

# GEOMETRIC DEEP LEARNING

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IPA ML WORKSHOP 2023/03/21

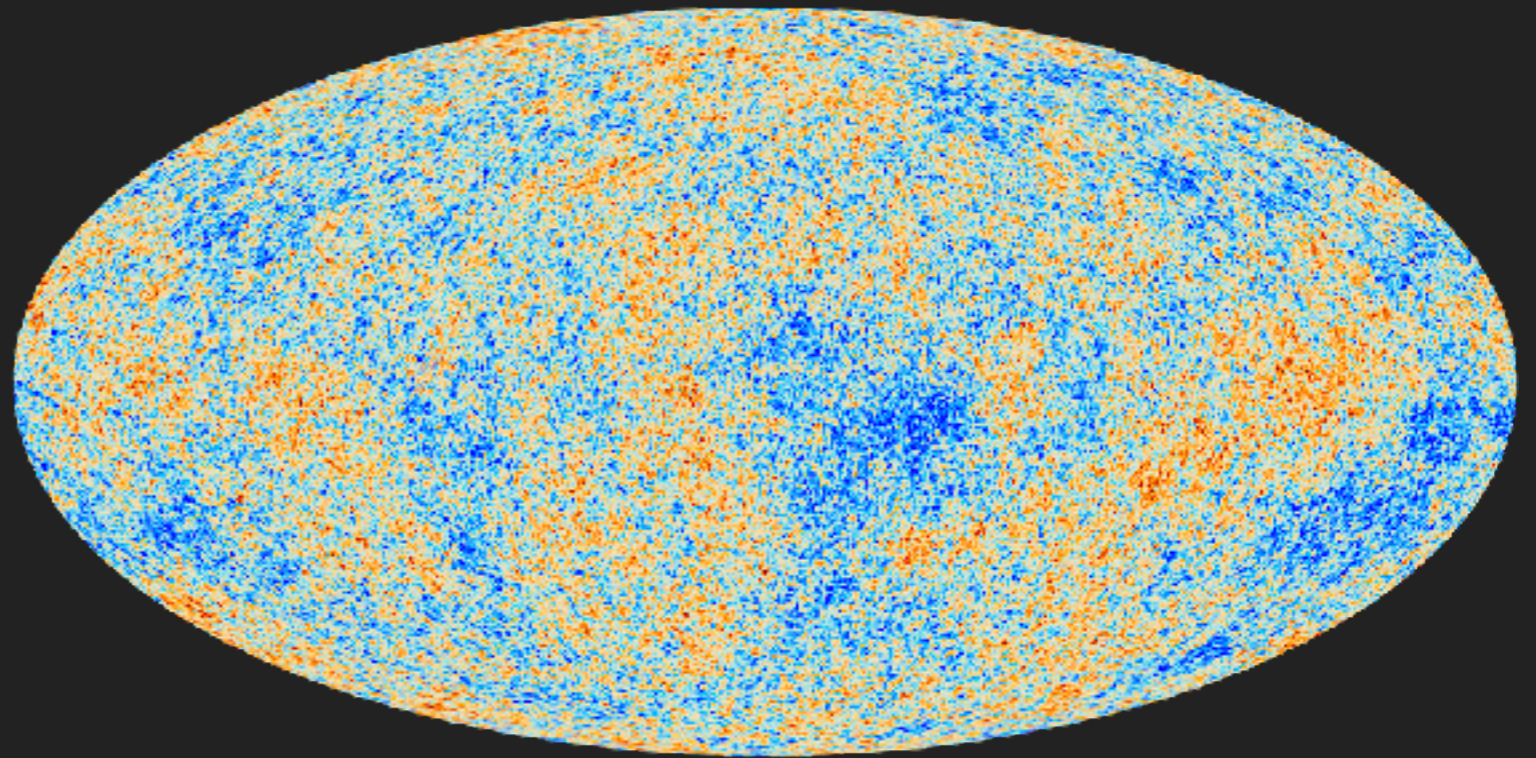
# Symmetries are ubiquitous in physics

- ▶ The Universe is homogeneous & isotropic
- ▶ Gauge theory in particle physics
- ▶ Crystal structures in solid state physics

