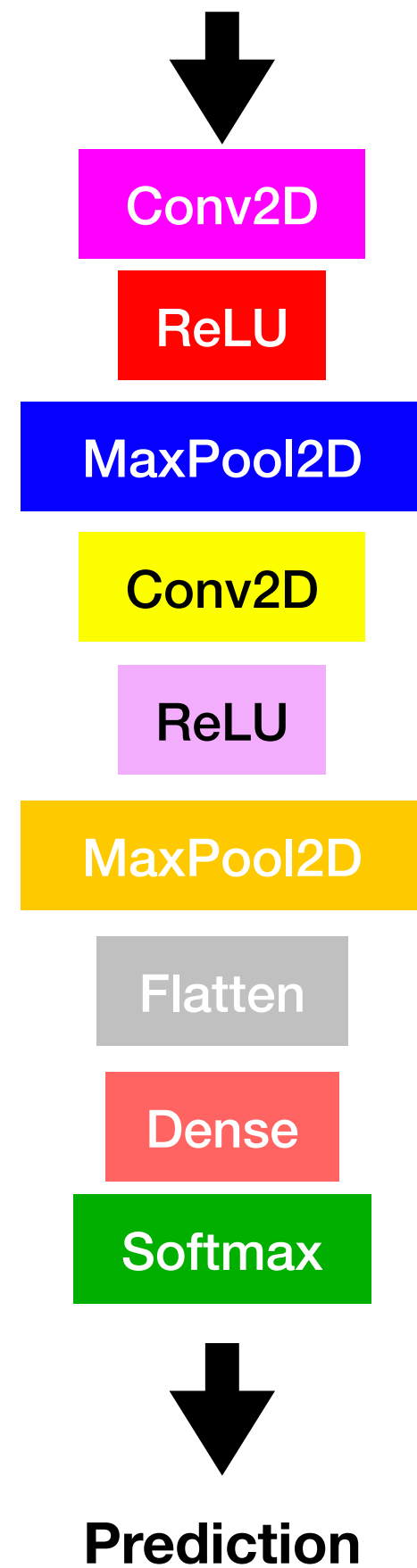
end architecture rtl;
```

$$\mathbf{x}_n = g_n(\mathbf{W}_{n,n-1}\mathbf{x}_{n-1} + \mathbf{b}_n)$$

Generic implementations for
DNN inference?

From Python code..... to hardware blocks that can do inference in nanoseconds!

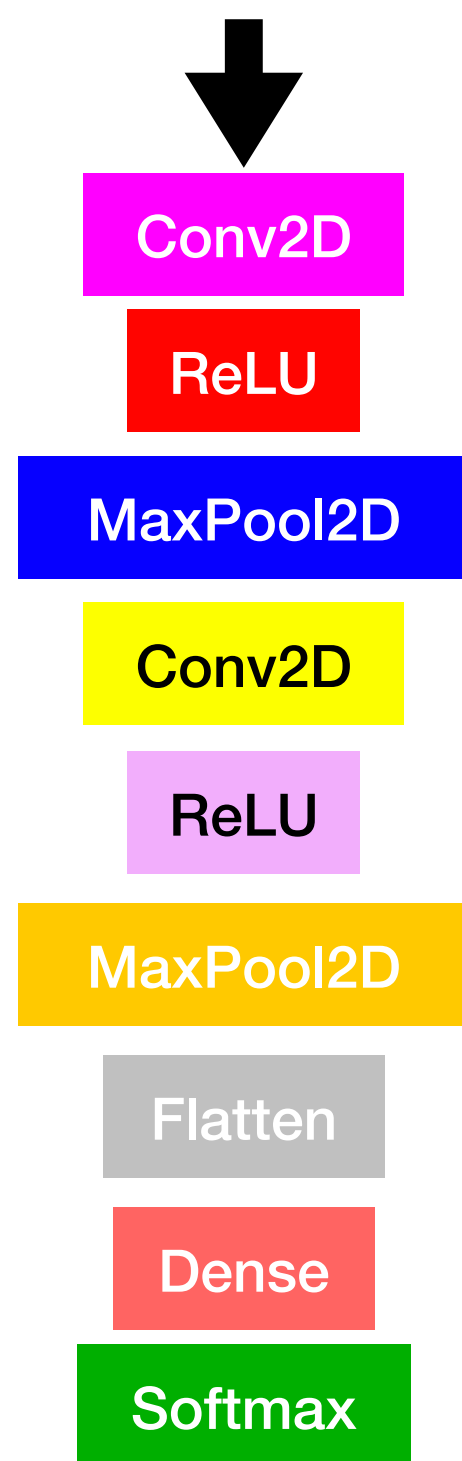
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9	9	9	9	9	9	9	9



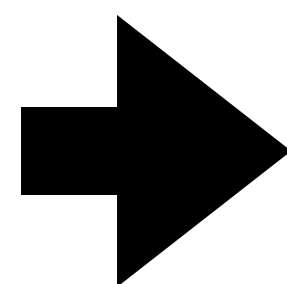
***Our work here at IPA!
P. Odagiu, C. Sun, A. Oliver, T. Årrestad***



0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9



Prediction



```

from hls4ml import ...
import tensorflow as tf

# train or load a model
model = ... # e.g. tf.keras.models.load_model(...)

# make a config template
cfg = config_from_keras_model(model,
granularity='name')

# tune the config
cfg['LayerName']['layer2']['ReuseFactor'] = 4

# do the conversion
hmodel = convert_from_keras_model(model, cfg)

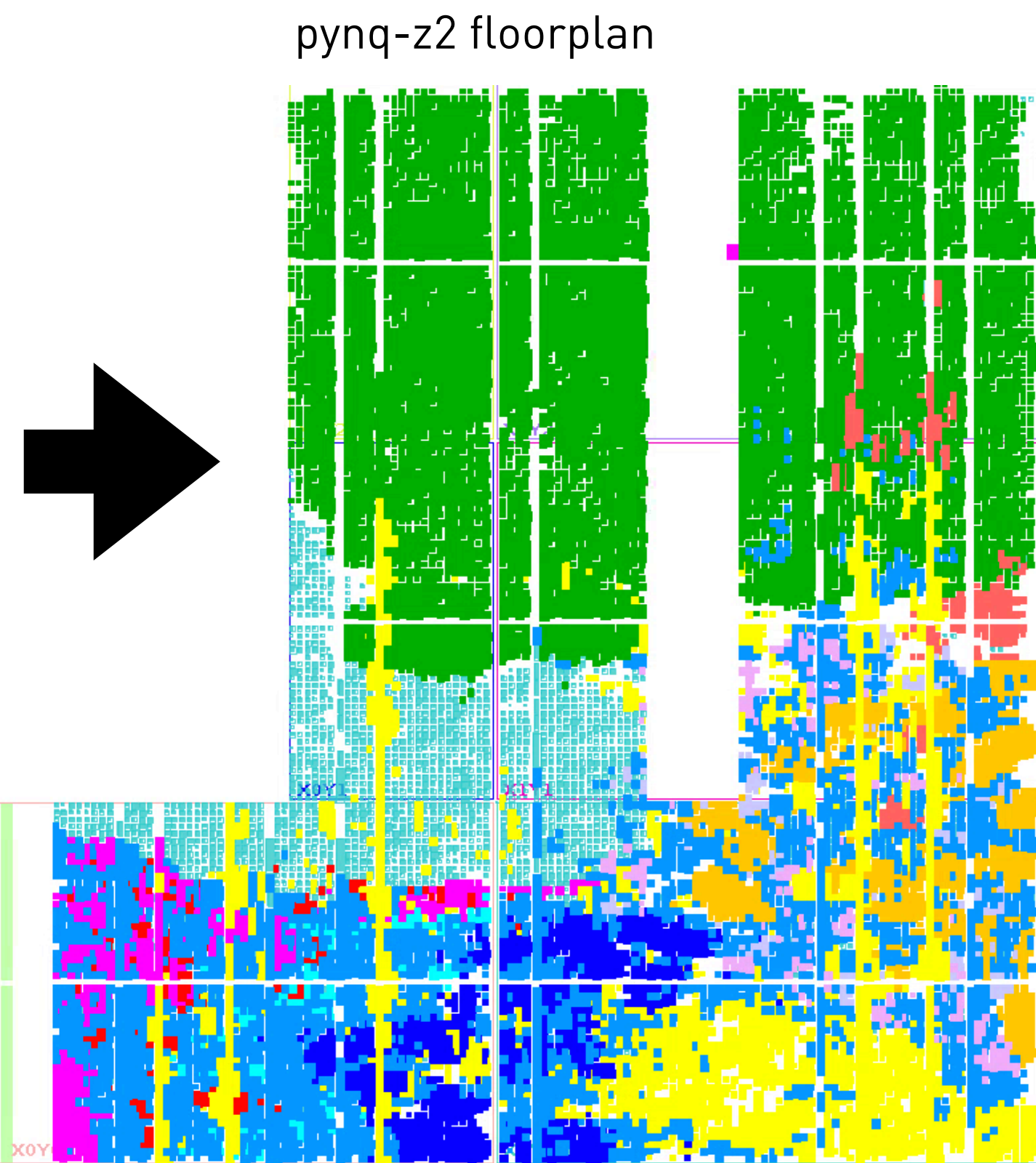
# write and compile the HLS
hmodel.compile()

# run bit accurate emulation
y_tf = model.predict(x)
y_hls = hmodel.predict(x)

# do some validation
np.testing.assert_allclose(y_tf, y_hls)

# run HLS synthesis
hmodel.build()

```




Our work here at IPA!
P. Odagiu, C. Sun, A. Oliver, T. Årrestad

[← Go to NeurIPS 2022 Track Datasets and Benchmarks h...](#)

Why do tree-based models still outperform deep learning on typical tabular data?

Leo Grinsztajn, Edouard Oyallon, Gael Varoquaux

06 Jun 2022 (modified: 16 Jan 2023) NeurIPS 2022 Datasets and Benchmarks Readers:  Everyone [Show Bibtex](#) [Show Revisions](#)

Abstract: While deep learning has enabled tremendous progress on text and image datasets, its superiority on tabular data is not clear. We contribute extensive benchmarks of standard and novel deep learning methods as well as tree-based models such as XGBoost and Random Forests, across a large number of datasets and hyperparameter combinations. We define a standard set of 45 datasets from varied domains with clear characteristics of tabular data and a benchmarking

Ongoing work by Andrew Oliver (IPA) of good main state-of-

the-art on medium-sized data (~10K samples) even without accounting



arXiv > cs > arXiv:2210.05189

[Help](#) | [Advanced](#)

Computer Science > Machine Learning

[Submitted on 11 Oct 2022 (v1), last revised 25 Oct 2022 (this version, v3)]

Neural Networks are Decision Trees

Caglar Aytekin

In this manuscript, we show that any neural network with any activation function can be represented as a decision tree. The representation is equivalence and not an approximation, thus keeping the accuracy of the neural network exactly as is. We believe that this work provides better understanding of neural networks and paves the way to tackle their black-box nature. We share equivalent trees of some neural networks and show that besides providing interpretability, tree representation can also achieve some computational advantages for small networks. The analysis holds both for fully connected and convolutional networks, which may or may not also include skip connections and/or normalizations.

