A novel approach in the Pandora multi-algorithm reconstruction to tackle challenging topologies at DUNE

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The Deep Underground Neutrino Experiment

- Long baseline (1285 km) oscillation experiment
- 2 MW → 2.4 MW beam at Fermilab (most intense v beam in the world)
 - Wide-band energy
- Liquid argon time projection chamber technology
- Near detector at Fermilab
- Four 17 kton Far Detector modules at SURF
- 1.5 km underground location



High-precision measurements of neutrino mixing and oscillation fundamental parameters (including CPV)

> Astrophysical neutrinos Supernova and solar neutrinos

> > Probe new physics including nucleon decay



The Horizontal and Vertical Drift Far Detector

TPC size: 12.0m × 14.0m × 58.2 m. Drift length: 3.5 m



- Modular wire-based charge readout
- 4 drift volumes defined by 5 arrays of anode and cathode planes



- PCB-based charge readout
- 2 drift volumes defined by a cathode plane, and 2 PCB-based anode planes

Liquid Argon Time Projection Chamber (LArTPC)

- Use scintillation and ionization to find 3D position of particles and interactions
- Drift charge recorded by several readout planes, with different orientations, forming images
- Light collected by photon detection system



LArTPC images



Pandora reconstruction multi-algorithm approach

- Reconstruction framework in use at all neutrino LArTPC experiments, and applied at linear colliders
- Many logical steps (> 100 algorithms) to go from input hits to 3D hierarchies
- Build different techniques, including deep learning, and physics and detector knowledge in the pattern recognition algorithms



Machine learning in Pandora

- Very diverse event topologies motivate exploiting different techniques
- Broad use of machine learning, and especially Deep Learning (DL)

Highlights:

- Neutrino interaction vertex finding in DUNE FD (see <u>Andy Chappell's talk</u>)
- Neutrino interaction vertex finding in the DUNE ND (AIDAinnova)
- Neutrino interaction vertex finding and background rejection in low-energy neutrino signatures
- Hierarchy building (see <u>Isobel Mawby's talk</u>)
- New reclustering approaches (this talk)





Reclustering approach

- Overlapping showers are challenging to reconstruct, and impact DUNE physics goals
 - Showers from π^0 mistaken as single electron are background in appearance analyses
- Tackle via new reclustering approach (STFC-funded project)
- A similar approach was successfully used at <u>linear colliders</u>
- Approach can be applied to other topologies, e.g. including tracks



Clustering 3D hits with Graph Neural Networks

- We are investigating DL techniques, such as transformer networks, to identify target topologies
- In this presentation, will assume that target topologies have already been identified
- Start from 3D hits, aim at proposing new possible clustering outcomes

Graph Neural Networks (GNNs) motivation

- Straightforward representation of a 3D cluster of hits as a graph:
 - One 3D cluster = 1 graph
 - Nodes = hits
 - Node features = hit *x*, *y*, *z*, charge
- Can imagine pairs of hits to be connected by a positive edge if most energy was deposited by the same true particle



Grey line = false edge Black line = true edge





Leverage GNN message-passing so that local features know about broader cluster structure

- For each layer, aggregate nearby nodes features to node under consideration (e.g. via averaging)
- Only consider nearby hits within radius, e.g. 10 cm
- Stacking together many layers means concatenating features from further away





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Two GNN-based approaches for clustering



Edge prediction GNN performance example

 \rightarrow 1M edges

positive and negative)

(equal number

Training and testing samples

- About 130 shower particles
- Number of hits > 400 and < 700
- with > 30% contamination
- 90%-10% training-testing split

Architecture

• 10 SAGEConv layers, 1 predictor layer, 16 hidden channels

Predicted edge scores

- 0.5 cut \rightarrow typical prediction accuracy around 75-80%
- Network could be tuned for further separation
- However, a harder cut on scores may already give good performance in clustering

How to use the predicted scores to guide 3D hit clustering?

Predicted edge scores



Blue distribution: true positive edges Red distribution: true negative edges



How to use the GNN output



• Four different outcomes

- There will be ambiguities as the network output is not perfect
- B is predicted to be strongly connected to A and C, but A and C are not predicted to be strongly connected together

A	A C	A	С	A		С
В	В	В			В	



GNN output in clustering algorithms

• Explored the idea of an "average connection score" to quantify how strongly connected each hit is to its local neighbourood.

Average connection score = (sum of edge scores above threshold within 10 cm) (for each hit) (# neighbouring hits within 10 cm)

Hope to show splitting points/regions, or differences between particles \rightarrow Use to split cluster





Merged particles score examples

Average connection score





These topologies are "track-like". Scores may be less useful in more shower-like topologies



Summary

- LArTPCs yield very high resolution images of particle interactions
- **State-of-the-art reconstruction** crucial to achieve DUNE physics goals
- Some topologies, such as overlapping showers, pose special challenges
- **Pandora's multi-algorithm approach** is well placed to tackle these challenges
- A reclustering paradigm, under development in Pandora, allows exploiting multiple techniques, including deep learning
- Exploring using GNNs, based on graph interpretation of 3D particles
- Initial training of network to predict true connections between hits
- Exploring use of output scores in new clustering algorithms
- In parallel, exploring an unsupervised clustering approach