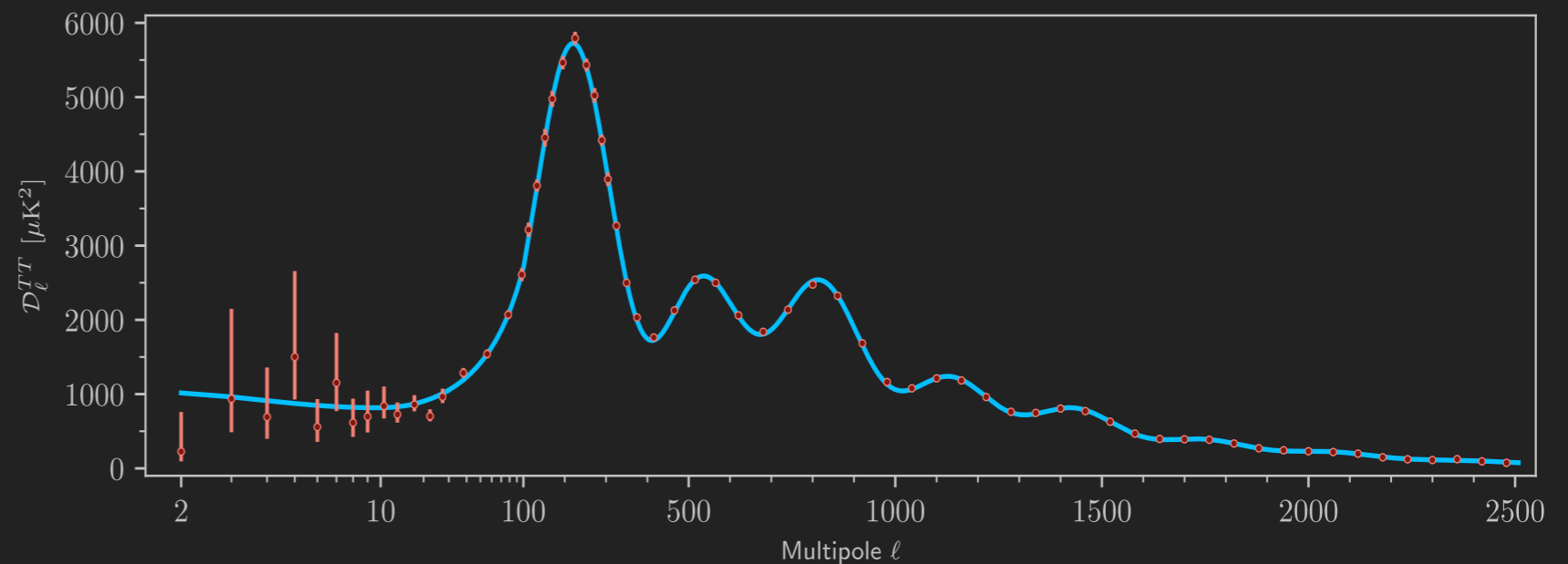
We should care about symmetries when using ML in physics

# “Classical” data analysis respects symmetries

- ▶ The Universe is isotropic



- ▶ Summary statistics in cosmology are invariant to rotations



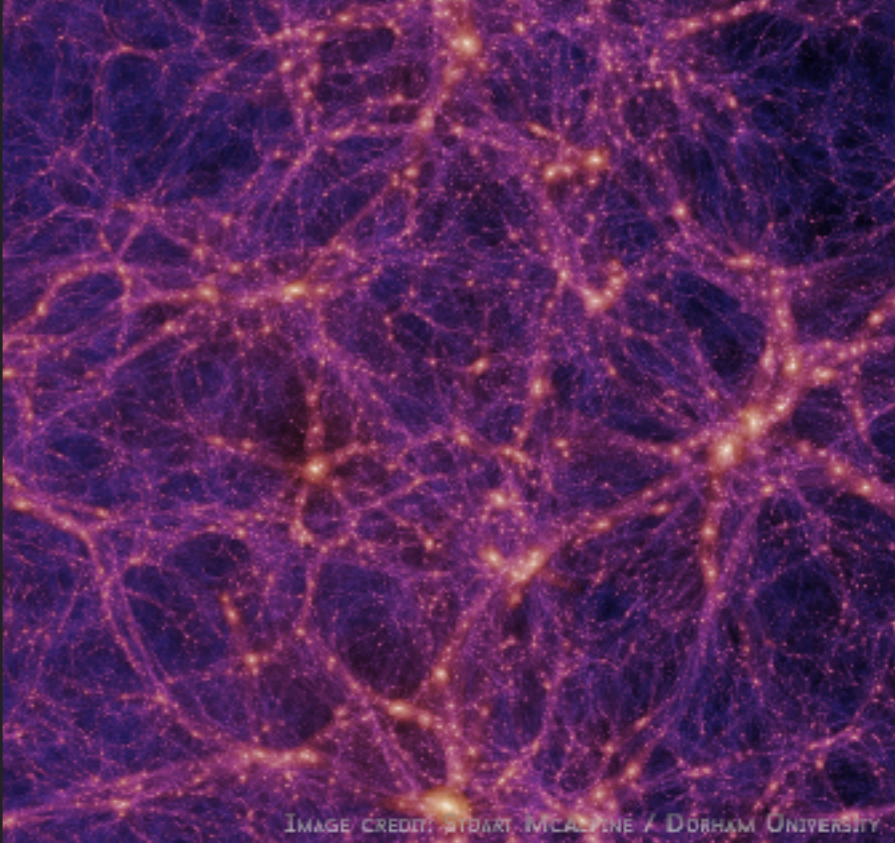
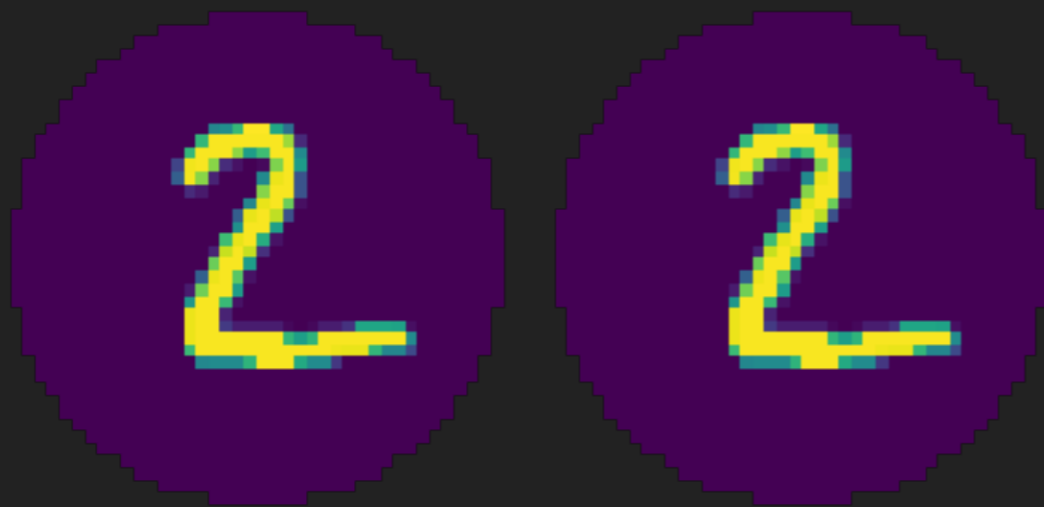