Subjects: **Machine Learning (cs.LG)**

Cite as: [arXiv:2210.05189](#) [cs.LG]

(or [arXiv:2210.05189v3](#) [cs.LG] for this version)

<https://doi.org/10.48550/arXiv.2210.05189> 

Submission history

From: Çağlar Aytekin [[view email](#)]

[v1] Tue, 11 Oct 2022 06:49:51 UTC (216 KB)

[v2] Mon, 17 Oct 2022 15:18:14 UTC (224 KB)

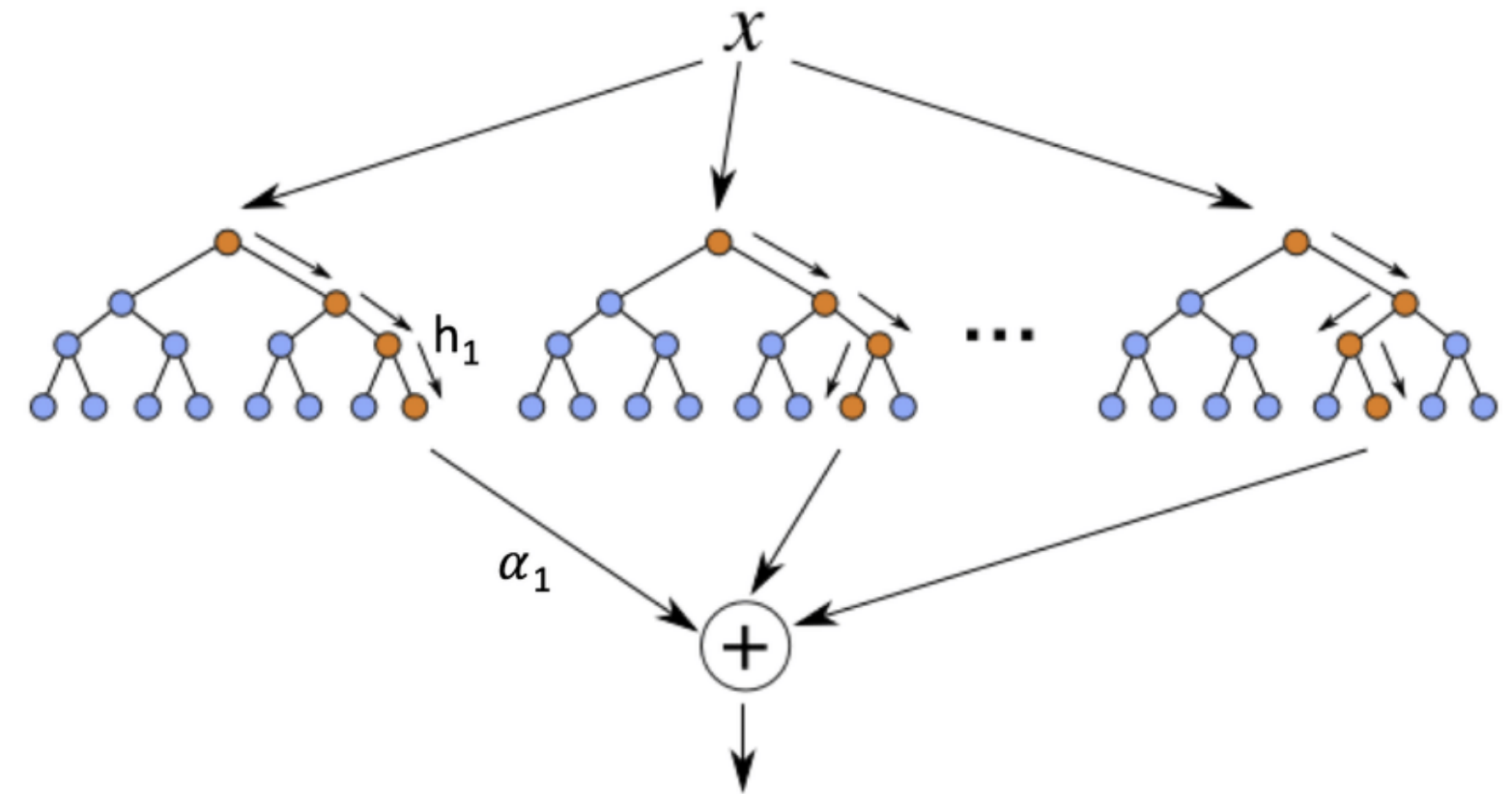
[v3] Tue, 25 Oct 2022 17:32:33 UTC (240 KB)

Google AI



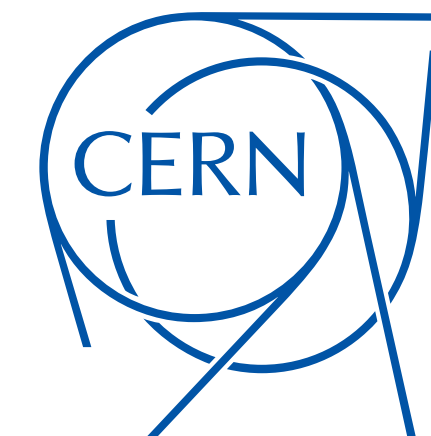
TensorFlow

Decision Forests



%VU9P	Accuracy	Latency	DSP	LUT
qDNN	75.6%	40 ns	22 (~0%)	1%
BDT	74.9%	5 ns	-	0.5%

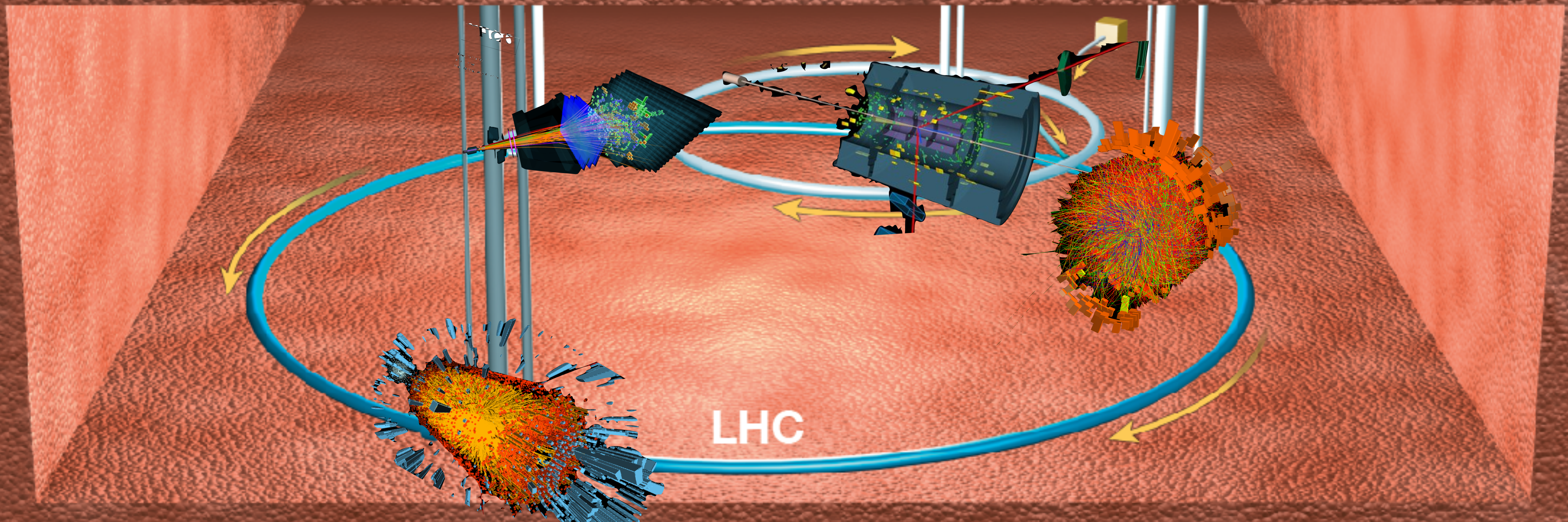
IPA

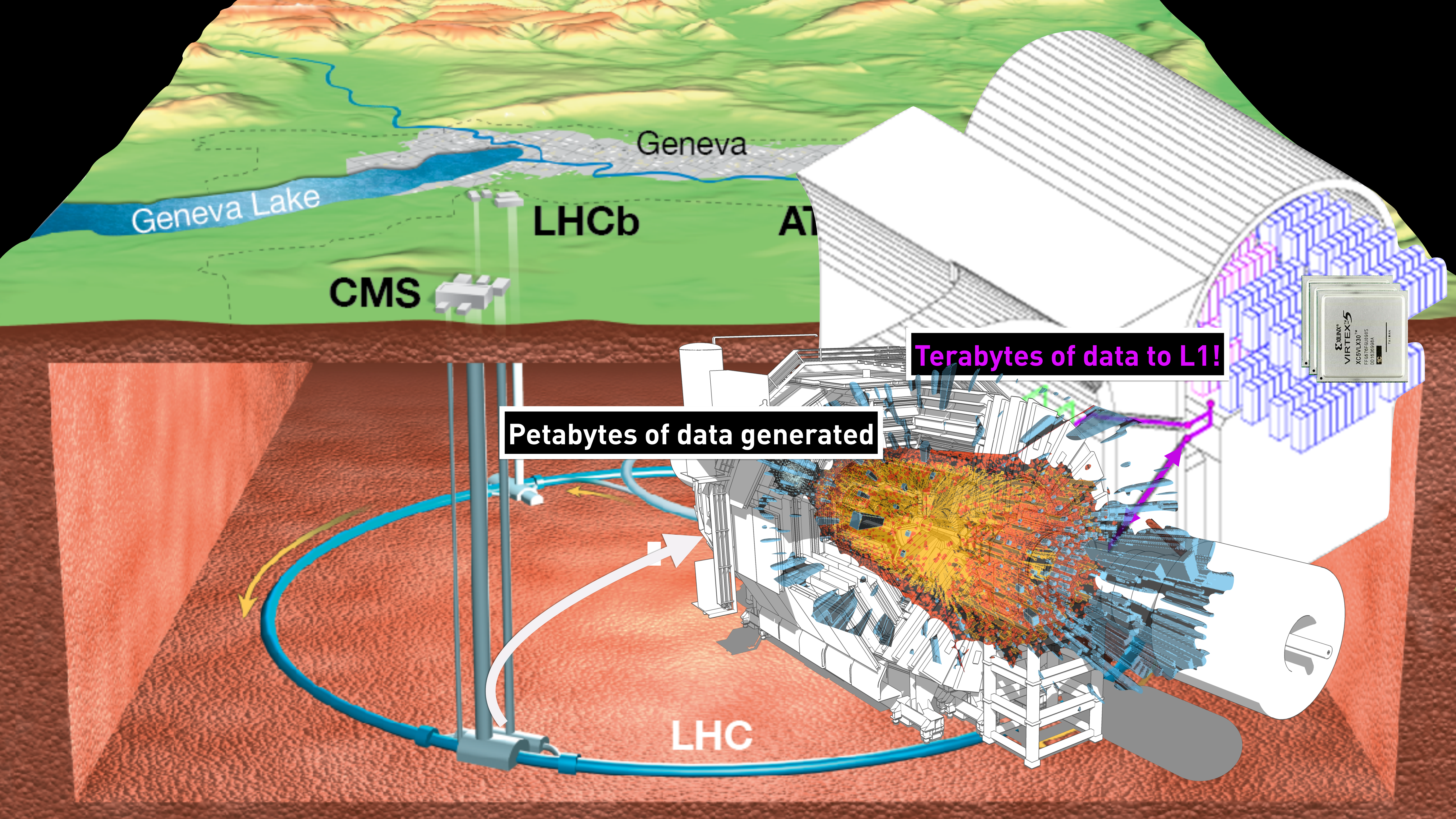


Conifer

Ongoing work by Andrew Oliver (IPA)

Where and how are we using this at LHC?





Geneva Lake

Geneva

CMS

LHCb

ATLAS

Petabytes of data generated

Terabytes of data to L1!

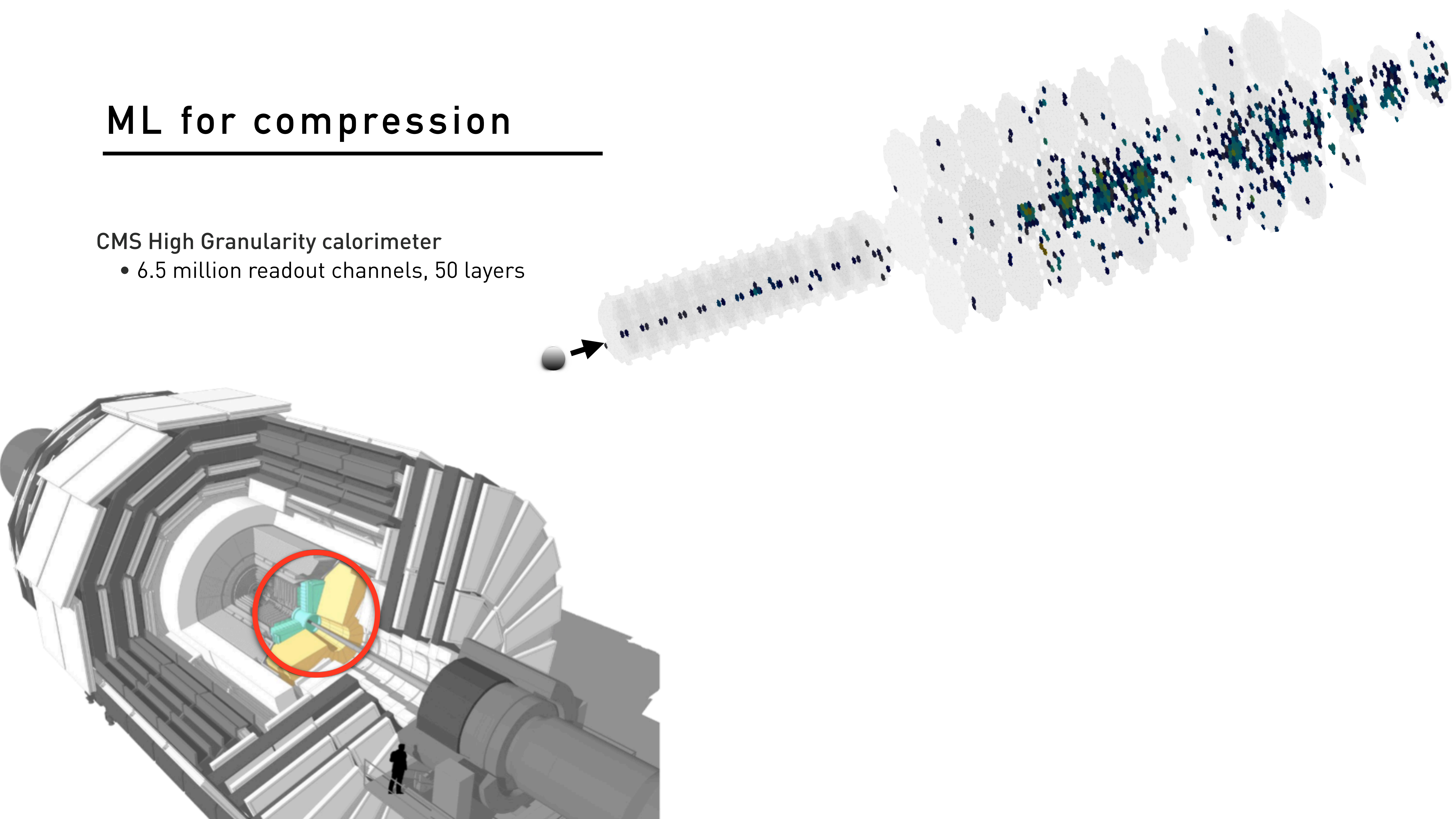
LHC



ML for compression

CMS High Granularity calorimeter

- 6.5 million readout channels, 50 layers

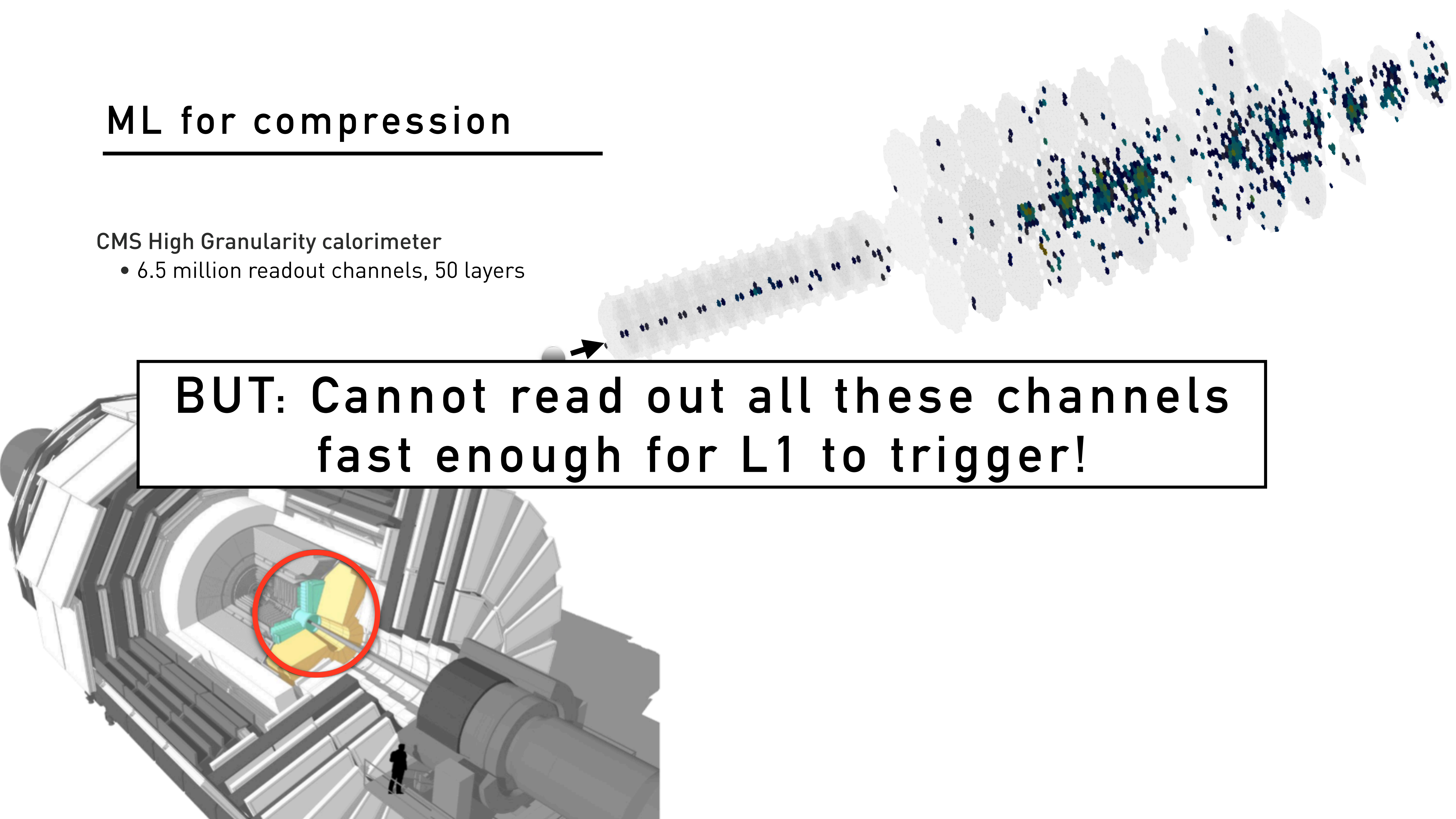


ML for compression

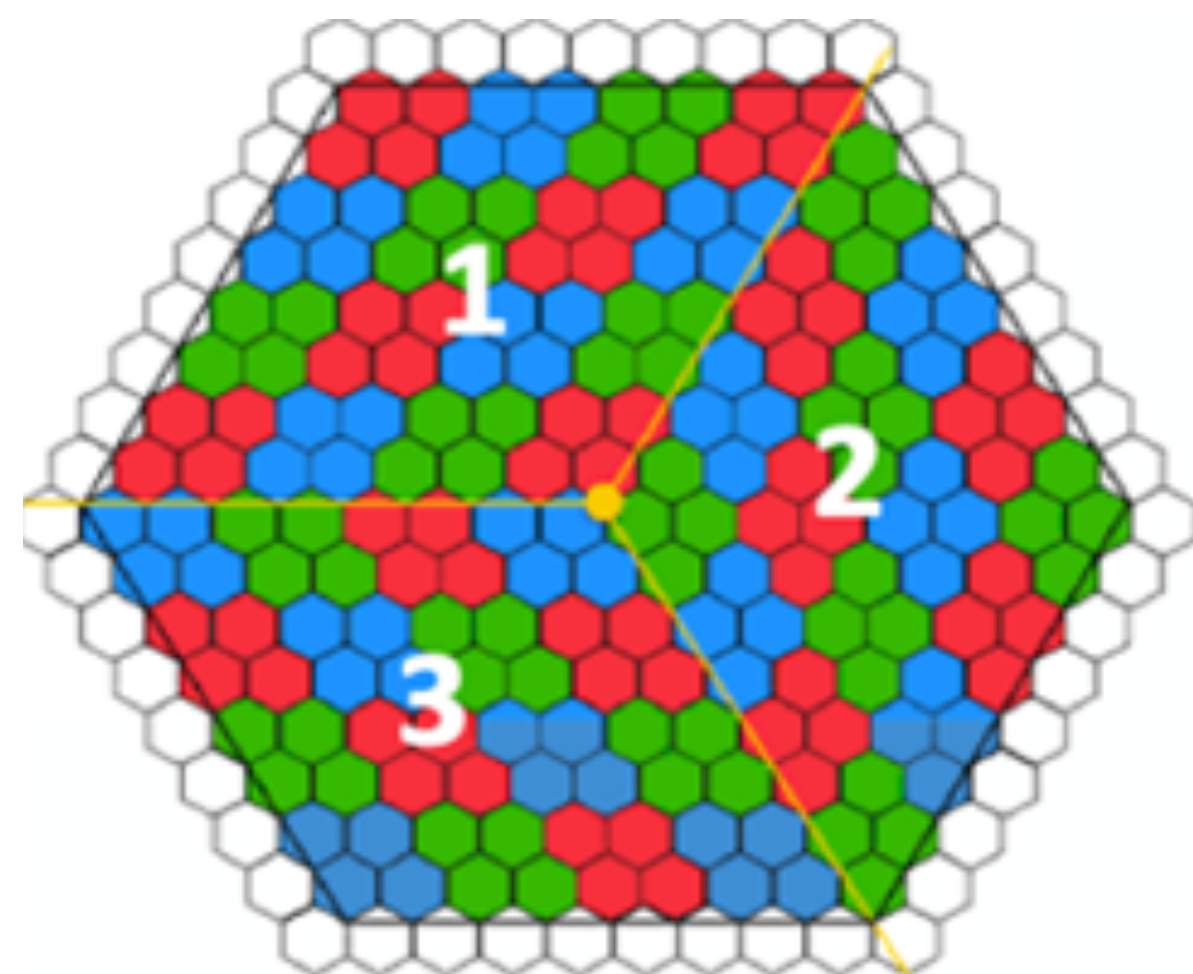
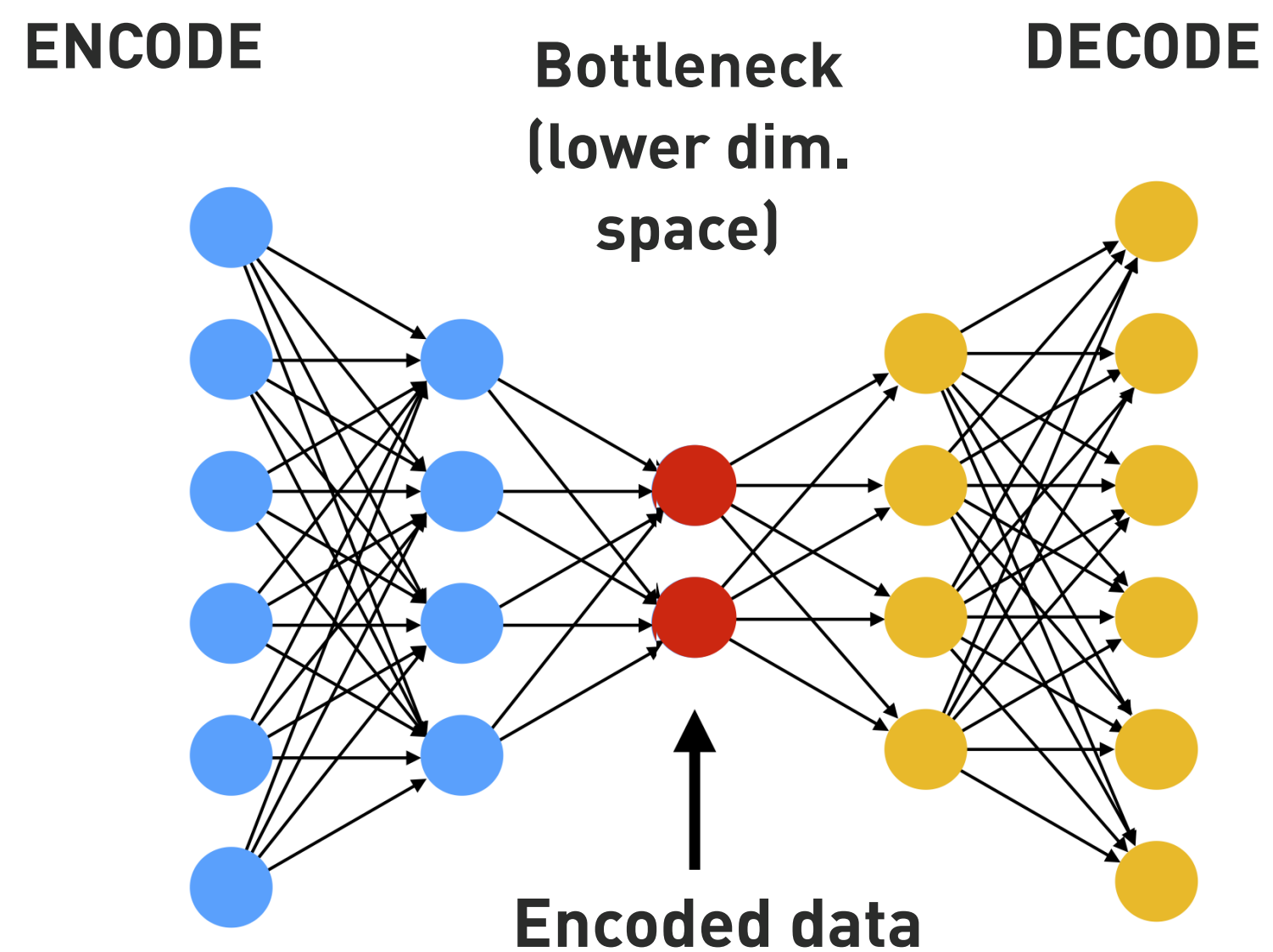
CMS High Granularity calorimeter

- 6.5 million readout channels, 50 layers

BUT: Cannot read out all these channels fast enough for L1 to trigger!

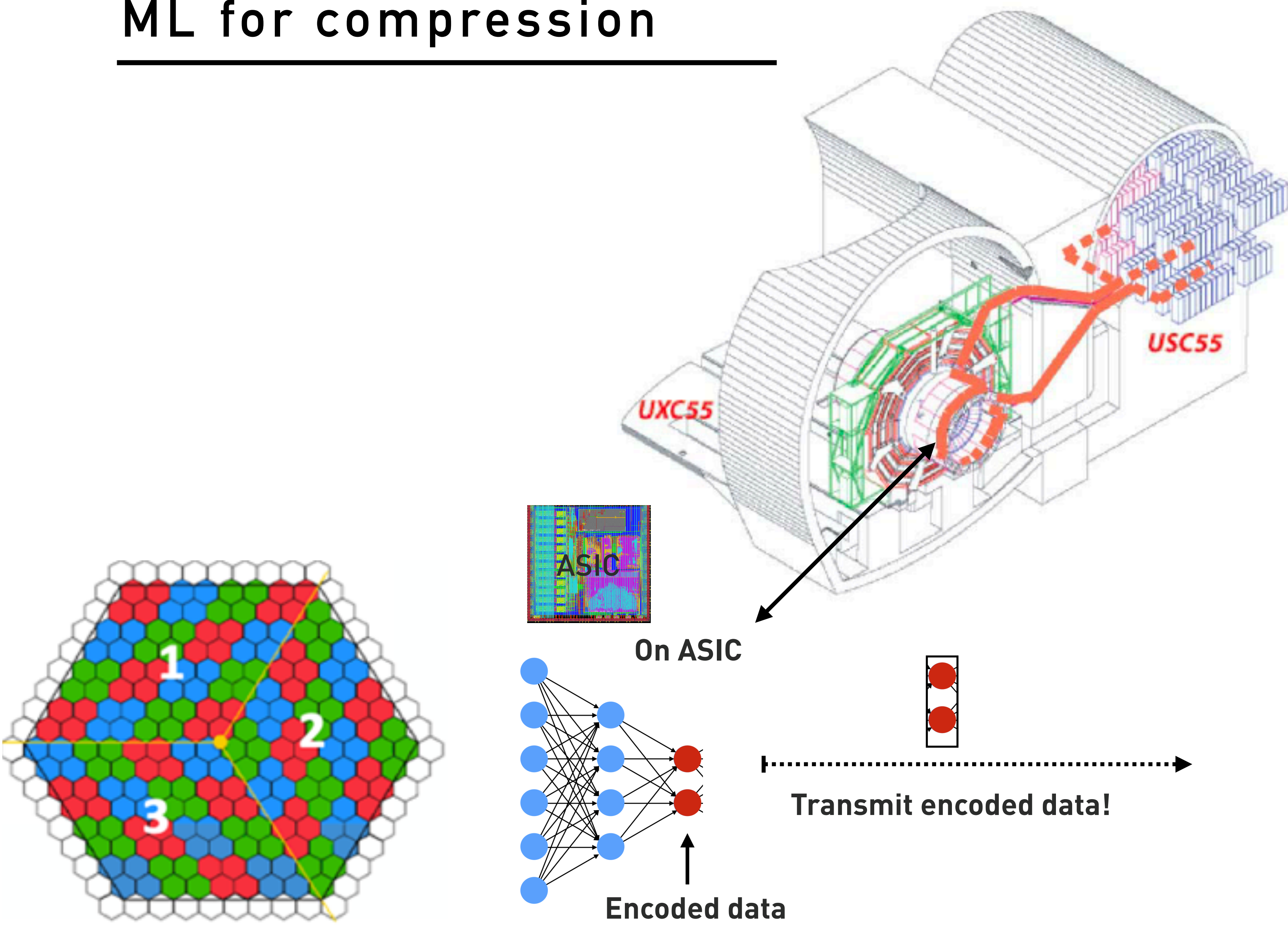


ML for compression

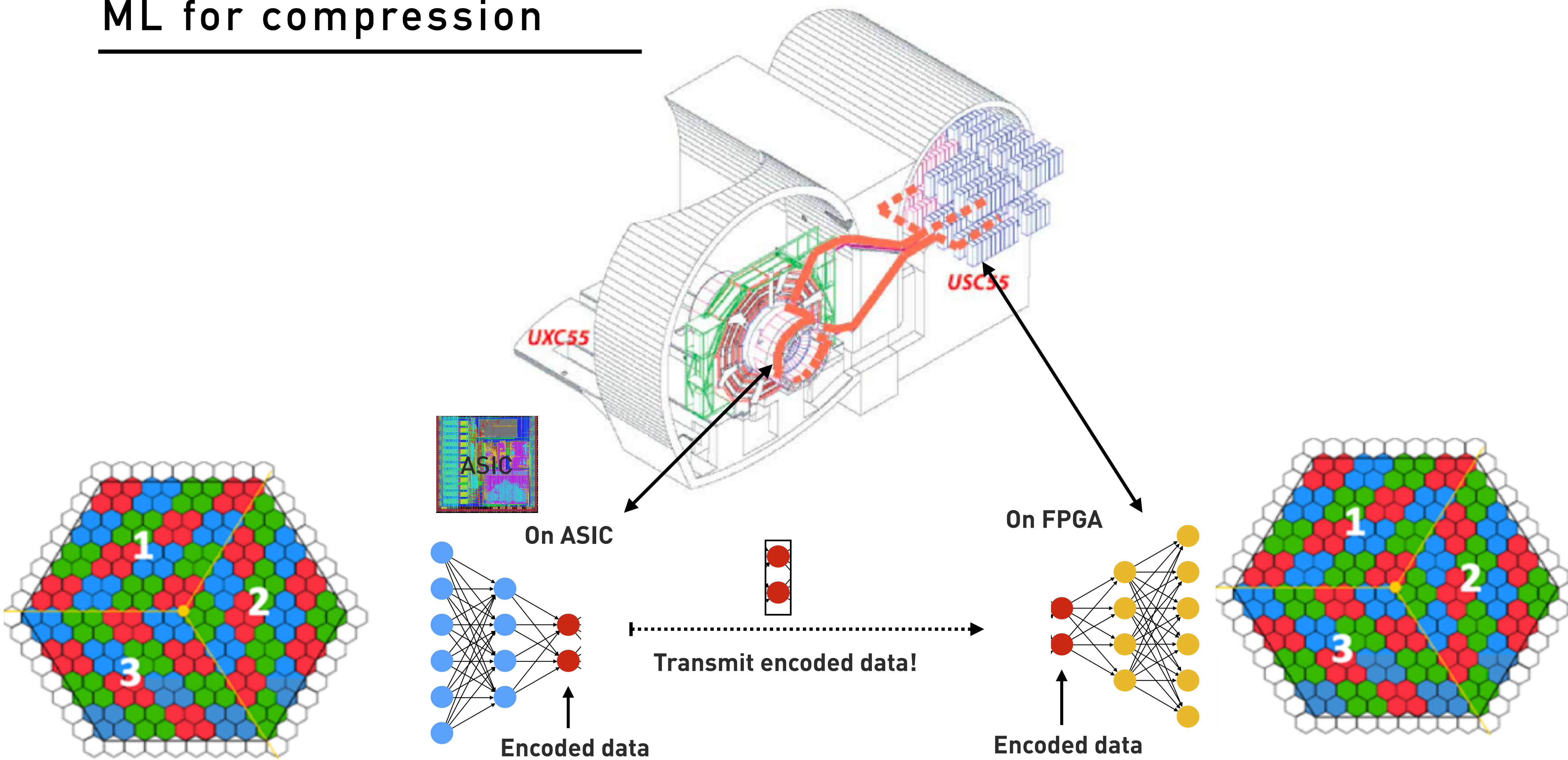


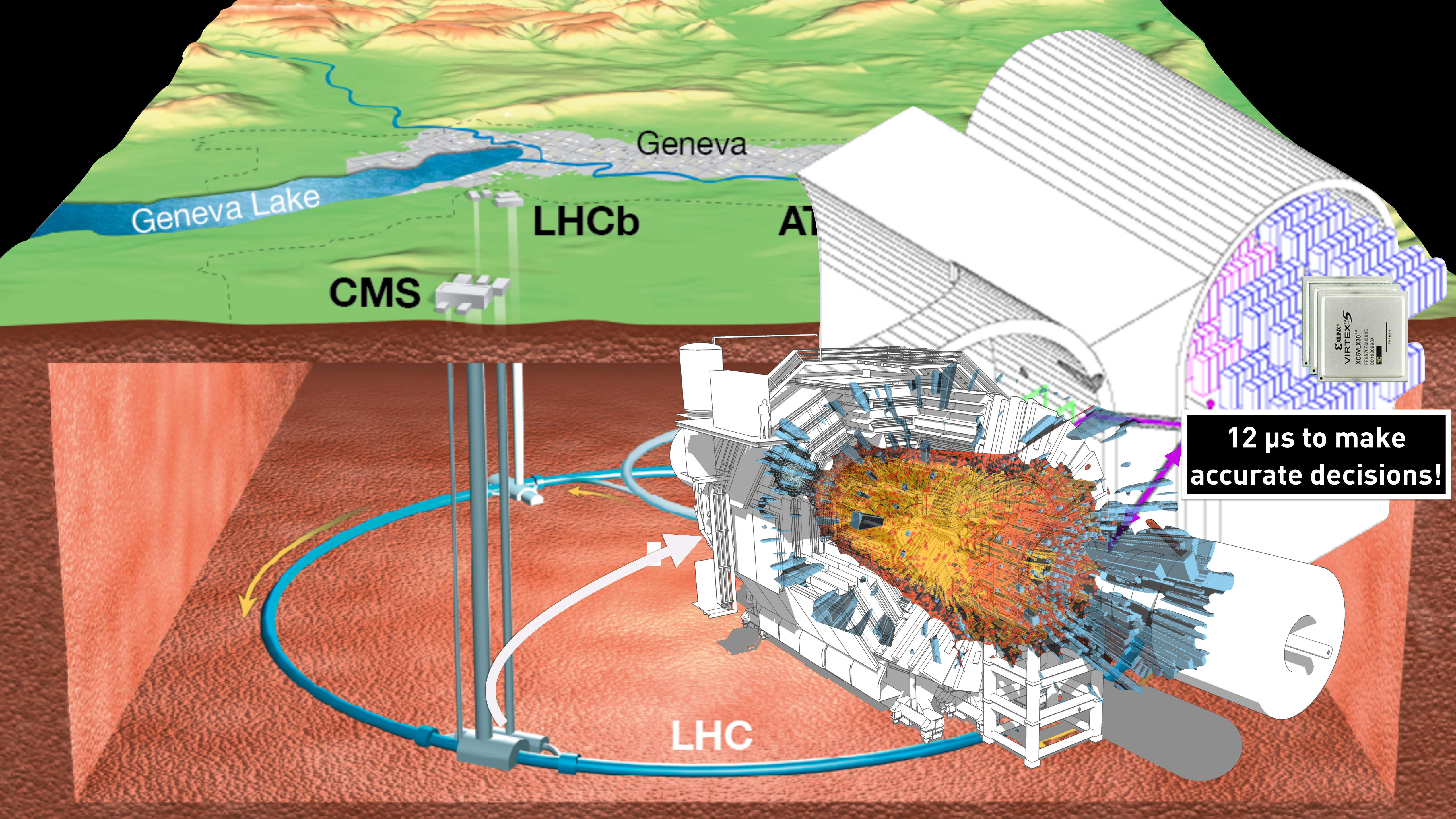
Variational Autoencoder

ML for compression



ML for compression





Geneva

Geneva Lake

CMS

LHCb

ATLAS