IMAGE CREDIT: SYDNEY MCALPINE / DURHAM UNIVERSITY



# ML data analysis should respect symmetries too

- ▶ Ignore symmetries



Predicted label: 2

# ML data analysis should respect symmetries too

- ▶ Data augmentation
  - ▶ No inductive bias
  - ▶ Need to learn symmetries
    - ▶ Redundant parameters
  - ▶ For 3D data, need many data augmentations
  - ▶ Inefficient, no guarantees

# ML data analysis should respect symmetries too

- ▶ Invariance
  - ▶ Output is invariant to transformations of the input
  - ▶ Example: Characterise a point cloud by distances and angles
  - ▶ Less model flexibility

# ML data analysis should respect symmetries too

- ▶ Equivariance
  - ▶ Output transforms consistently with transformed input
  - ▶ Best of both worlds
    - ▶ No need for data augmentation
    - ▶ More flexible models than invariance



- ▶ Deep learning is about finding intermediate representations
  - ▶ These representations should respect the geometry of the data
- ▶ Output and intermediate representations should transform consistently or be invariant

# Geometric features



- ▶ Scalars
  - ▶ Images



- ▶ Vectors
  - ▶ Velocities



- ▶ Tensors
  - ▶ Polarisation

Rotated input

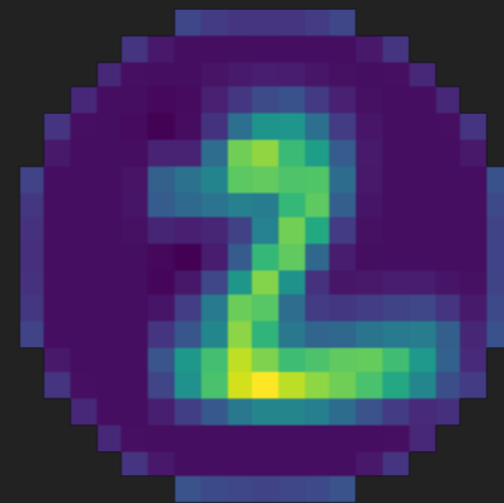
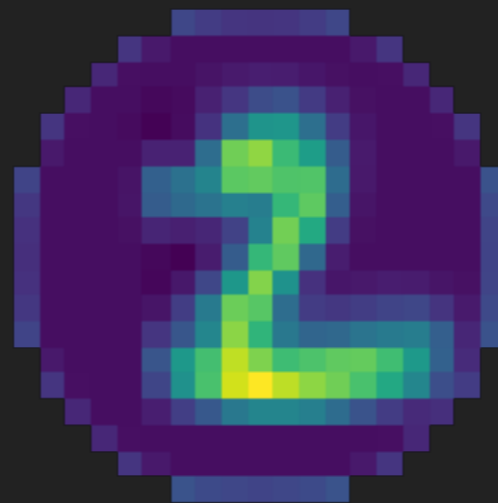
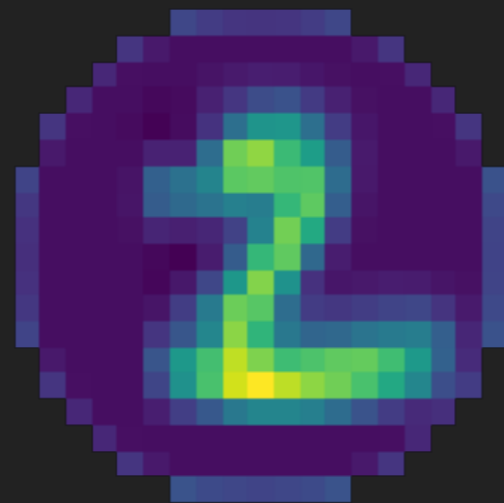
Rotated input  
stabilised