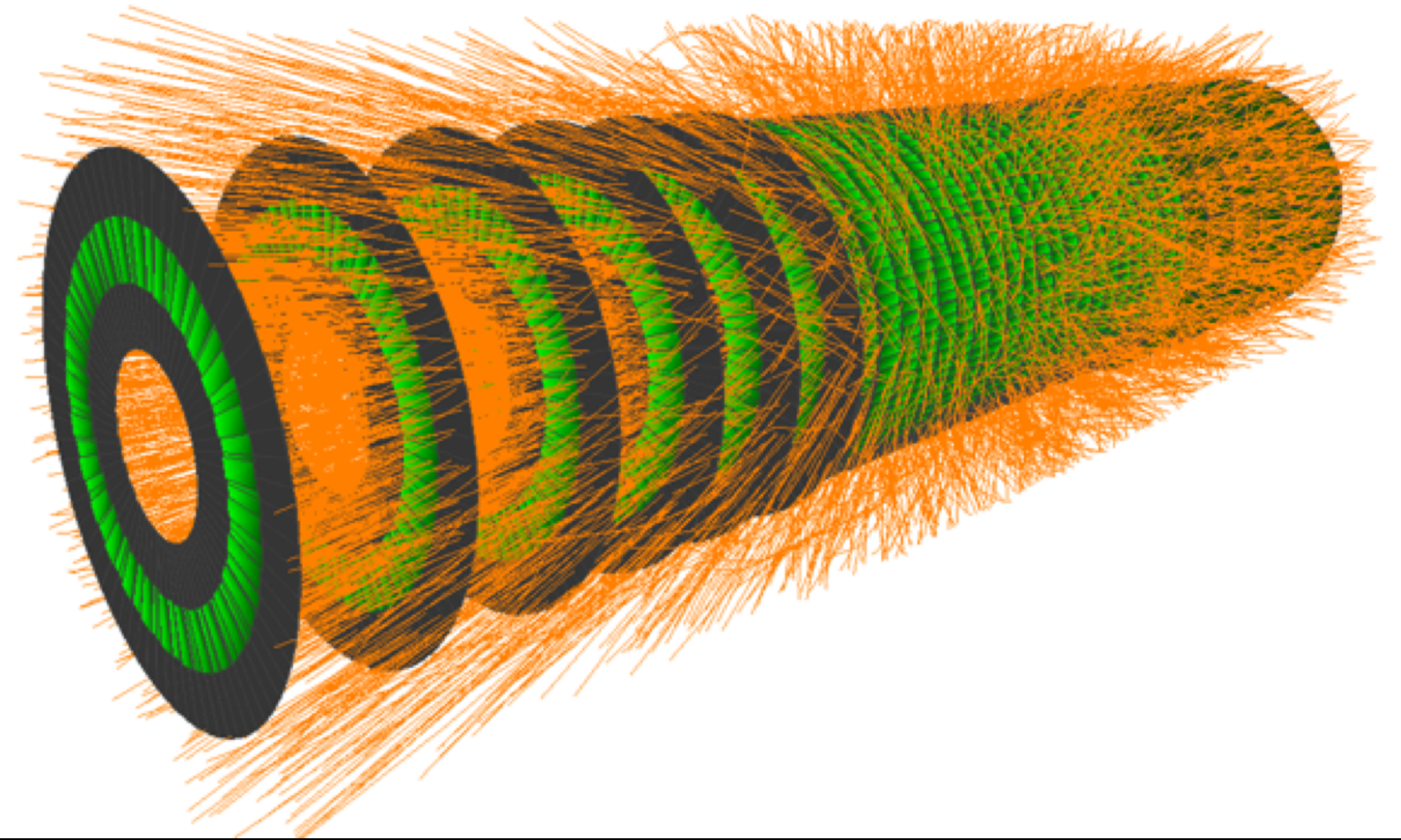
12 μ s to make accurate decisions!

LHC

ML for track reconstruction

- $O(1000)$ hits
- $O(100)$ tracks
- $5 \mu\text{s}$ latency!

Graph Neural Networks for fast reconstruction!

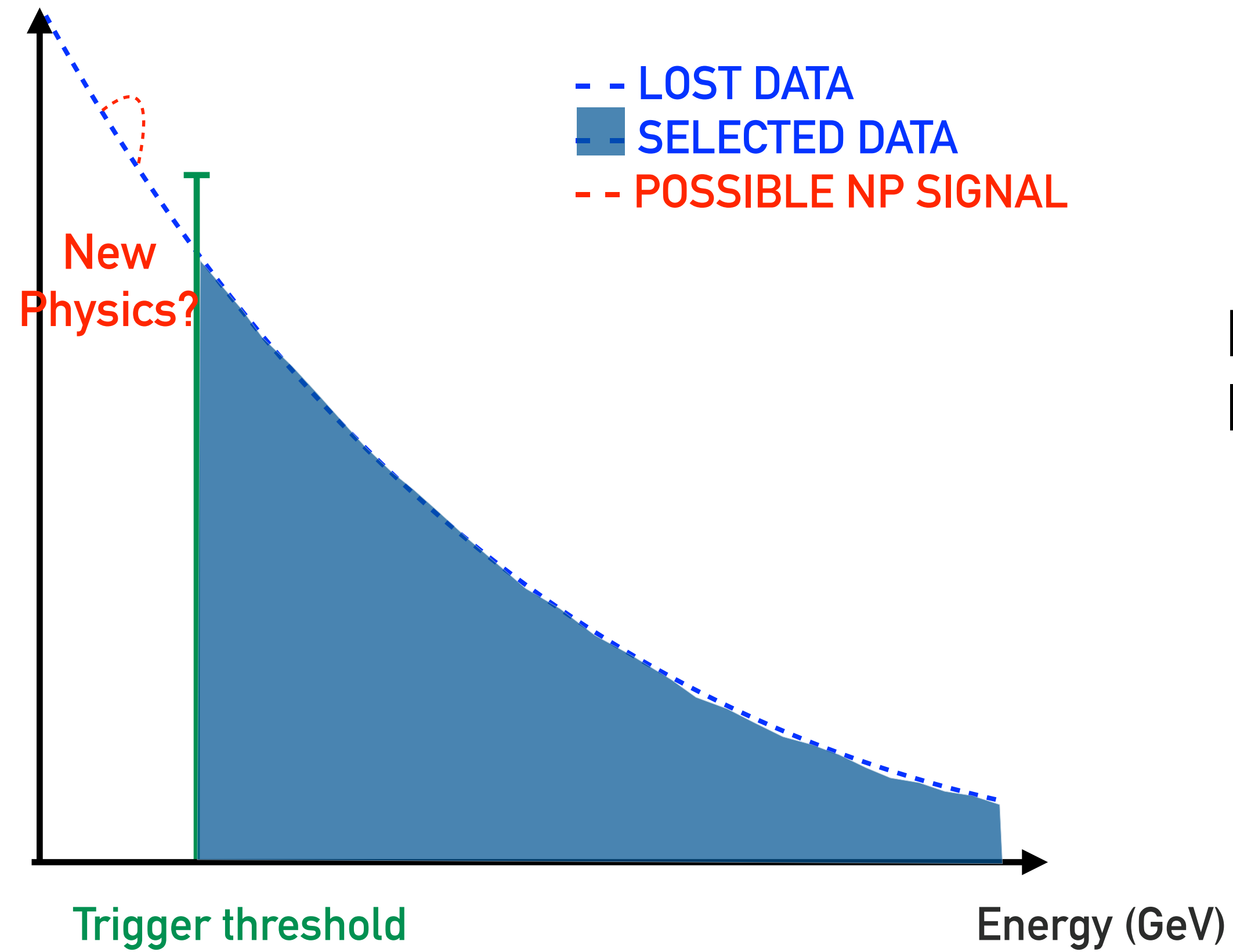


Design	$(n_{\text{nodes}}, n_{\text{edges}})$	RF	Precision	Latency [cycles]	II [cycles]	DSP [%]	LUT [%]	FF [%]	BRAM [%]
Throughput-opt.	(28, 56)	1	ap_fixed<14, 7>	59	1	99.9	66.0	11.7	0.7

$3 \mu\text{s}$, but all the FPGA resources are used!

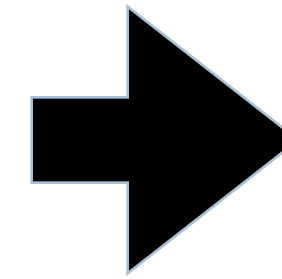
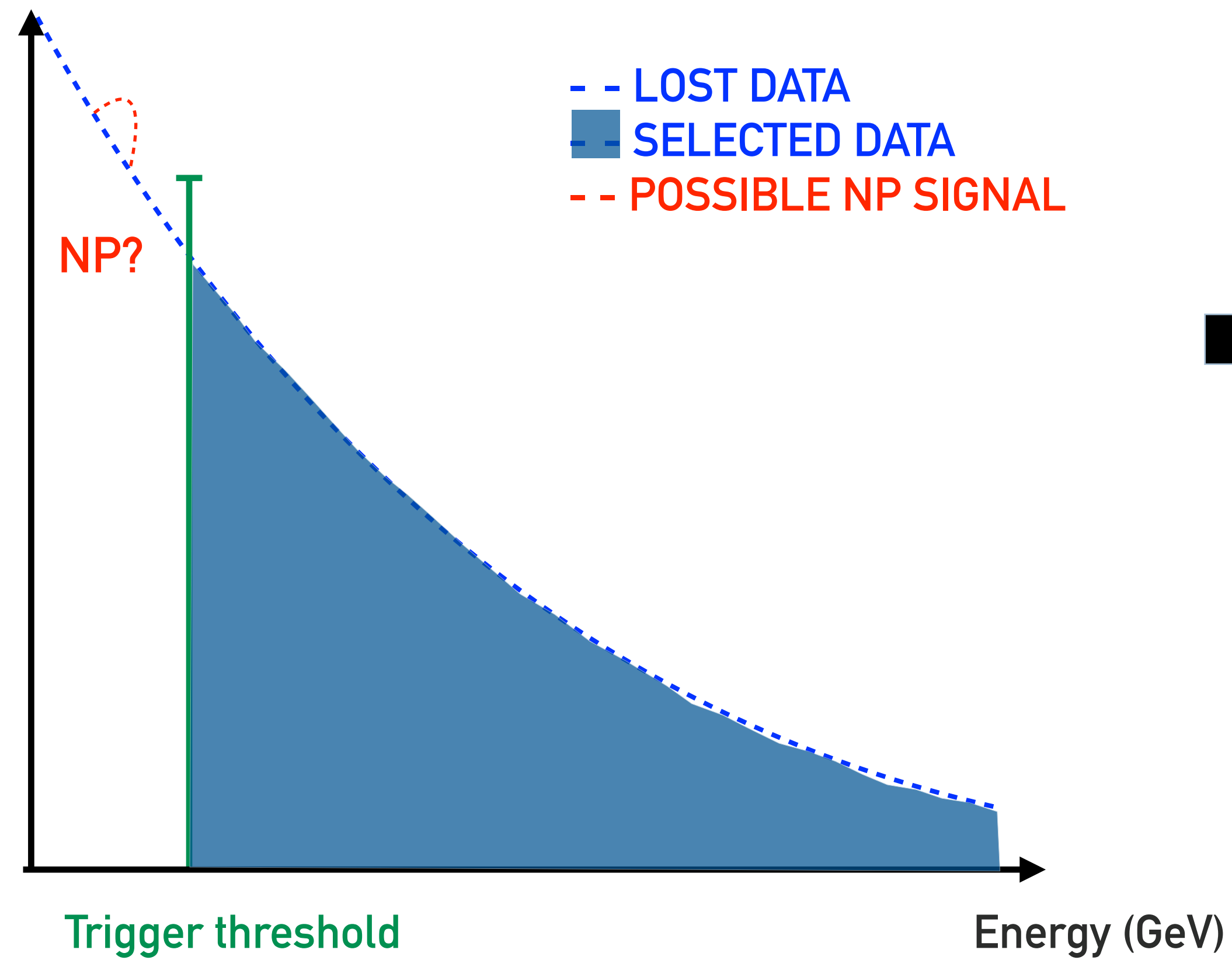
How to get fast and small graph-like NNs on FPGAs? Ongoing work by Patrick Odagiu (IPA)

Limitations of current trigger



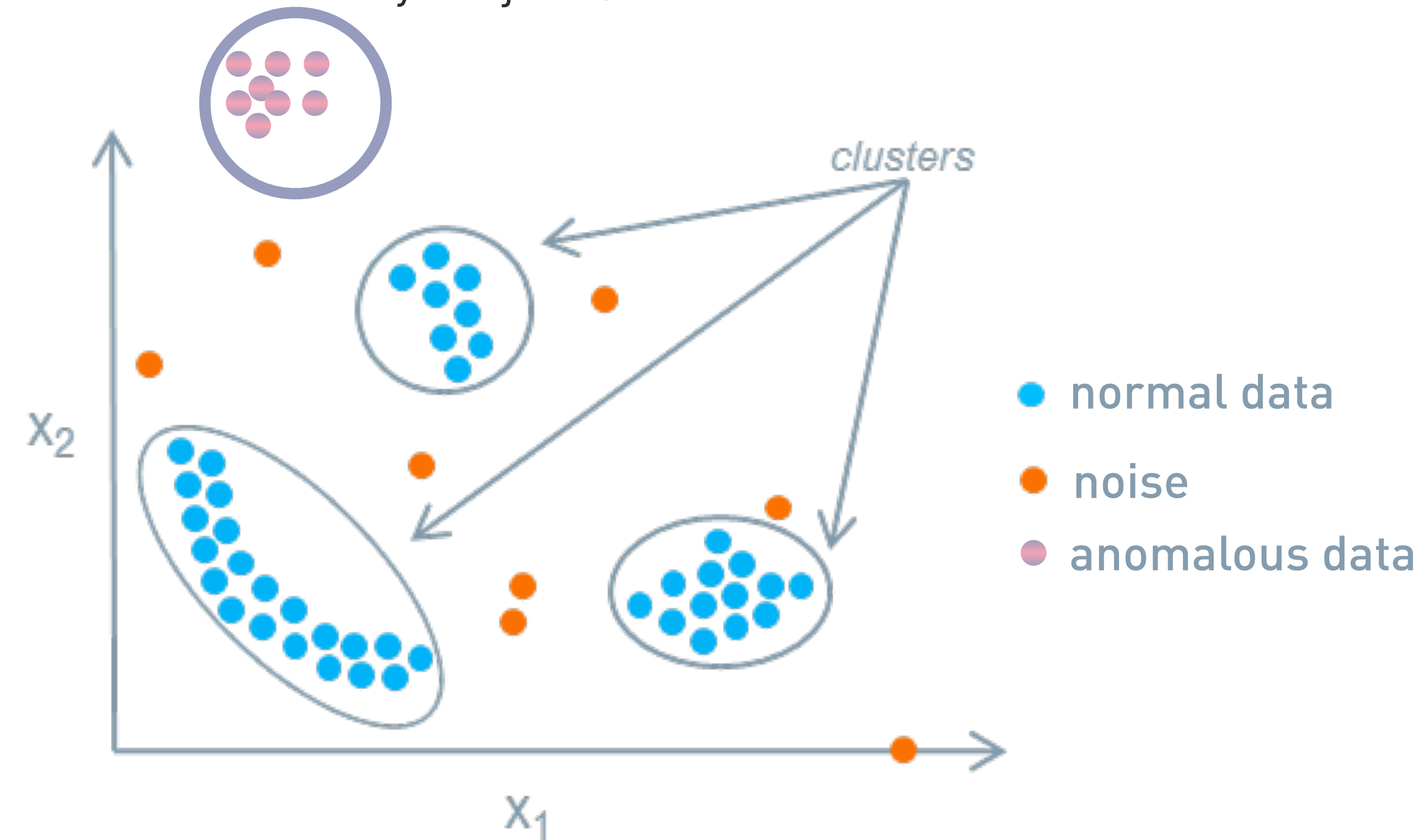
Level-1 rejects >98% of events!