Input

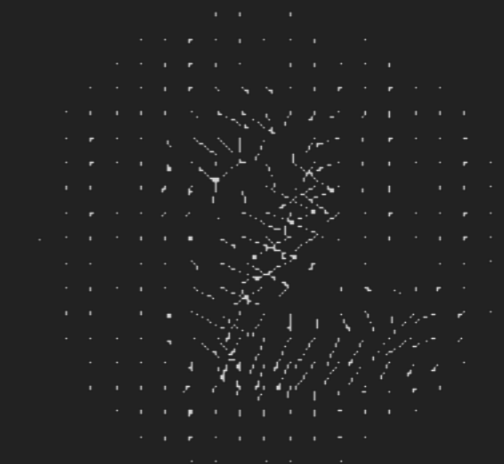
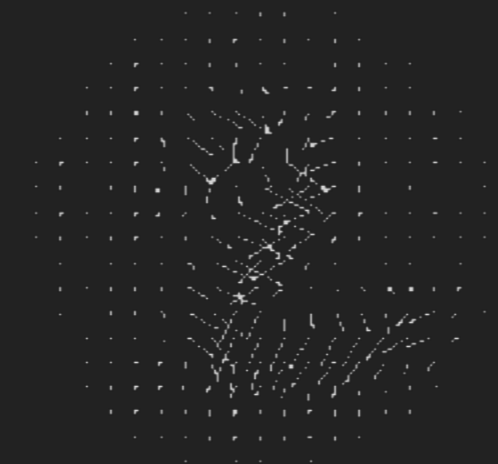
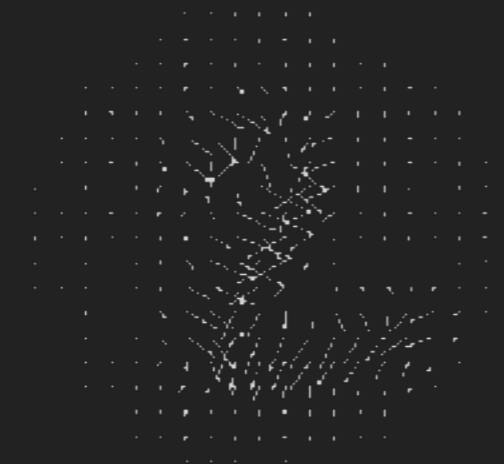


Predicted label: 2

Scalar  
features



Vector  
features



# Invariance & Equivariance

▶  $f: X \rightarrow Y$

▶ Example:  $n$  features on a 2d grid:  $X = \mathbb{R}^2, Y = \mathbb{R}^n$

▶ Group element  $g \in G$

▶ Example:  $G = SO(2)$

▶ Representations on  $X$  and  $Y$ :  $\rho_X(g), \rho_Y(g)$

▶ Example:  $X = \mathbb{R}^2, \rho_X(\theta) = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$

▶ Invariance:  $f(\rho_X(g)x) = f(x)$

▶ Equivariance:  $f(\rho_X(g)x) = \rho_Y(g)f(x)$

Rotated input

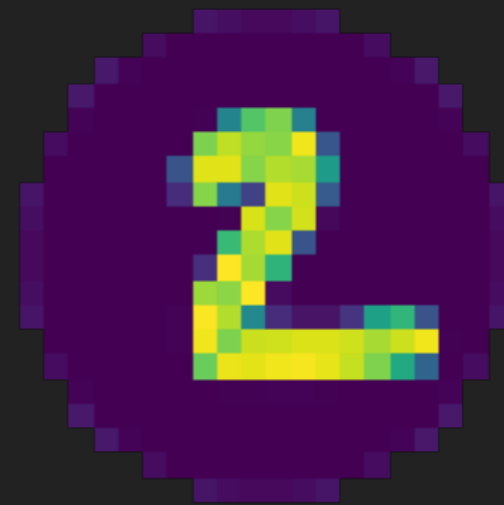
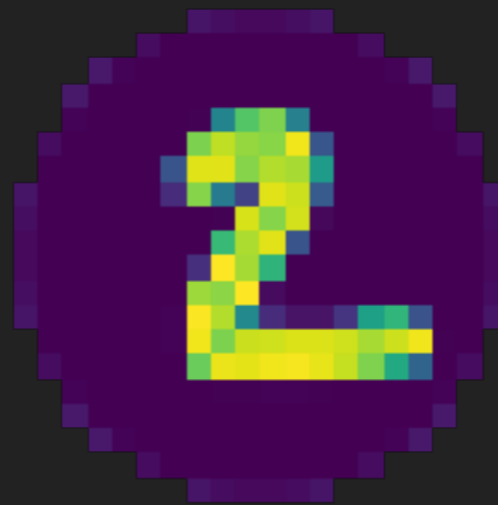
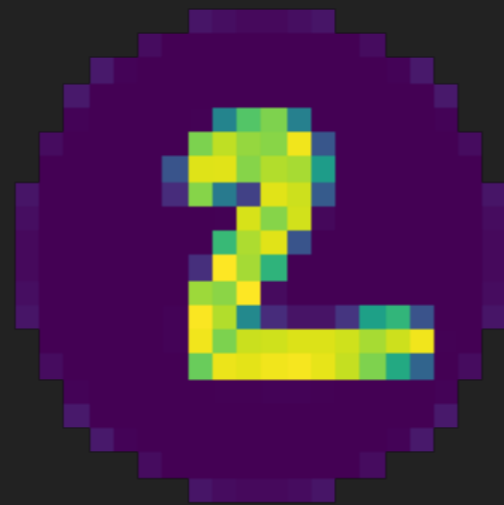
Rotated input  
stabilised

Input

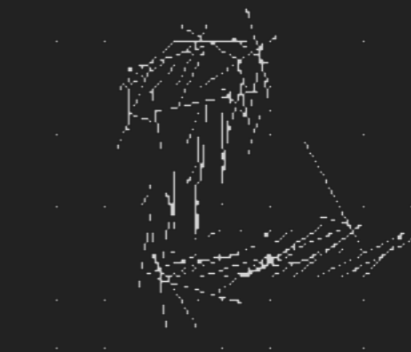
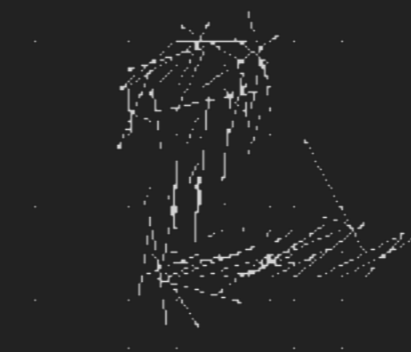
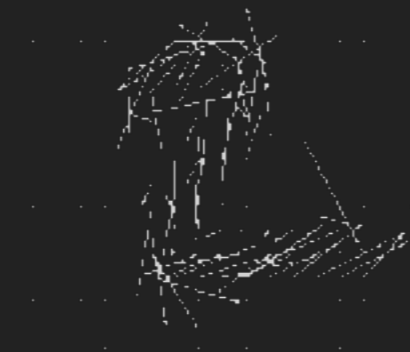


Predicted label: 2

Scalar  
features



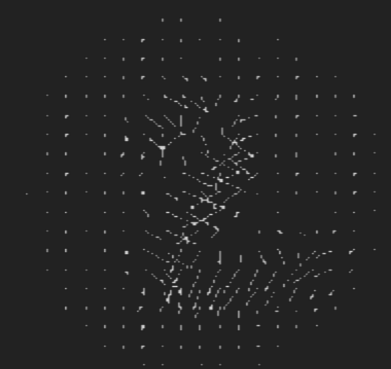
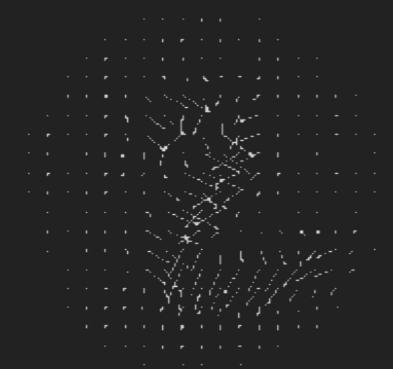
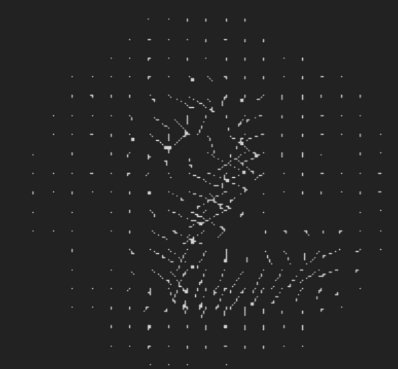
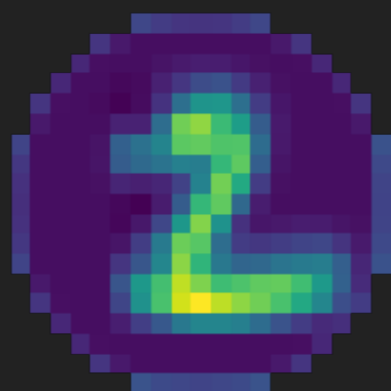
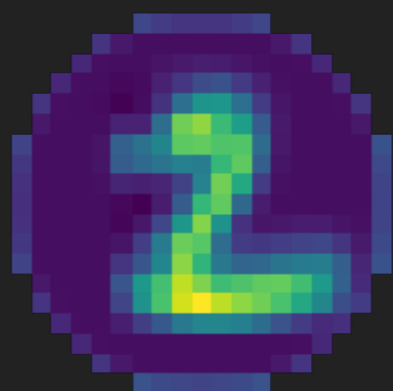
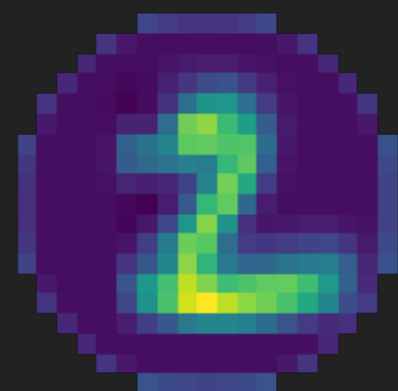
Vector  
features