Is there a smarter way to select?

Learning from data



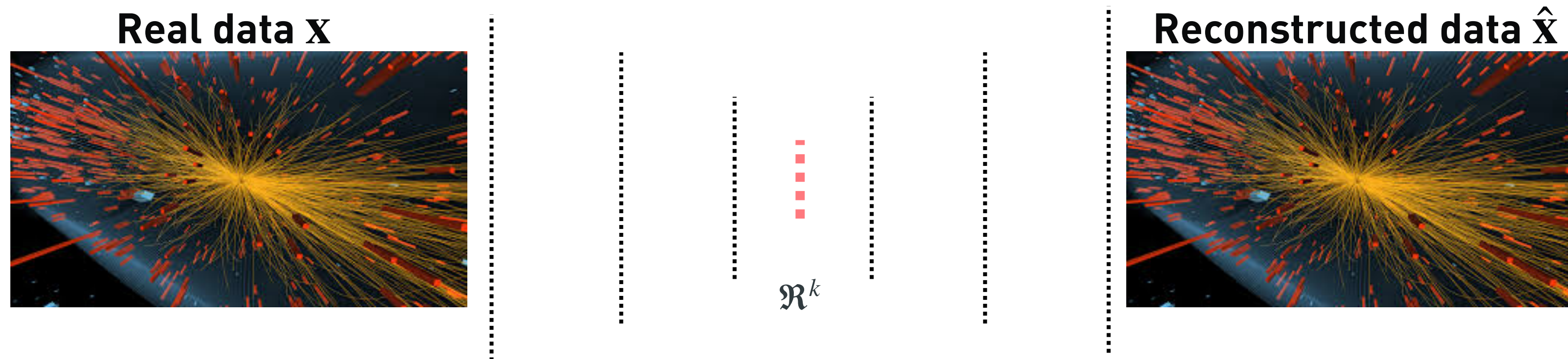
Look at **data** rather than defining signal hypothesis a priori

- Can we "classify" objects/events?

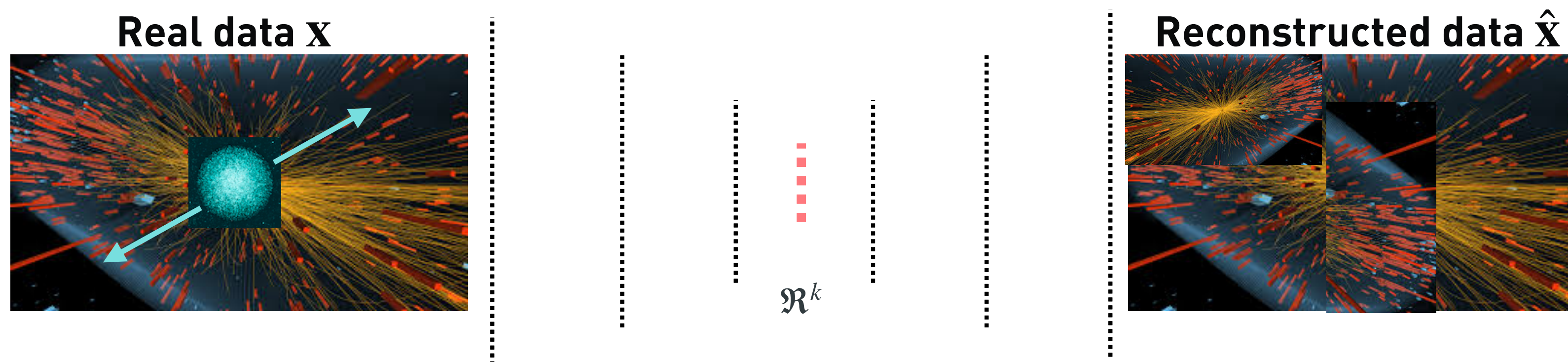


ML for anomaly detection

VAE: Learn from data

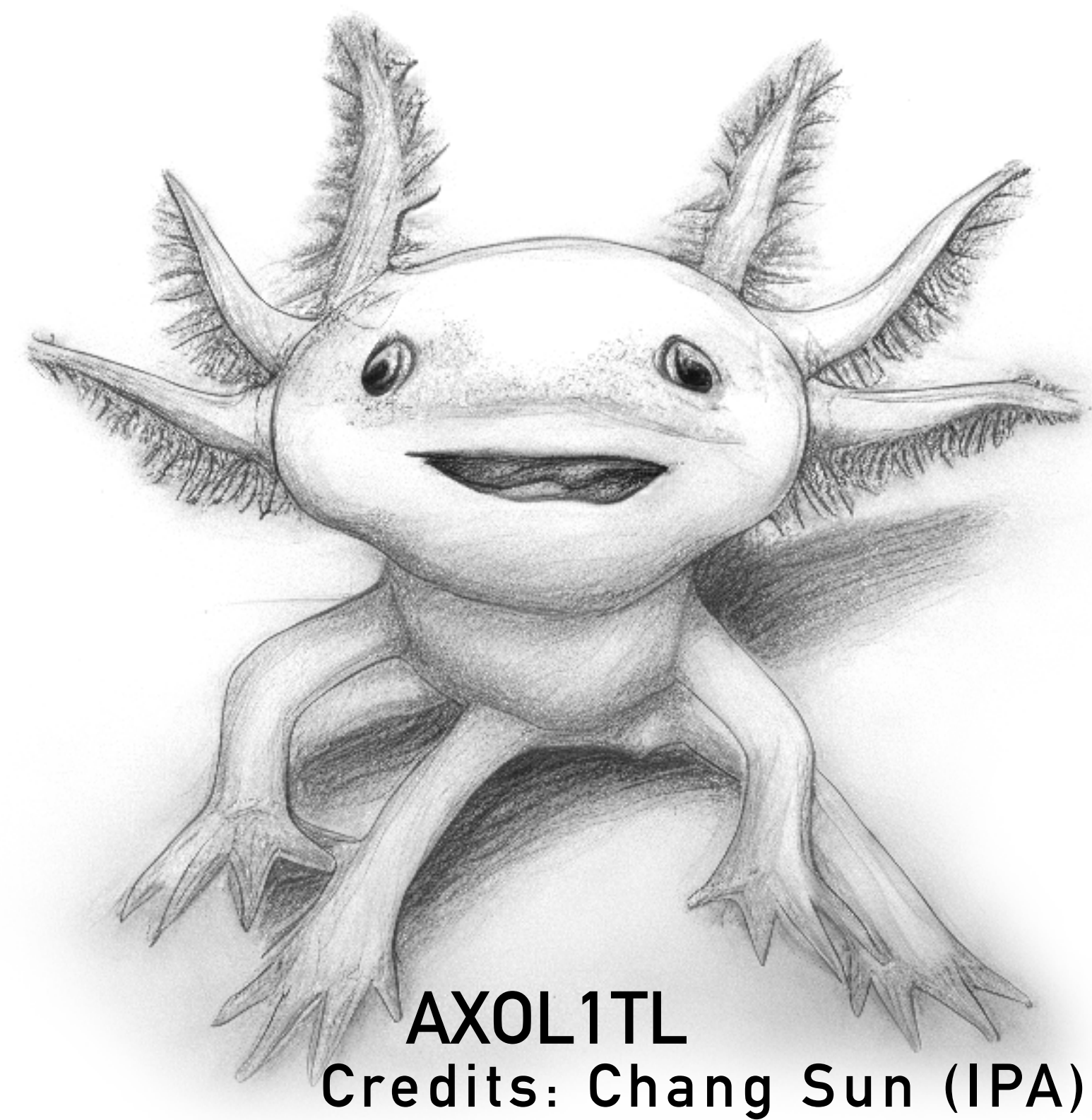
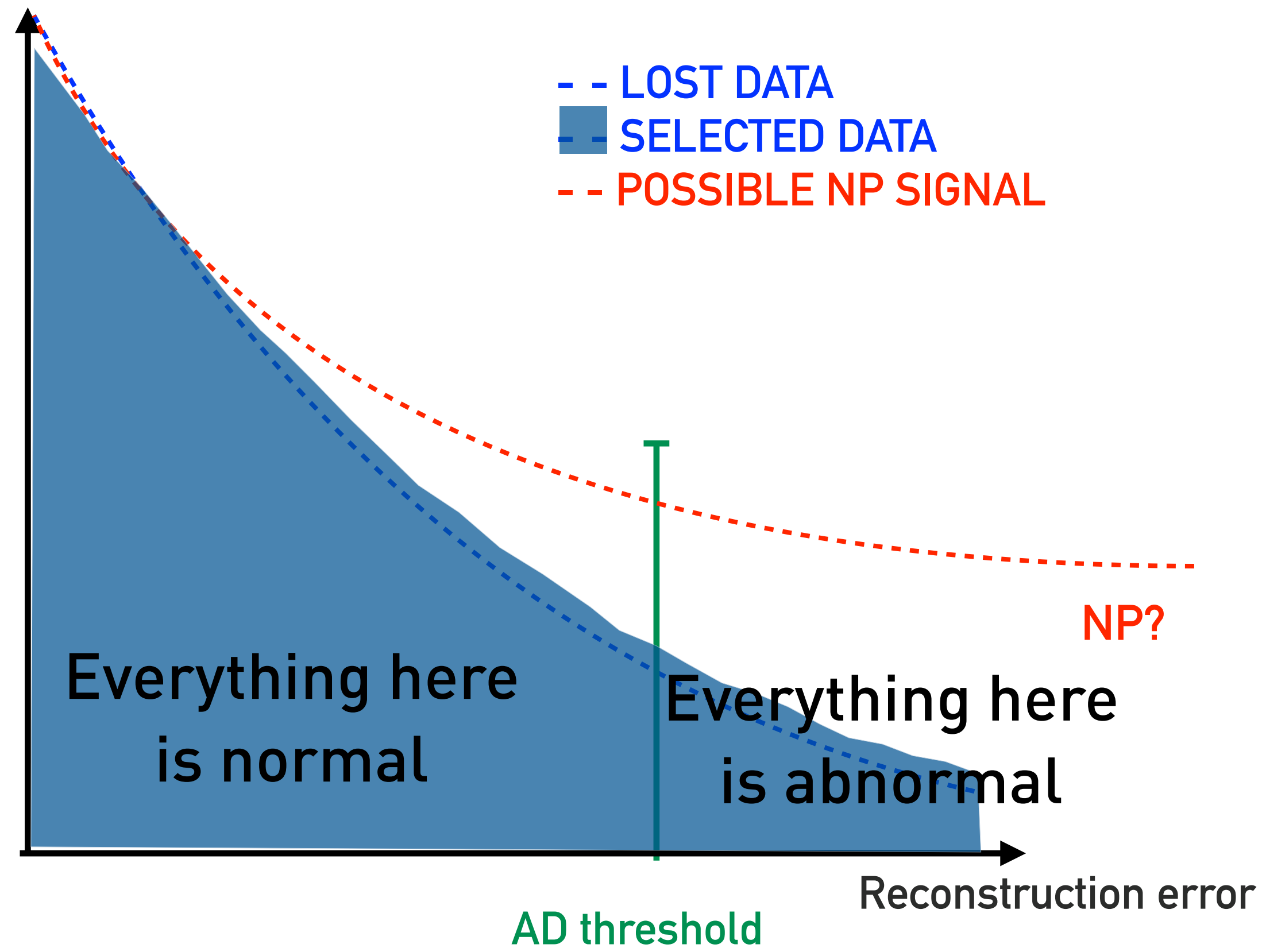


ML for anomaly detection



- Difference $\mathbf{x} - \hat{\mathbf{x}}$ defines "degree of abnormality"

ML for anomaly detection

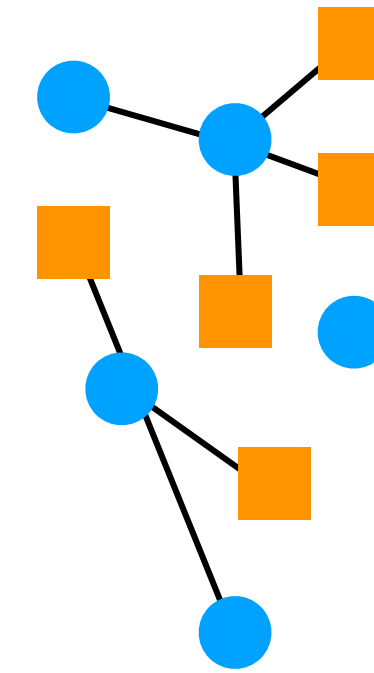


Select based on degree of abnormality!