# CNN



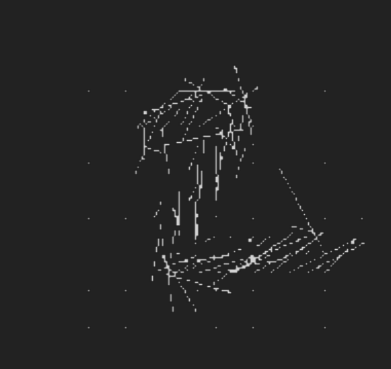
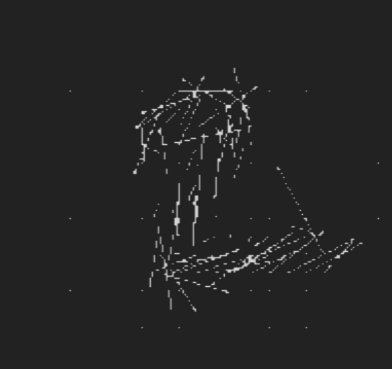
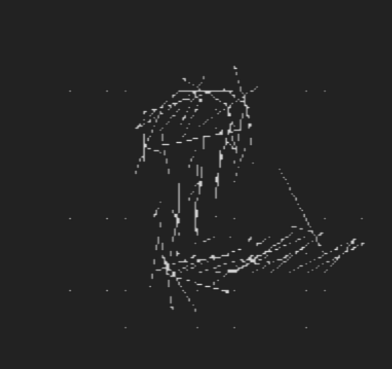
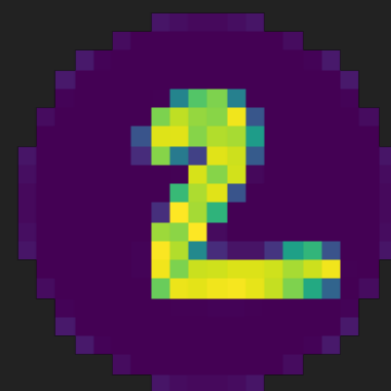
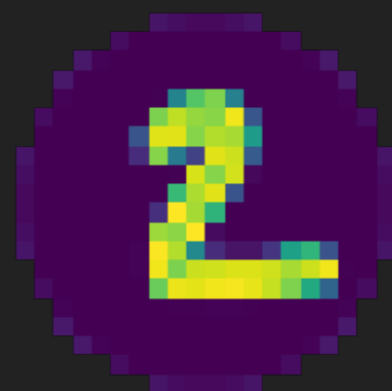
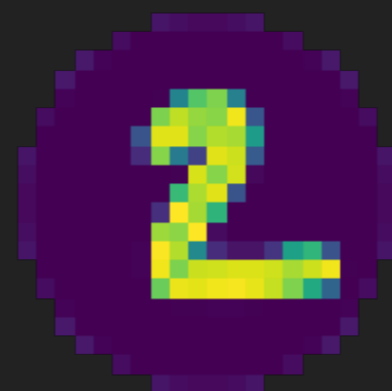
Predicted label: 2



# Equivariant CNN



Predicted label: 2

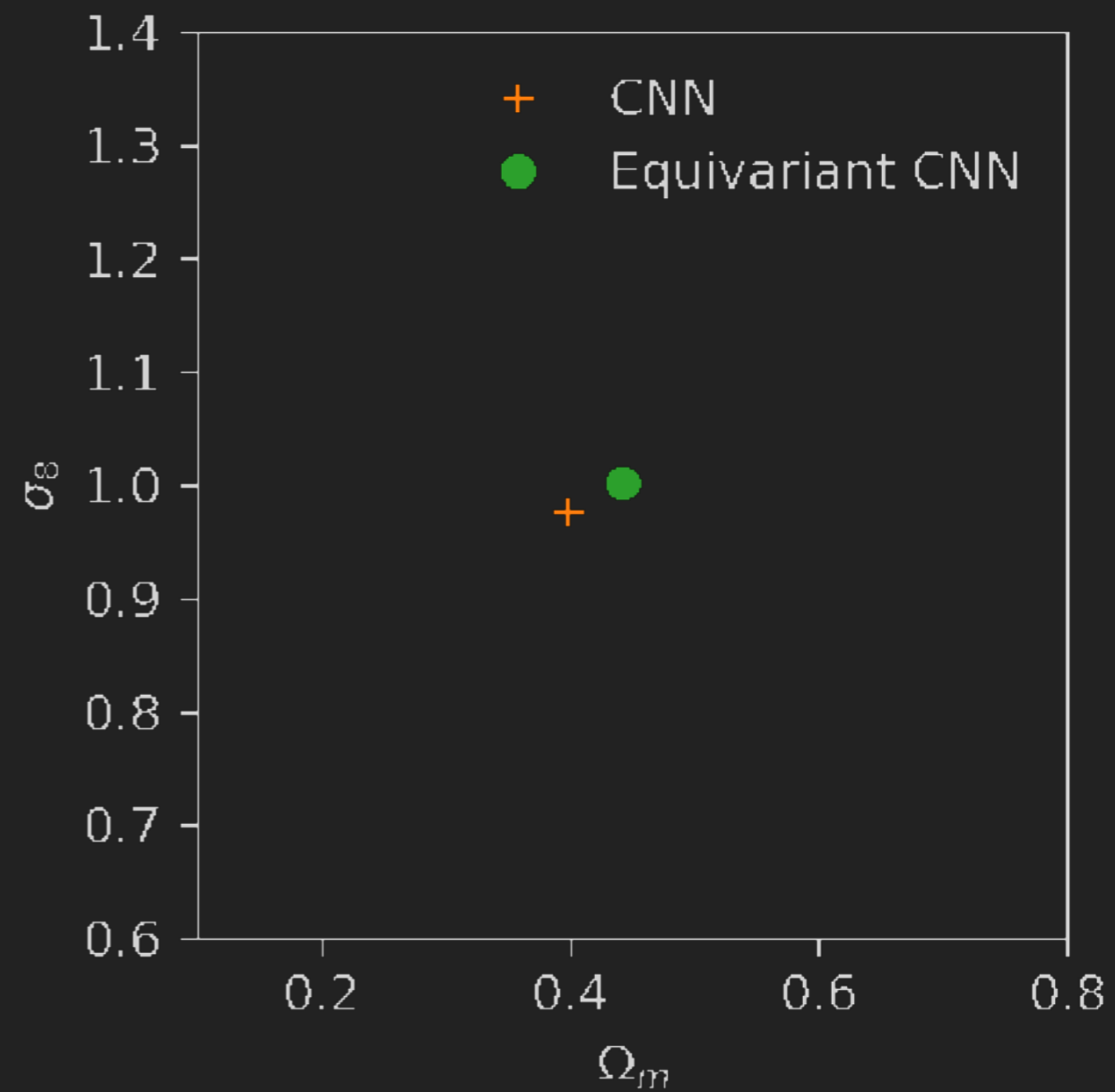
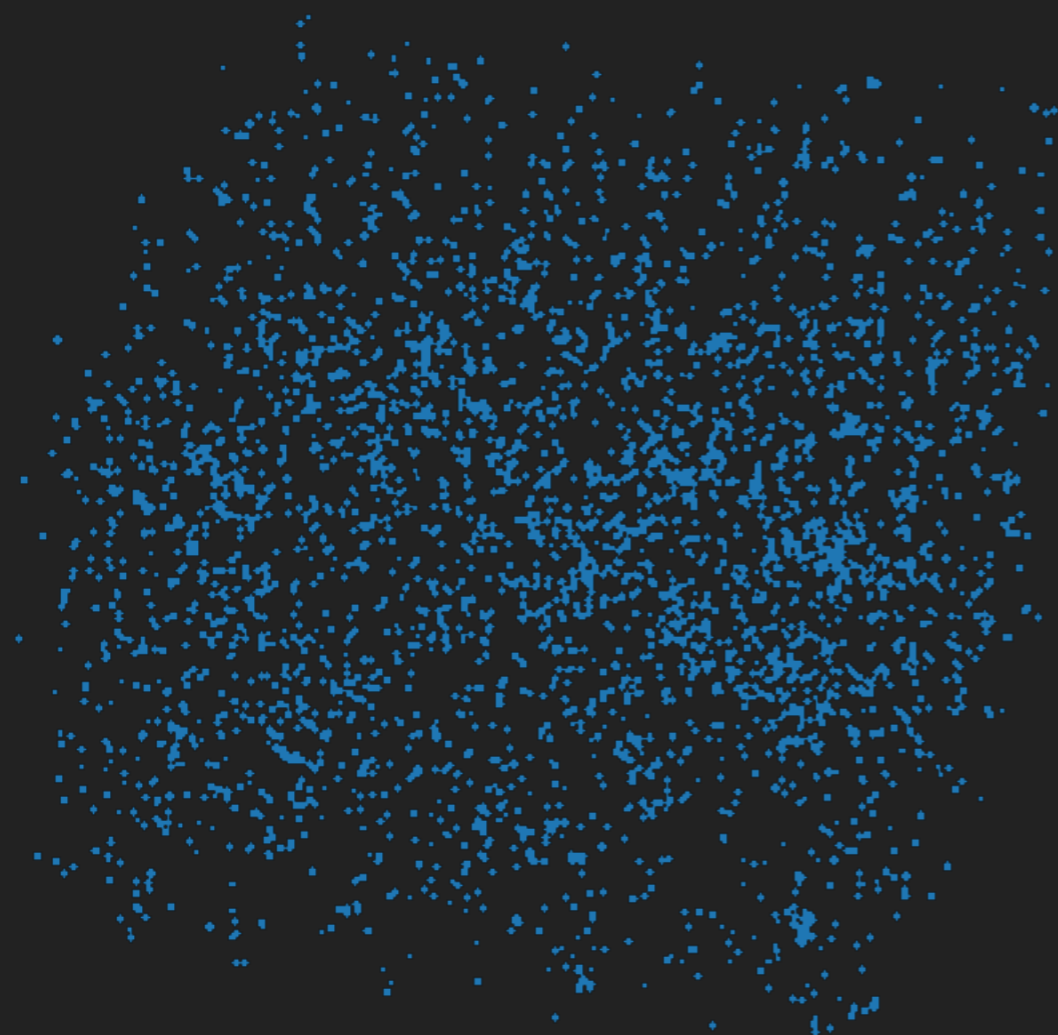


# Ingredients for equivariant models

- ▶ Define geometric meaning of features: ● ↗ 0 ...
  - ▶ Specify the irreducible representation of the features
- ▶ Use equivariant operations
  - ▶ E.g. steerable convolutions for  $SO(3)$ 
    - ▶ Kernel constraint:  $k(rx) = \rho_{\text{out}}(r)k(x)\rho_{\text{in}}(r)^{-1}$
    - ▶  $k(x) = F(|x|)\overline{Y^{\ell_{\text{out}}}(x/|x|)}Y^{\ell_{\text{in}}}(x/|x|)^T$
  - ▶ Tensor products of irreps
    - ▶ Decompose into irreps using Clebsch-Gordan coefficients