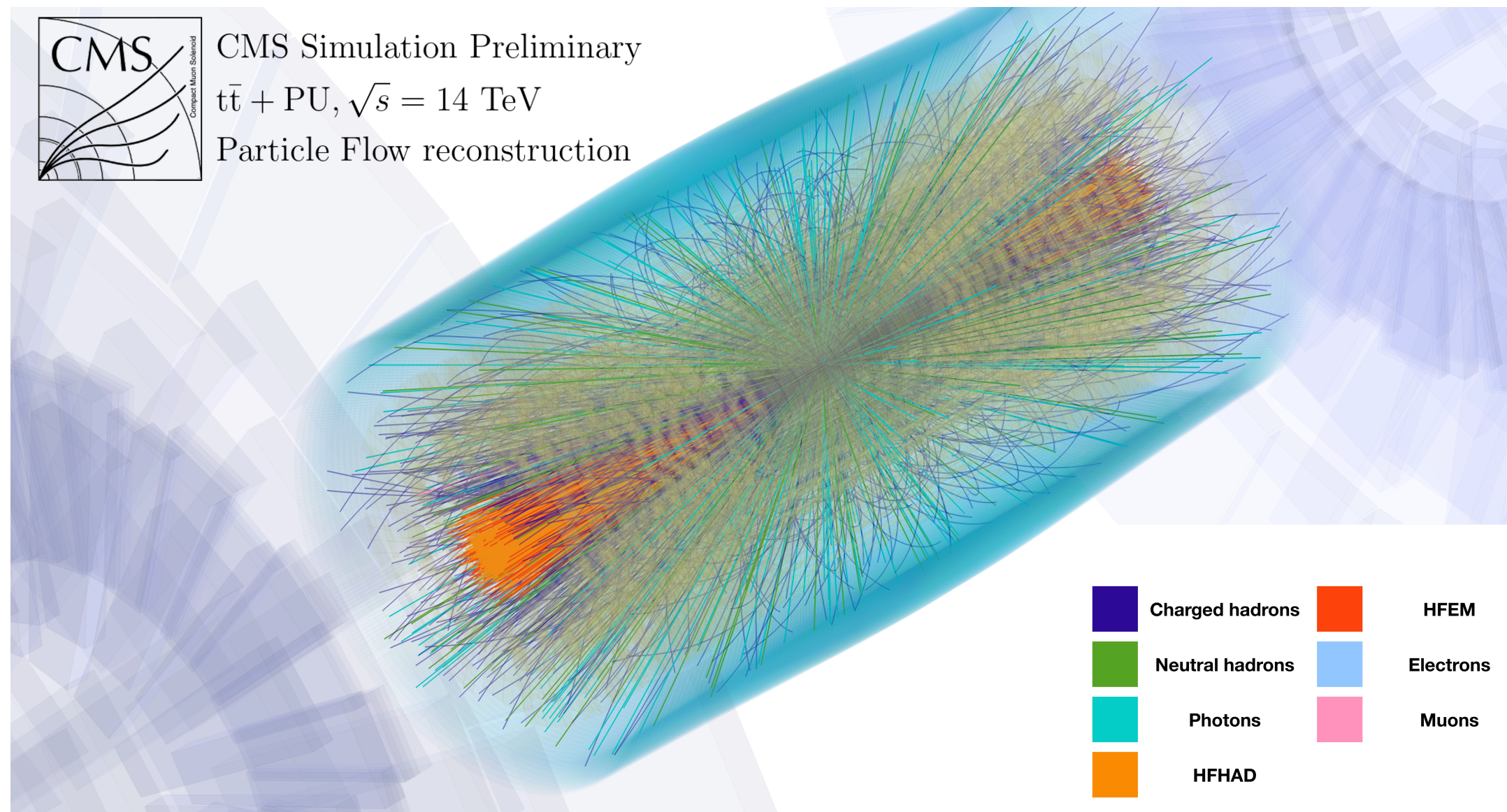
Ongoing work by Chang Sun, P. Odagiu (IPA)

The dream: ML for everything?

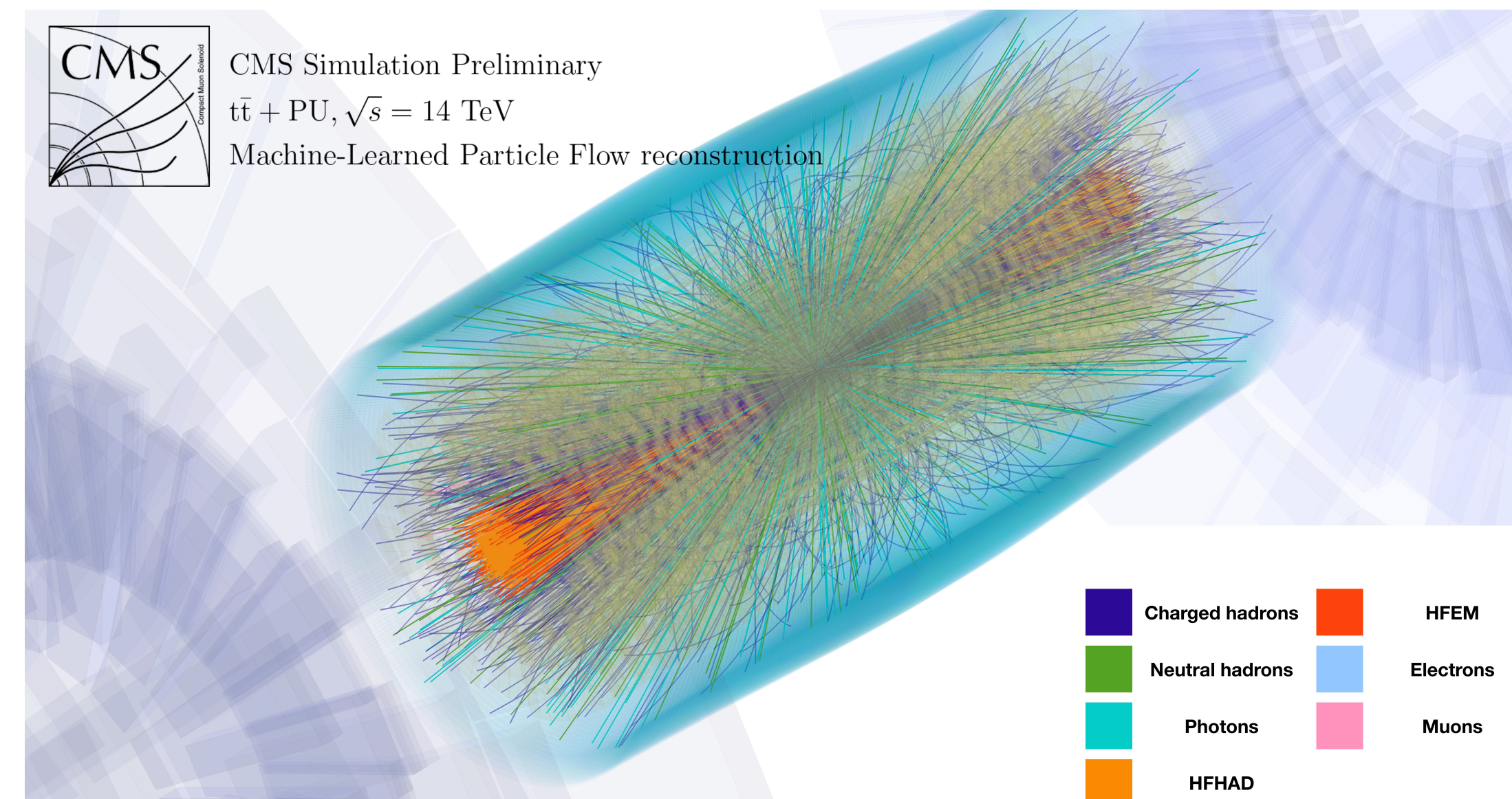
Graph Deep Neural Networks:
End-to-end ML for reconstructing the full collision?
Faster and better than classical reconstruction algorithms