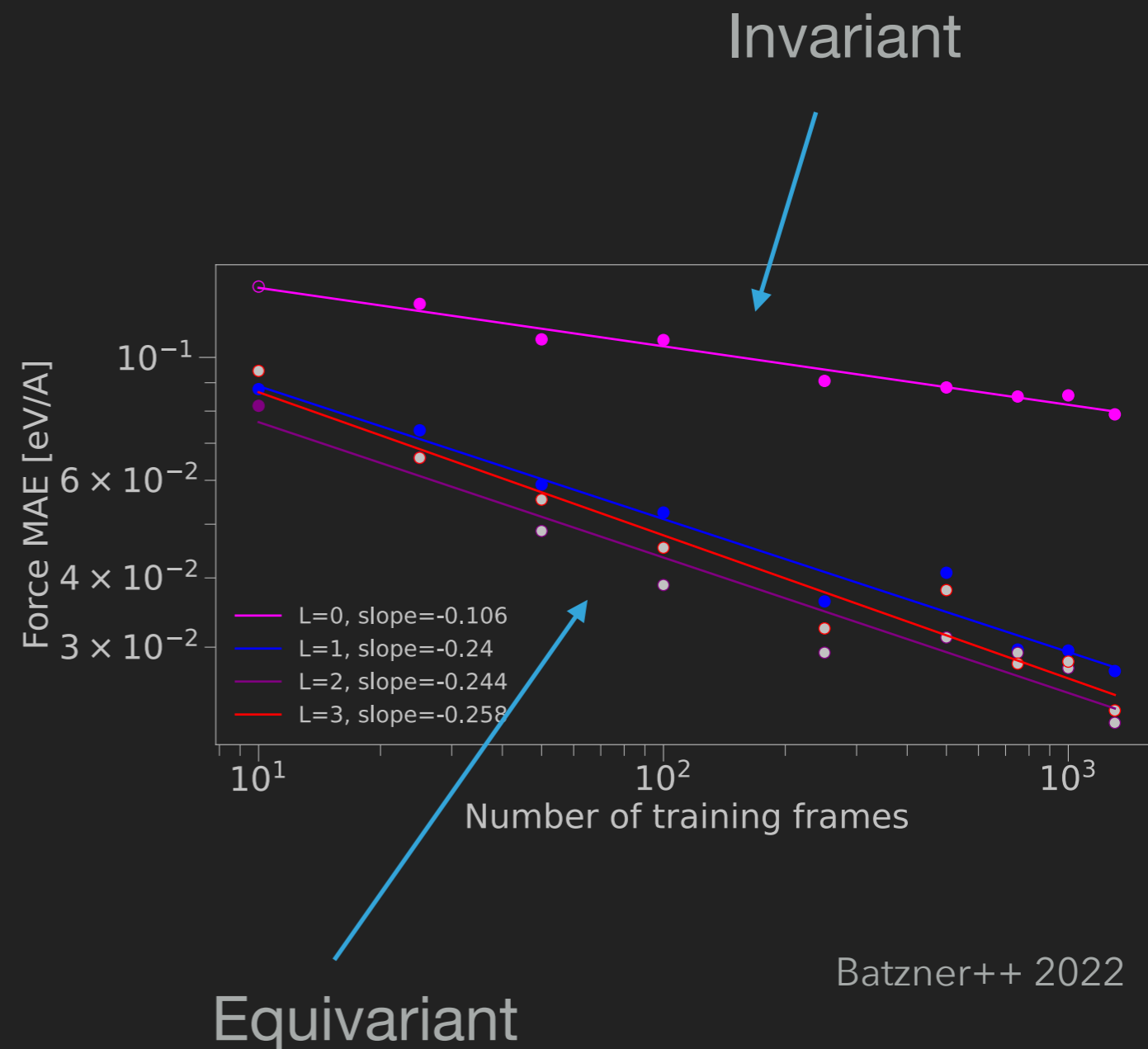


# Preliminary application to galaxy point clouds



# Why should you care?

- ▶ Guaranteed respect for symmetries in the data
- ▶ Sample efficiency
  - ▶ Preliminary: Equivariant point cloud model achieves same accuracy with order of magnitude less parameters
- ▶ Equivariant models seem to scale better with number of training samples than invariant models



# Geometric deep learning

- ▶ Deep learning on structured and geometric data
  - ▶ Graphs
  - ▶ Point clouds
  - ▶ Manifolds (e.g.  $S^2$ )
  - ▶ Meshes
  - ▶ ...
- ▶ Consistent treatment of transformations
  - ▶ (Global) group equivariance
  - ▶ Gauge equivariance
  - ▶ ...

# Some (very incomplete) literature

## ▶ Early works

- ▶ Group Equivariant Convolutional Networks: Cohen++ 2016 (1602.07576)
- ▶ Tensorfield Networks: Thomas++ 2018 (1802.08219)
- ▶ 3D Steerable CNN: Weiler++ 2018 (1807.02547)

## ▶ Reviews & background

- ▶ A General Theory of Equivariant CNNs on Homogeneous Spaces: Cohen++ 2018 (1811.02017)
- ▶ Theoretical Aspects of Group Equivariant Neural Networks: Esteves 2020 (2004.05154)
- ▶ Geometric Deep Learning: Grids, Groups, Graphs, Geodesics, and Gauges: Bronstein++ 2021 (2104.13478)

# Summary

- ▶ Geometric deep learning provides a framework to include inductive biases about symmetries of the data in our models
- ▶ Equivariant model preserve geometric meaning of inputs, intermediate representations, and outputs
- ▶ Greater interpretability, robust, and sample efficient