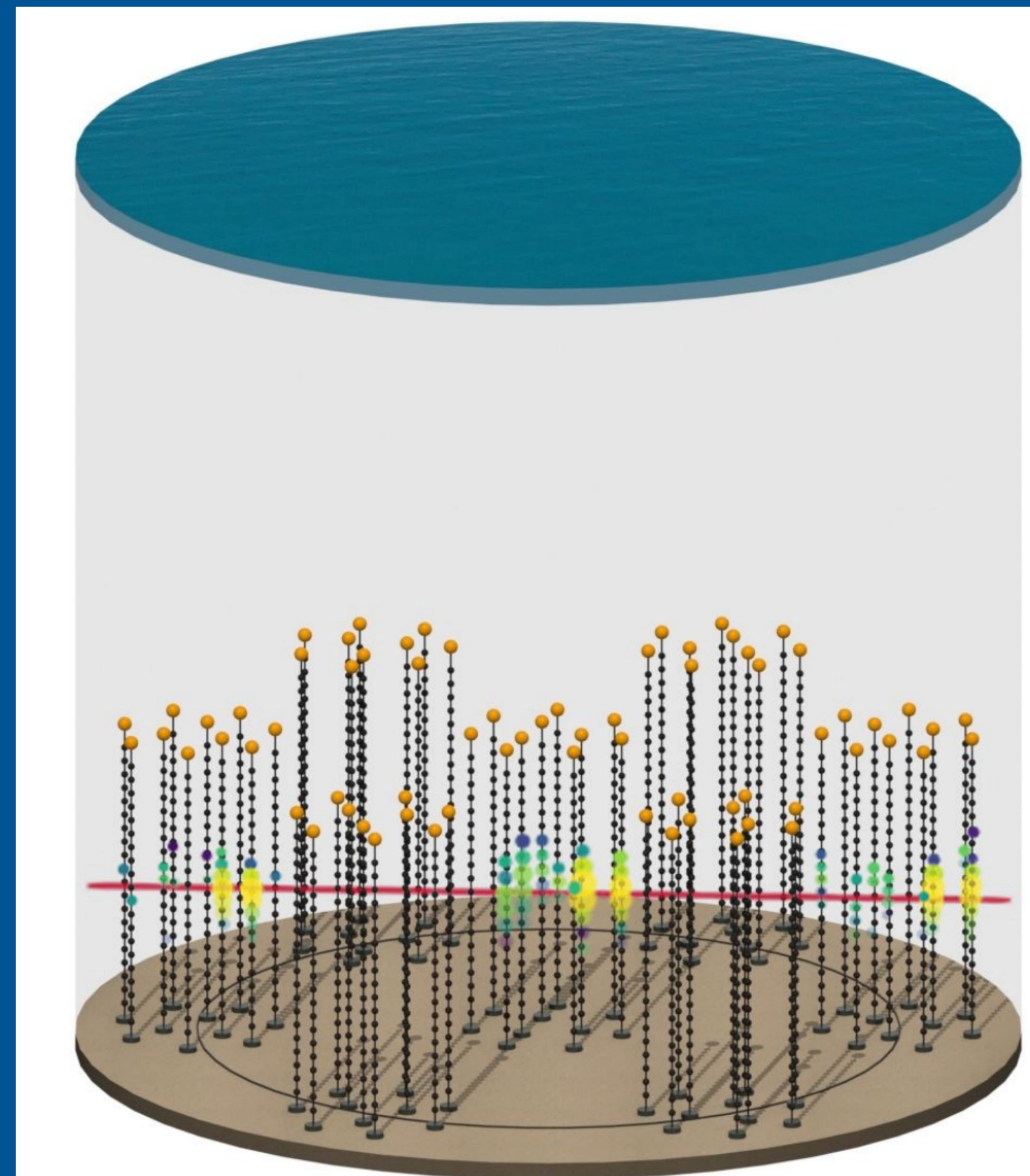
Classical Particle Flow

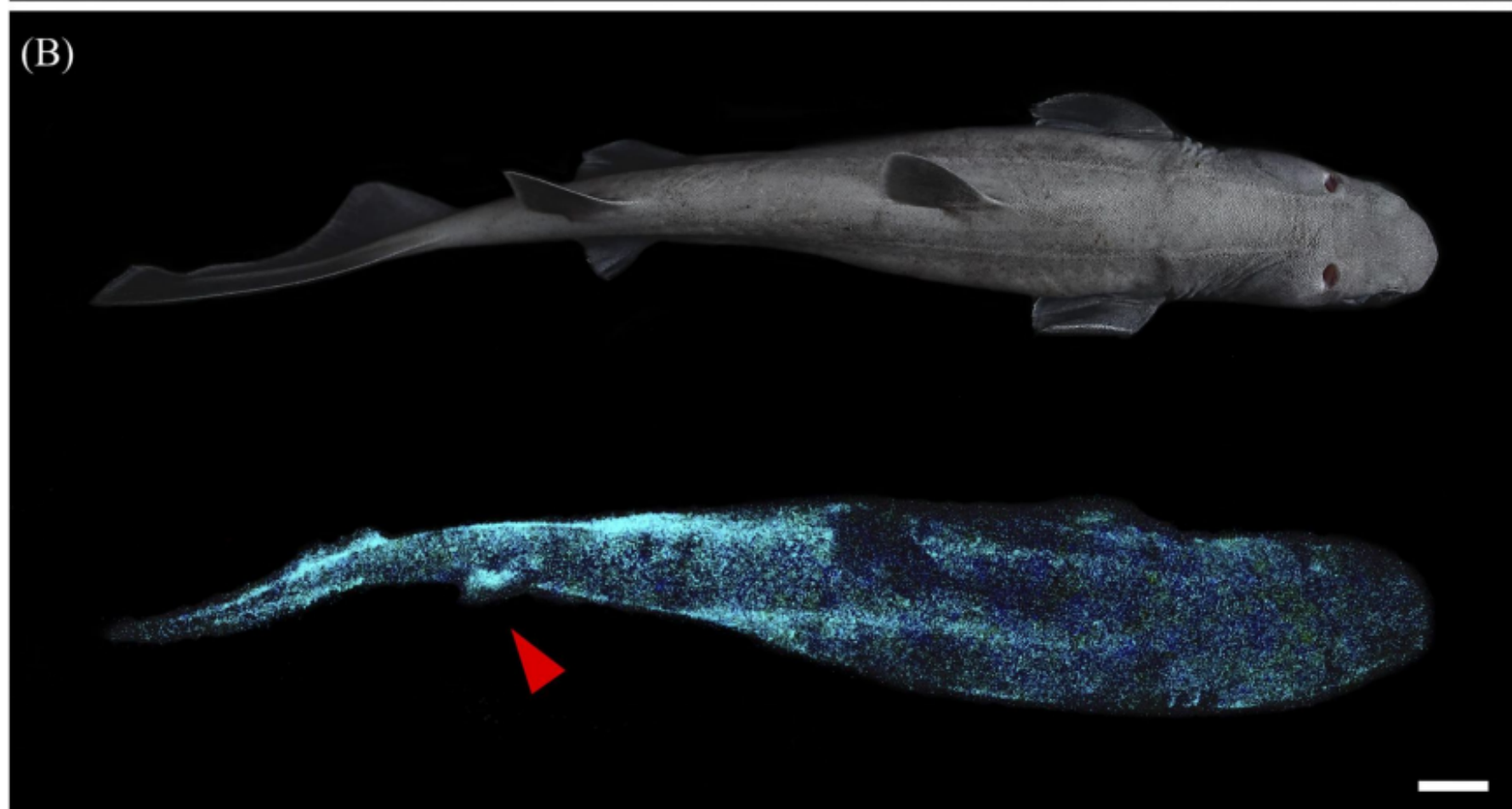
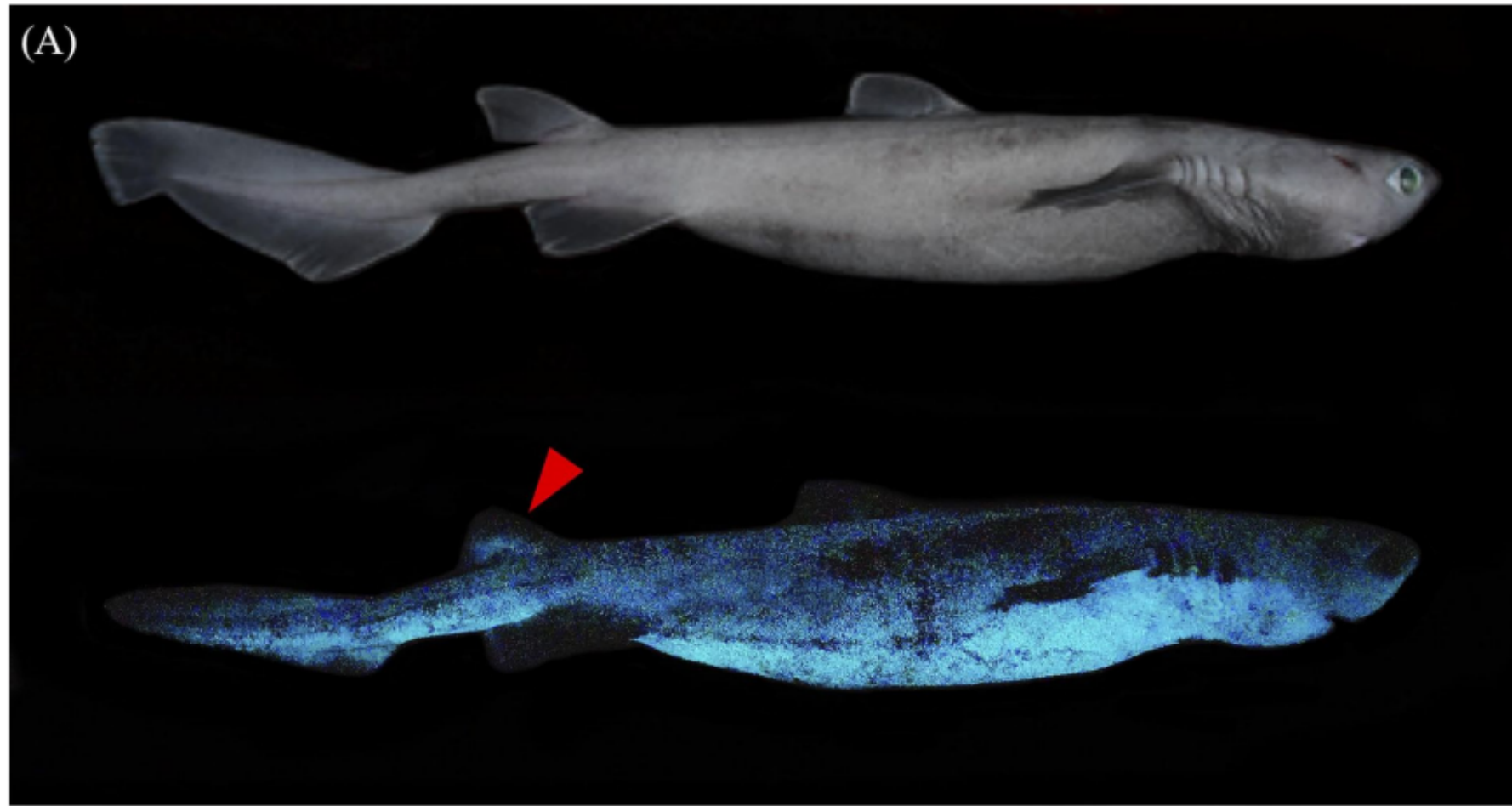


Graph Neural Network

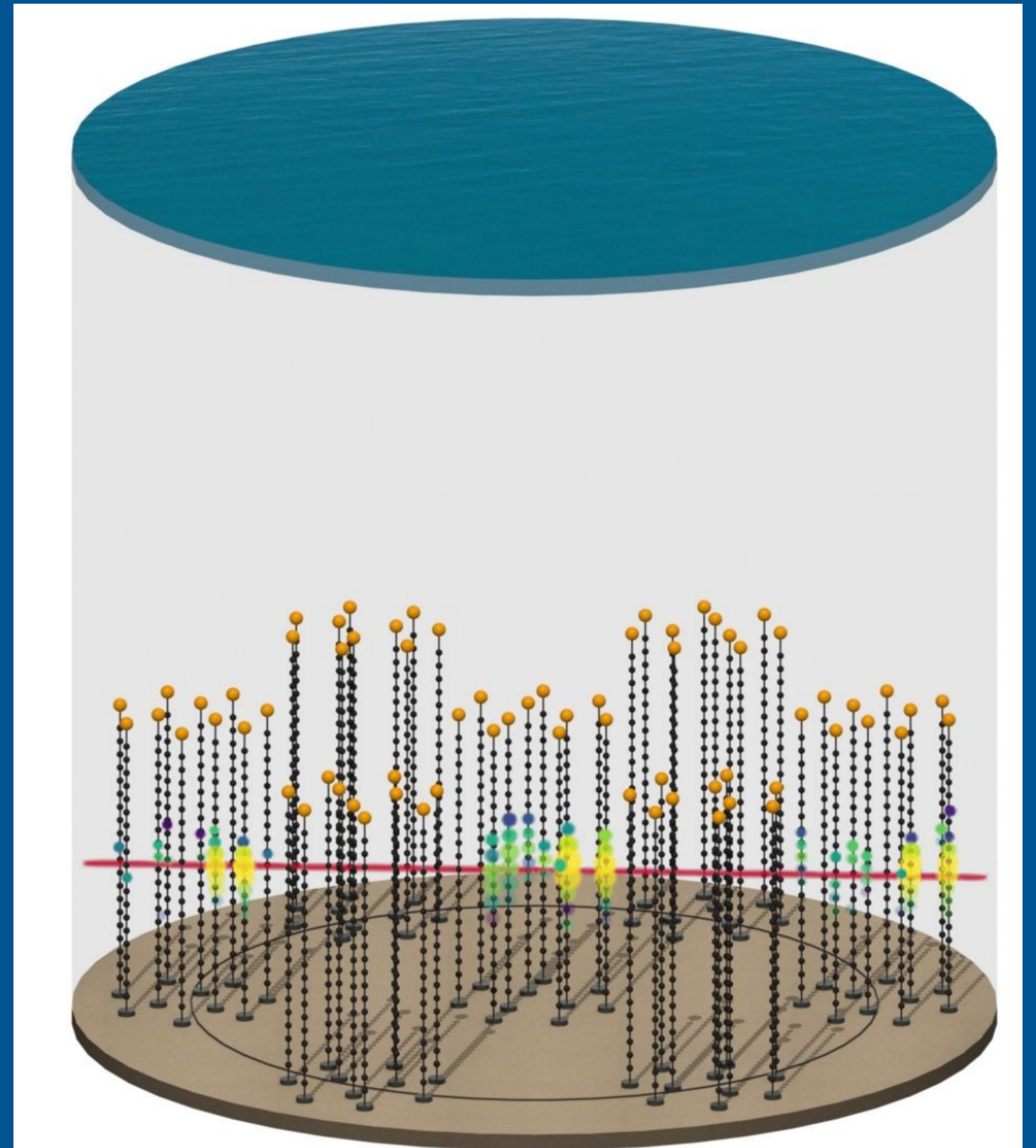


Triggering in other experiments

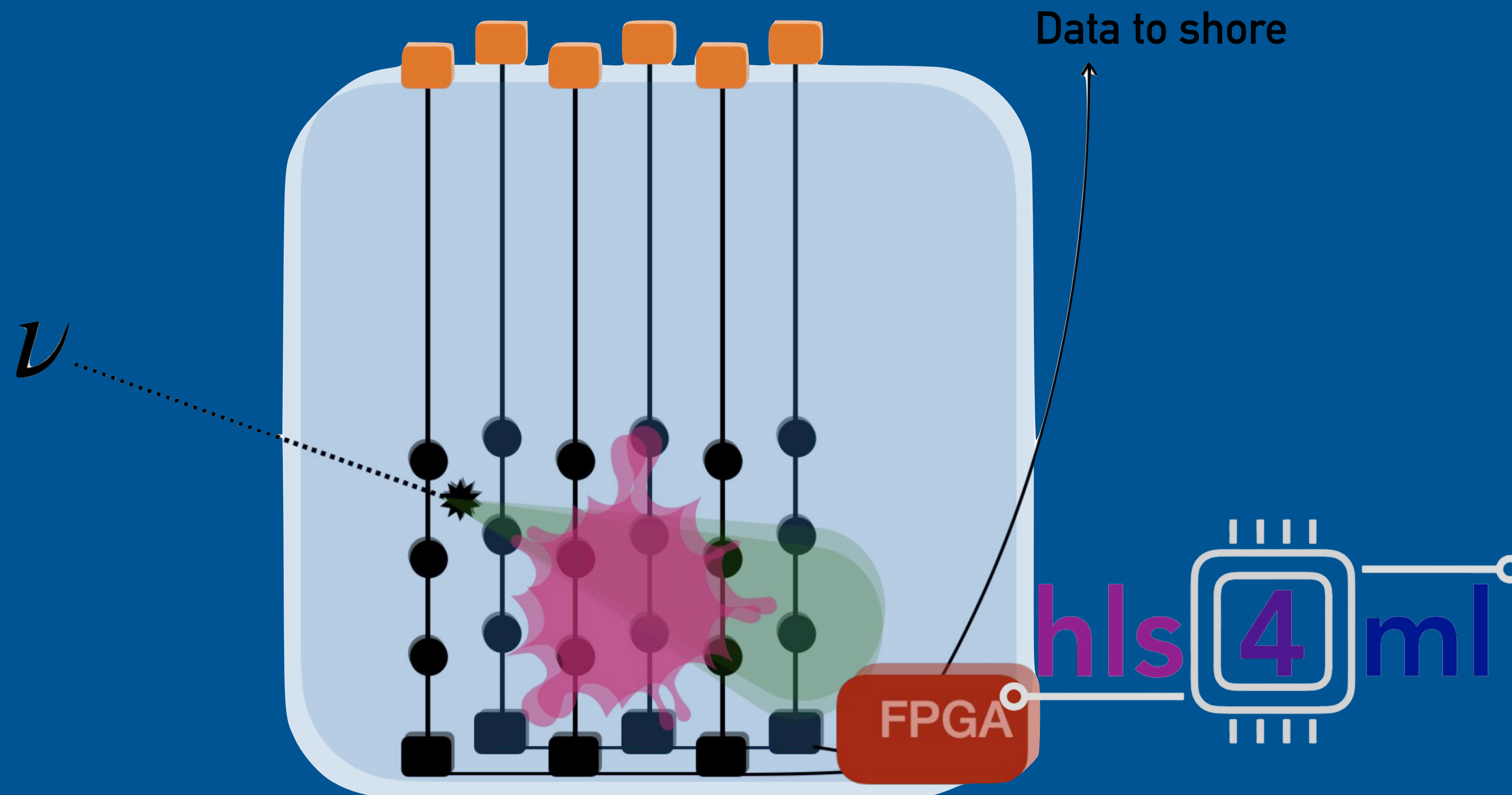




Bioluminescence bursts up to few MHz!

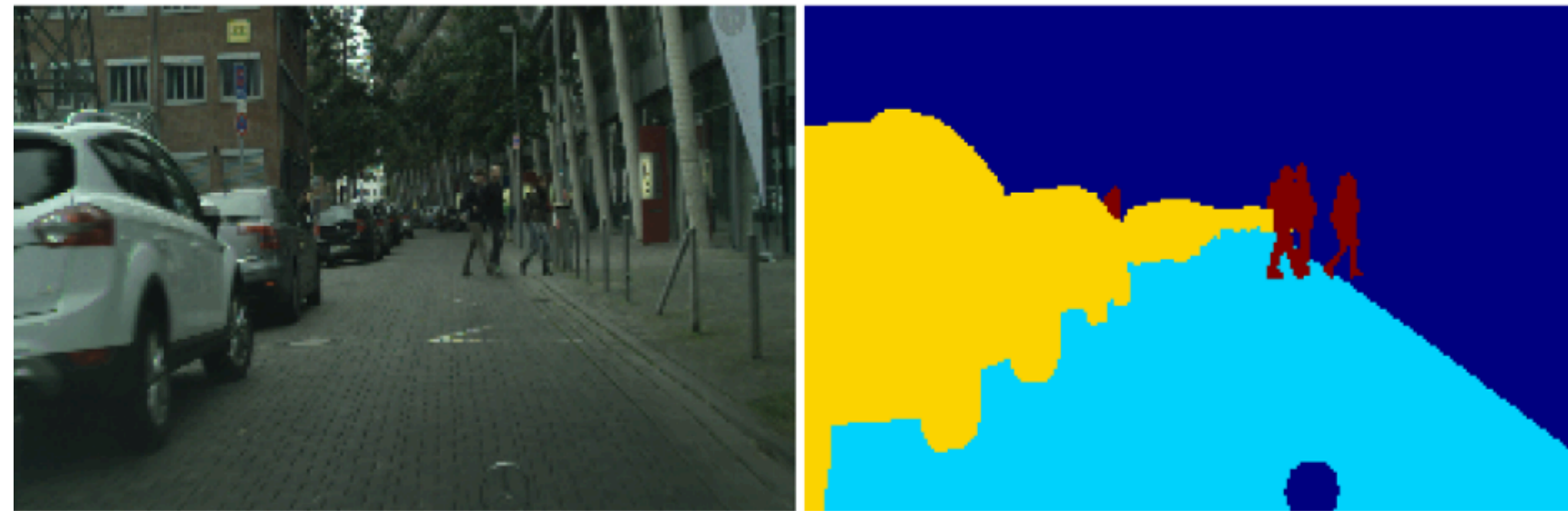


Signals and backgrounds



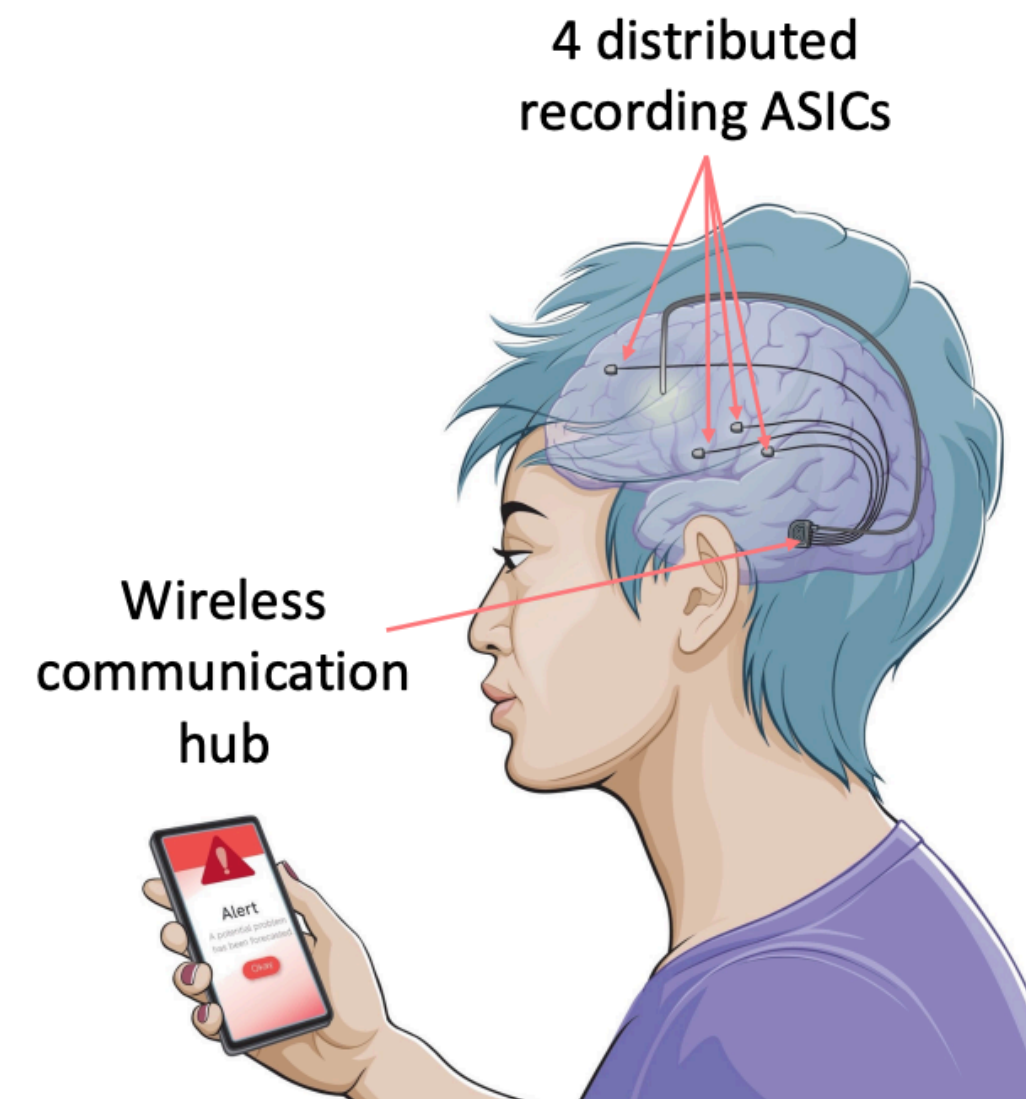
...and outside of HEP

Semantic segmentation for autonomous vehicles



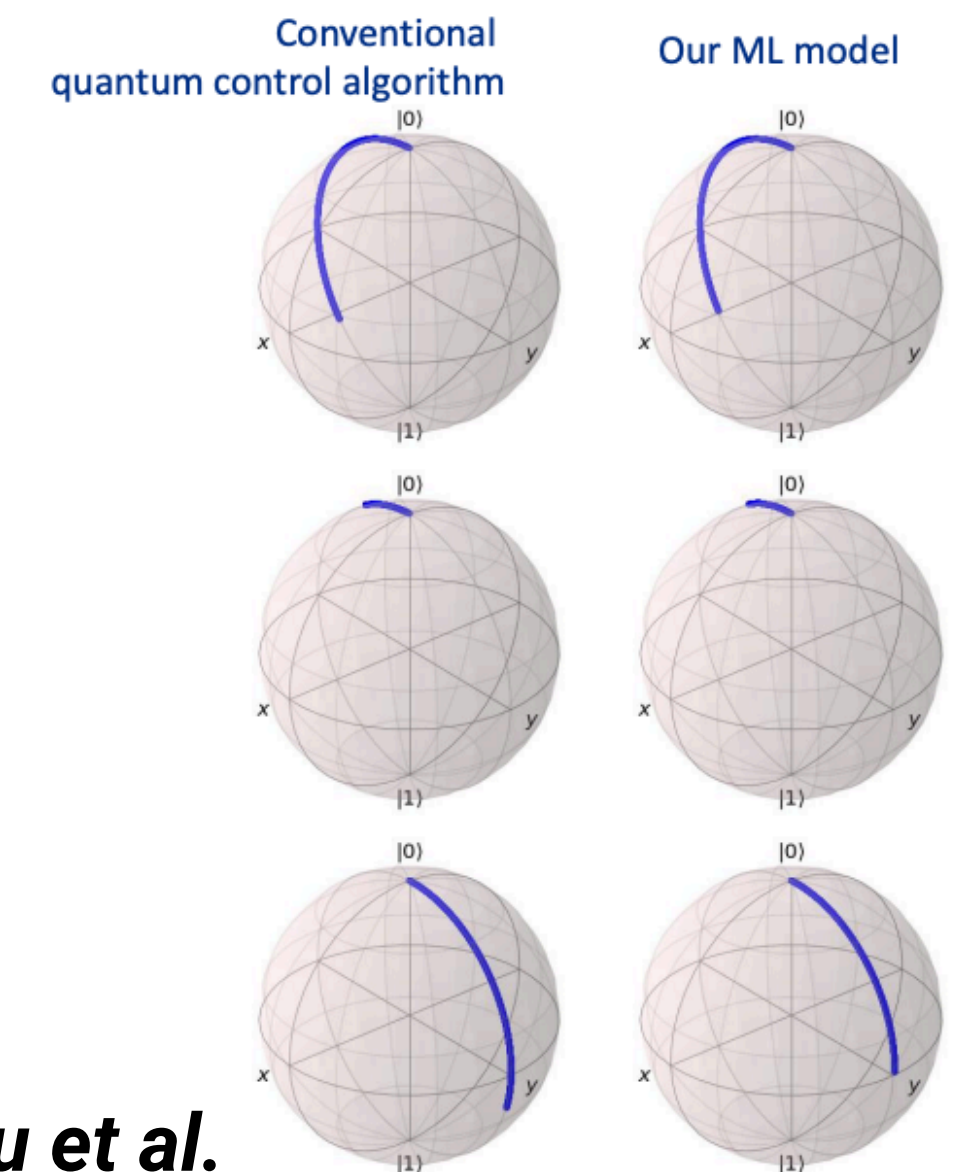
N. Ghielmetti et al.

Seizure Predicting Brain Implant



W. Lemaire et al.

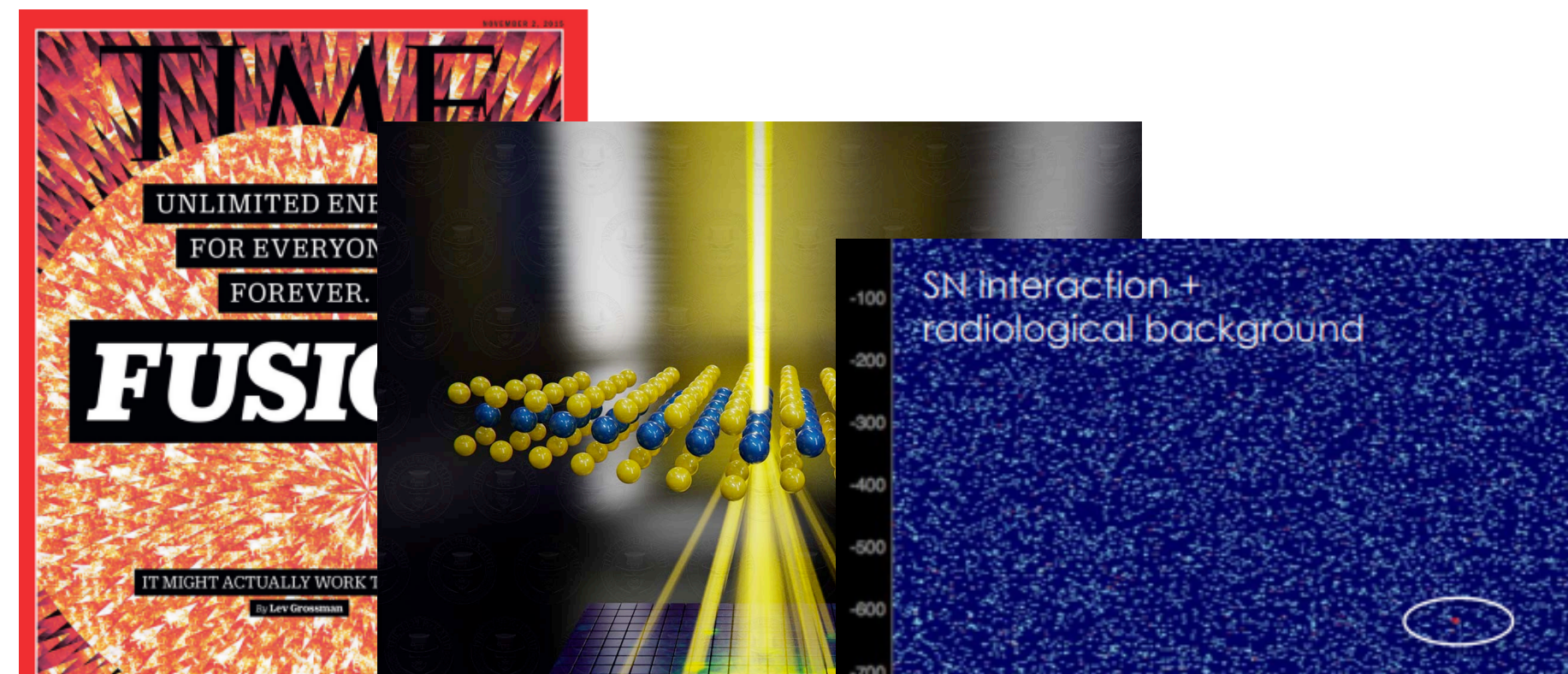
NN accelerator for quantum control

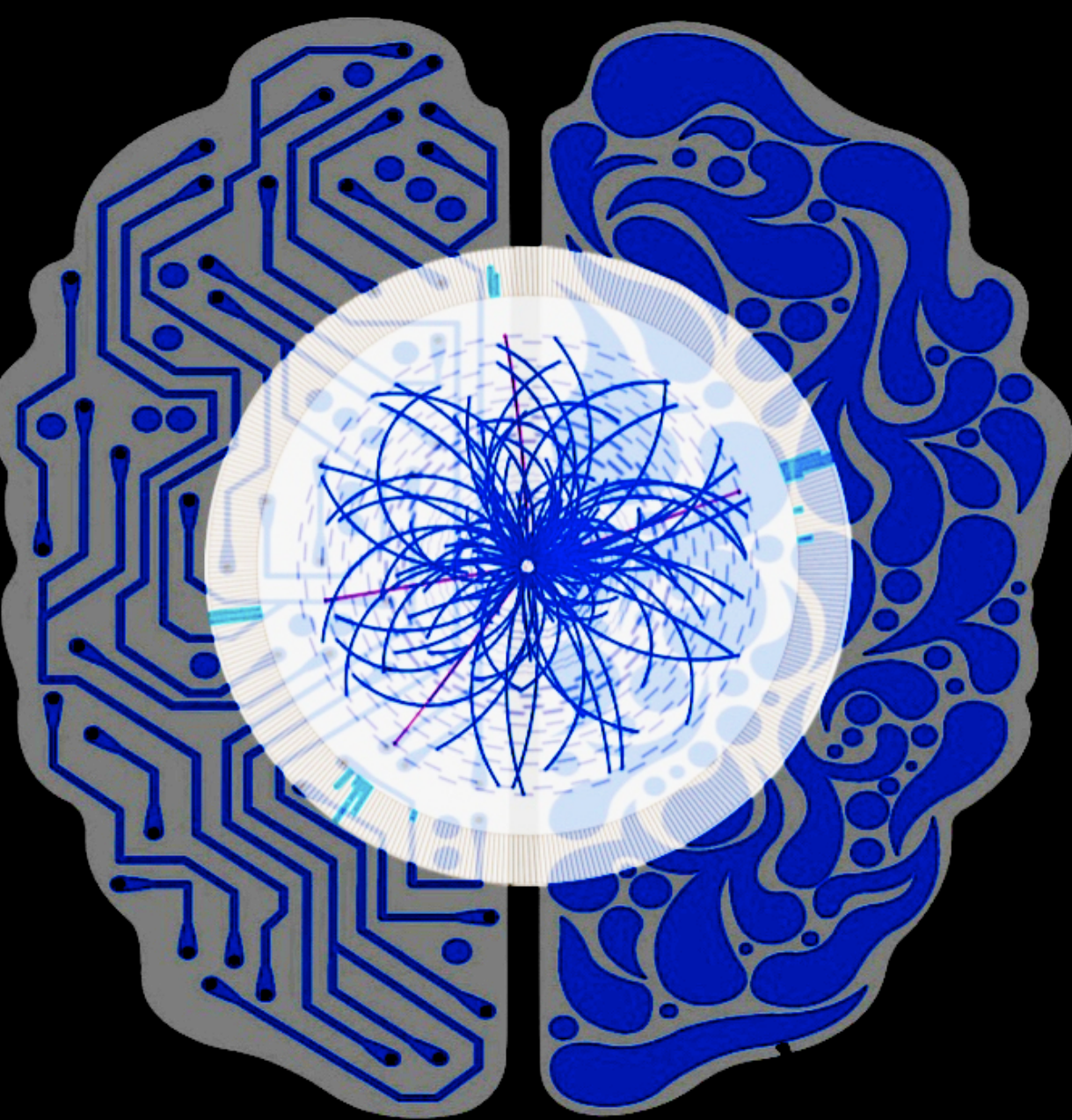


D Xu et al.

Other examples

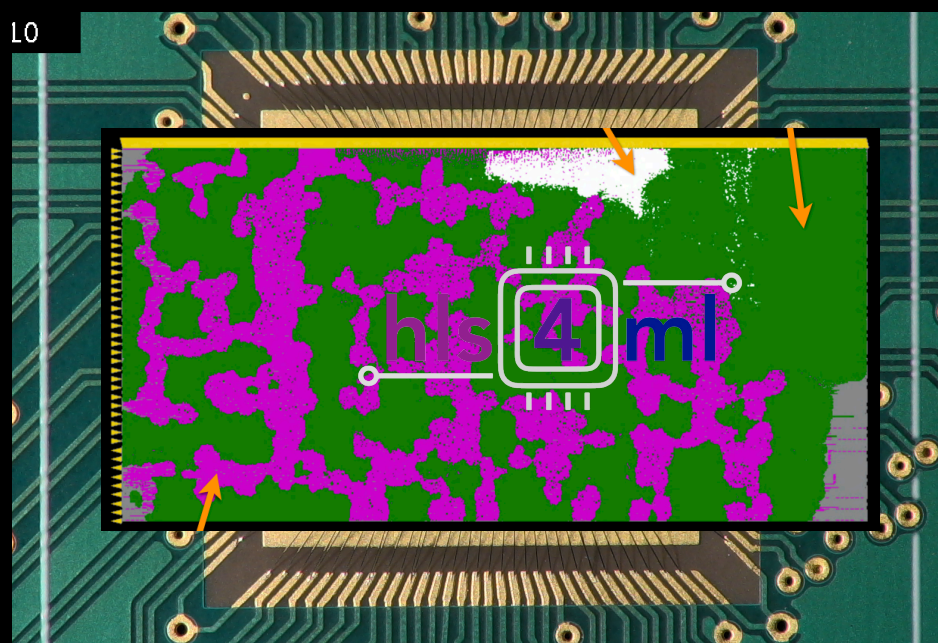
- ***For fusion science phase/mode monitoring***
- ***Crystal structure detection***
- ***Triggering in DUNE***
- ***Accelerator control***
- ***Magnet Quench Detection***
- ***MLPerf tinyML benchmarking***
- ***Food contamination detection***
- etc....





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fastmachinelearning.org

Sign up to the [hls-fml group](#)



...or come have a chat with
Patrick, Chang, Andrew and me in HPK E 29!

Extra material

Training FLOPs Scaling for SOTA CV, NLP, and Speech Models

